

Singularities and unsteady separation for the inviscid two-dimensional Prandtl system

CHARLES COLLOTO, TEJ-EDDINE GHOUL & NADER MASMOUDI

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Abstract

We consider the inviscid unsteady Prandtl system in two dimensions, motivated by the fact that it should model to leading order separation and singularity formation for the original viscous system. We give a sharp expression for the maximal time of existence of regular solutions, showing that singularities only happen at the boundary or on the set of zero vorticity, and that they correspond to boundary layer separation. We then exhibit new Lagrangian formulae for backward self-similar profiles, and study them also with a different approach that was initiated by Elliott–Smith–Cowley and Cassel–Smith–Walker. One particular profile is at the heart of the so-called Van-Dommelen and Shen singularity, and we prove its generic appearance (that is, for an open and dense set of blow-up solutions) for any prescribed Eulerian outer flow. We comment on the connection between these results and the full viscous Prandtl system. This paper combines ideas for transport equations, such as Lagrangian coordinates and incompressibility, and for singularity formation, such as self-similarity and renormalisation, in a novel manner, and designs a new way to study singularities for quasilinear transport equations.

1. Introduction

We consider the inviscid Prandtl equations on the upper half-plane $\mathscr{H}:=\mathbb{R}\times [0,\infty)$

$$\begin{cases} u_{t} + uu_{x} + vu_{y} = -p_{x}^{E} \\ u_{x} + v_{y} = 0, \\ v|_{y=0} = 0, & \lim_{y \to \infty} u(t, x, y) = u^{E}(t, x), \end{cases} (t, x, y) \in [0, T) \times \mathcal{H},$$

$$(1.1)$$

where p^E and u^E are the trace of the Eulerian pressure and tangential flow at the boundary $\mathbb{R} \times \{0\}$ induced by the Eulerian flow at infinity. The functions p^E and

 u^E are prescribed, and then act as forcing terms for u. They are linked through Bernoulli's equation

$$u_t^E + u^E u_x^E = -p_x^E, (1.2)$$

whose solutions have to be global in two dimensions.

1.1. Historic Background

1.1.1. Boundary Layer Separation and Singularities Prandtl's system comes from the vanishing viscosity limit of the Navier–Stokes equations with Dirichlet boundary condition. It describes the formation of a boundary layer, where the solution does a sharp transition from the vanishing at the boundary of an obstacle, induced by the Dirichlet condition, to a solution of the Euler system away from its boundary.

Prandtl describes in [29] the phenomenon of boundary layer separation, when "a fluid layer, set rotating as a result of friction at the wall, moves out into the free stream" (this English translation being taken from [1]). For the steady Prandtl system, separation happens at the boundary with the condition of vanishing wall shear stress $\partial_y u(x_0, 0) = 0$. Goldstein [17] finds that at such location the solution is singular, and as a result so is the displacement thickness (a quantity describing the influence of the layer on the outer flow), revealing that the layer separates past x_0 . We refer to the textbook [33] for details. Dalibard and Masmoudi [9] gave recently a mathematically rigorous description of the Goldstein singularity.

For the unsteady Prandtl system, Moore, Rott and Sears [27,30,34] realised that $\frac{\partial}{\partial y}|_{y=0}u=0$ was not a correct condition for separation, and came up with what is now known as the MRS conditions. These conditions state that if a piece of layer is separating off the boundary, then there is a point $(x_s(t), y_s(t))$ at the center of this separating piece of layer, at which the vorticity vanishes $\partial_y u(t, x_s(t), y_s(t)) = 0$, and whose tangential velocity $u(t, x_s(t), y_s(t))$ is equal to the tangential velocity of the whole separating piece of layer. We recall that $\partial_y u$ is the vorticity, when considering the approximation of the Navier–Stokes equations with the Prandtl system at high Reynolds number. It was then believed [35] that a criterion for separation at time T_0 was that at such a point the solution u becomes singular as $t \uparrow T_0$. Van Dommelen and Shen [36,38] showed this equivalence between separation and singularity formation. We refer to the introduction of [5] for an historic perspective for criteria for steady and unsteady separation.

It is noted in [36] that the layer becomes inviscid to leading order during separation. This justifies our study of the inviscid Prandtl system (1.1). The aim of this article is to give a rather complete study of (1.1). In particular, we justify in a mathematical and rigorous way the aforementioned results: we prove the equivalence between separation and singularities for (1.1), and describe the generic mechanism for this phenomenon.

This introduction will now be restricted to unsteady problems.

1.1.2. Existence and Regularity of Solutions The first rigorous mathematical justification of the unsteady Prandtl system is due to Oleinik [28]; she proves the local wellposedness by imposing a monotonicity in *y* condition on the tangential velocity *u* in order to use the Crocco transform. Xin and Zhang [39] obtain global existence of weak solutions by imposing monotonicity and an extra condition on the pressure. The monotonicity condition allows Masmoudi and Wong in [26], and Alexandre, Wang, Xu and Yang in [2] to prove wellposedness in Sobolev regularity. Without the monotocity condition, the equation can be ill-posed in Sobolev regularity [16]. Indeed, the authors in [18,20] constructed instabilities that can prevent the Prandtl system to be a good approximation of the Navier–Stokes system in the vanishing viscosity limit. We refer to [15,25,31] and the references therein for further informations. Otherwise, in the general case the system is locally well-posed in the analytical setting [11,22,24,32].

To the best of our knowledge, the only local existence with general smooth initial data for the inviscid Prandlt system (1.1) is due to Hong and Hunter, in [21] (see also [3,19]). They find a lower bound for the maximal time of existence which corresponds to that of the Burger's equation $T = (-\inf_{\mathcal{H}} \partial_x u_0)^{-1}$ in the case of a trivial outer Eulerian flow (1.12). We find in this current paper that the sharp maximal existence time for the homogeneous inviscid Prandtl system (1.12) is $T = -(\inf_{\{\partial_y u_0 = 0\} \cup \{y = 0\}} \partial_x u_0)^{-1}$ which is larger. We prove that this time is sharp which clarifies why the aforementioned monotonicity condition is important to guarantee global wellposedeness for the inviscid Prandtl system. We obtain more generally a sharp maximal time of existence in the case of nontrivial Eulerian flows.

1.1.3. Description of Singularities The first reliable numerical result on the unsteady Prandtl system explaining how the separation is linked to the formation of singularity was obtained by Van Dommelen and Shen [36]. They characterise the singularity as a result of particles being squashed in the streamwise direction, with a compensating expansion in the normal direction of the boundary. We refer to [10,14] for recent numerical simulations and references therein for previous ones.

The first rigorous result on singularity formation for the unsteady Prandtl system is due to E and Enquist [12] (see [23] for nontrivial outer flows). They consider the trace of the tangential derivative of odd solutions in x along the transversal axis $\xi(t, y) = -u_x(t, 0, y)$, which obeys the following equation for $y \in [0, \infty)$:

$$\begin{cases} \xi_t - \xi_{yy} - \xi^2 + \left(\int_0^y \xi \right) \xi_y = p_{xx}^E(t, 0), \\ \xi(t, 0) = 0, \ \xi(0, y) = \xi_0(y), \ \lim_{y \to \infty} \xi(t, y) = -u_x^E(t, 0). \end{cases}$$
(1.3)

They also prove singularity formation for (1.3). In [6] we give a precise description of the singular dynamics of the equation above, where we find a stable profile (and instable ones) and prove that the blowup point is ejected to infinity in the transversal direction because of the incompressibility condition. This result can be interpreted as a partial stability result for one of the profiles studied in the present paper, see Remark 1.6.

It is interesting to understand singularities for simplified models. In a first part of [7], we treat the inviscid Burgers equation $u_t + uu_x = 0$ and prove that the Taylor expansion of the initial data around the blowup point will decide which profile and

scaling law the flow will select to form the singularity. The solution will be of the form $u(t, x) = (T - t)^{1/(2i)} \Psi_i(x/(T - t)^{1+1/(2i)})$ where $(\Psi_i)_{i \ge 1}$ are the profile, and the Taylor expansion selects the integer i. We prove that the generic profile

$$\Psi_1(\mathfrak{X}) := \left(-\frac{\mathfrak{X}}{2} + \left(\frac{1}{27} + \frac{\mathfrak{X}^2}{4} \right)^{\frac{1}{2}} \right)^{\frac{1}{3}} + \left(-\frac{\mathfrak{X}}{2} - \left(\frac{1}{27} + \frac{\mathfrak{X}^2}{4} \right)^{\frac{1}{2}} \right)^{\frac{1}{3}}, (1.4)$$

appears generically during blow-up. Surprisingly, the above profile is also going to play a role in the generic separation phenomenon for the Prandlt's system.

In order to understand the effect of the transversal viscosity on the horizontal transport we consider in the second part of [7] a two dimensional Burgers system

$$u_t - u_{yy} + uu_x = 0$$
 $(t, x, y) \in [0, T) \times \mathbb{R}^2$. (1.5)

We found infinitely many different profiles, one being stable under suitable perturbations. We find that despite the infinite speed of propagation induced by the transverse viscosity, the Taylor expansion of the initial datum around the blowup point will still decide the profile and the scaling law. We prove that the vertical viscosity affects the shock formation of Burgers equation, in the sense that the solutions are now anisotropic and of the form $u(x, y, t) \sim \lambda^{1/(1+2i)}(t, y)\Psi_i(x/\lambda(t, y))$ where Ψ_i is a profile of the Burger's equation and $\lambda \to 0$ depends on the solutions of a parabolic system similar to (1.3) without the nonlocal term.

Inspired by [4,8,13,36,37] where it is suggested based on numerics and formal calculations that the viscosity is asymptotically negligible during singularity formation for the unsteady Prandtl system, we treat in this paper the singularity formation for the inviscid problem (1.1). In a forthcoming paper we treat the viscous case.

1.2. Results

1.2.1. A Sharp Existence Result and Equivalence Between Separation and Singularity We give here a sharp local well-posedness result for (1.1), relying on the Lagrangian approach initiated in [21,36]. As a by-product, we prove that the layer separates if and only if the solution becomes singular, establishing rigorously this standard criterion for separation in the physics literature (see for example [35]).

We denote by (X, Y) the Lagrangian variables and (x, y) the Eulerian ones for equation (1.1). The position at time t of a particle with initial position (X, Y) and that is transported by the flow, is denoted by (x(t, X, Y), y(t, X, Y)). Using dots for differentiation with time t, these are related by the characteristics ODE

$$\dot{x} = u(t, x, y), \quad \dot{y} = v(t, x, y), \quad (x(0), y(0)) = (X, Y).$$
 (1.6)

Our definition of separation, meaning that the layer penetrates the outer flow (following Prandtl as cited in Subsubsection 1.1.1), is

Definition 1.1. Given $T_0 > 0$, u^E , $p^E \in C^1([0, T_0) \times \mathbb{R})$ solving (1.2) and $u \in C^1([0, T_0) \times \mathcal{H})$ solving (1.1), we say that there is boundary layer separation at time T_0 if there exists a solution (x(t), y(t)) of (1.6) such that $\lim_{t \uparrow T_0} y(t) = \infty$.

From (1.1), along the characteristics u solves the ODE $\dot{u} = -p_x^E(t, x)$. Therefore, the tangential position x of the particle can be retrieved without any knowledge about the normal one y, by solving the following ODE for each triple $(X, Y, u_0(X, Y))$:

$$\begin{cases} \dot{x} = u, \\ \dot{u} = -p_x^E(t, x), \end{cases} (x(0), u(0)) = (X, u_0(X, Y)).$$
 (1.7)

The above equation is that of one dimensional particle moving in a force field $-p_x^E$. The corresponding change of variables $(X,Y)\mapsto (X,u)$ is called the Crocco transform and has been used extensively in the study of the Prandtl system. One key fact about (1.1) is that the vorticity u_y is preserved along the characteristics, as differentiating (1.1) with respect to y yields $u_{yt}+uu_{yx}+vu_{yy}=0$ because p^E does not depend on y, and using incompressibility. Hence the set $\{u_y=0\}$ is transported by the characteristics. The boundary $\{y=0\}$ is also preserved as $v_{|y=0}=0$. Hence for any (x,y) either in the set $\{u_y=0\}$ or at the boundary $\{y=0\}$, one has $v_xu_y=0$, so that differentiating (1.1) with respect to x yields $u_{xt}+uu_{xx}+vu_{xy}=-(u_x)^2-p_{xx}^E$. It follows from this equation and (1.7) that the transport along the tangential variable and the tangential compression u_x , when restricted to these two sets, are given by the previous ODE completed by an inhomogeneous Riccati equation as follows

$$\begin{cases}
\dot{x} = u, \\
\dot{u} = -p_x^E(x), \\
\dot{u}_x = -(u_x)^2 - p_{xx}^E(x),
\end{cases} (x, u, u_x)(0) = (X, u_0(X, Y), u_{0x}(X, Y)).$$
(1.8)

Given a global in time pressure field $p^E \in C^k([0,\infty) \times \mathbb{R})$ with $k \ge 2$, the solution to the above system might not exist for all time due to the nonlinearity in the last equation, and we denote by T(X,Y) the corresponding maximal time of existence. We will distinguish later on between singularities happening at the boundary or away from it, and define, to this end

$$T := \min(T_a, T_b), \quad T_a := \min\{T(X, Y), \quad \partial_Y u_0(X, Y) = 0, \quad Y > 0\},$$

$$T_b := \min\{T(X, Y), \quad Y = 0\}.$$
(1.9)

The time T defined above is a natural upper bound for the maximal existence of a solution to (1.1) with $u_x \in L^{\infty}$. In fact, this time is sharp. We introduce the spaces

$$\begin{split} &L^{\infty}_{\text{loc},0}([0,\infty)\times\mathbb{R})\\ &=\left\{f,\ \|f\|_{L^{\infty}([0,t]\times\mathbb{R})}<\infty\ \text{and}\ \lim_{m\to\infty}\|f\|_{L^{\infty}([0,t]\times\{|x|\geqq m\})}=0\ \text{for all}\ t>0\right\},\\ &\mathcal{F}^k=\left\{(u^E,p^E_x)\in C^k([0,\infty)\times\mathbb{R})\ \text{solving}\ (1.2),\ \text{with}\ (u^E_x,p^E_{xx})\in L^{\infty}_{\text{loc},0}([0,\infty)\times\mathbb{R})\right\}, \end{split}$$

for the outer flow, and the following spaces for the initial datum (depending on $u^{E}(0)$):

$$\begin{split} L_0^\infty(\mathcal{H}) &= \left\{ f, \ \|f\|_{L^\infty(\mathcal{H})} < \infty \text{ and } \lim_{m \to \infty} \|f\|_{L^\infty(\{|x| \ge m\} \times [0,\infty))} = 0 \right\}, \\ \mathcal{E}^k &= \left\{ u_0 \in C^k(\mathcal{H}) \text{ with } \partial_y u_0 \in L^\infty(\mathcal{H}), \ \partial_x u_0 \in L_0^\infty(\mathcal{H}) \right. \\ &\qquad \qquad \text{and } \lim_{y \to \infty} \|u_0(\cdot,y) - u^E(0,\cdot)\|_{C^1(\{|x| \le m\})}, \text{ for all } m > 0 \right\}. \end{split} \tag{1.11}$$

Theorem 1. For any $(u^E, p_x^E) \in \mathcal{F}^2$ and $u_0 \in \mathcal{E}^2$, there exists a unique solution $u \in C^1([0,T) \times \mathcal{H})$ of (1.1) where T is defined by (1.9). This satisfies $\sup_{t \in [0,\tilde{T}]} \|\nabla u(t)\|_{L^{\infty}(\mathcal{H})} < \infty$ for any $\tilde{T} < T$. If T is finite, then

$$\lim_{t \uparrow T} \|u_X(t)\|_{L^{\infty}(\mathcal{H})} = \infty,$$

and if, moreover, $T = T_a$ then there is boundary layer separation at time T in the sense of Definition 1.1. If in addition $u_0 \in C^k(\mathcal{H})$ and $(u^E, p_x^E) \in C^k([0, \infty) \times \mathbb{R})$ for some $k \geq 3$, then $u \in C^{k-1}([0, T) \times \mathcal{H})$. The mapping which to u_0 assigns the solution u is strongly continuous from $C^k(\mathcal{H}) \cap \mathcal{E}^2$ into $C^{k-1}([0, T'] \times \mathcal{H})$ for any T' < T.

Remark 1.2. Boundedness of the gradient in (1.10) and (1.11) is the natural requirement for classical solutions. The decay as $|x| \to \infty$ facilitates the study of singularities, forcing them to appear at a finite location in x, and not at infinity in x. We use the word singularity as it is usual, but it can be misleading: the solution might remain smooth at time T. Indeed, the points where u_x becomes large can be sent to infinity in the normal direction as the study below shows. Also, from Theorem 1 and the ODE (1.8), one easily derives the following criteria for global-well posedness or finite time blow-up:

• In the case of normal monotonicity $u_y > 0$ or $u_y < 0$, the solution is global if and only if the solution to the Burgers equation at the boundary

$$\partial_t u_{|y=0} + u_{|y=0} \partial_x u_{|y=0} = -p_x^E$$

is global.

- The solution is global in the case of tangential growth $u_{0x} \ge 0$ on both the set of zero vorticity $\{u_{0y} = 0\}$ and the boundary $\{y = 0\}$, and of concave pressure $p_{xx}^E \le 0$.
- The maximal time of existence is $T = (-\min_{\{u_{0y}=0\} \cup \{y=0\}} u_{0x})^{-1}$ in the pressureless case $p^E = 0$ (with the convention $T = \infty$ if the min is nonnegative).

Remark 1.3. For a singularity away from the wall, $T_a < T_b$, let (X_0, Y_0) be the point attaining the minimum in the definition of T_a . Then the time dependent position (x(t), y(t)) in Definition 1.1 can be chosen as the characteristics starting initially at (X_0, Y_0) . One thus recovers a standard criterion for separation in the physics

literature: the MRS conditions of Subsubsection 1.1.1 at this point (x(t), y(t)) supplemented by the appearance of a Burgers type compression at this point (this supplementary condition was found by Van Dommelen and Shen [36]).

1.2.2. The Generic Self-Similar Singular Solution Considering the nonlinearity in the ODE (1.8), Theorem 1 and a standard convexity argument shows that given any prescribed Eulerian flow u^E and p^E , there exist initial data u_0 such that the corresponding solution becomes singular in finite time. Theorem 1 also indicates where singularities of (1.1) form: either at the boundary $\{y=0\}$, or away from the boundary on the set of zero vorticity $\{y>0, u_y=0\}$. We now focus on the description of this phenomenon. Motivated by the full original viscous Prandtl system, where the Dirichlet boundary condition forces $u_{|y=0}=0$, we will only study what happens when the singularity forms away from the boundary, i.e. $T_a < T_b$ and $T_a < \infty$. The study done in this document could be adapted to the case of a blow-up at the boundary.

We are interested first in a leading order description of the singularity. Since as ∇u becomes large, the effects of the pressure p^E and of the boundary conditions become of lower order, we start by dropping them and investigate the homogeneous inviscid Prandtl system

$$\begin{cases} u_t + uu_x + vu_y = 0, \\ u_x + v_y = 0, \quad v|_{y=0} = 0, \end{cases} (t, x, y) \in [0, T) \times \mathcal{H}.$$
 (1.12)

This equation has the following invariances: if u is a solution then so is

$$\frac{\mu}{\lambda}\iota u\left(\frac{t}{\lambda}, \iota \frac{x - ct}{\mu}, \frac{y}{v}\right) + c \tag{1.13}$$

for $(\iota, \lambda, \mu, \nu, c) \in \{-1, 1\} \times (0, \infty)^3 \times \mathbb{R}$. Backward self-similar solutions are special solutions living in the orbit of the initial datum under the action of a one dimensional scaling subgroup, of the form $u(t, x, y) = (T - t)^{\alpha - 1}\Theta(x/(T - t)^{\alpha}, y/(T - t)^{\beta})$. We develop in this paper, in Section 3, a method to find the admissible exponents α and β , and an explicit formula for Θ . To have a solution to (1.12) of this form is equivalent to have a solution of the stationary equation

$$\begin{cases} (1 - \alpha)\Theta + (\alpha \mathcal{X} + \Theta)\partial_{\mathcal{X}}\Theta + (\beta \mathcal{Y} + \Upsilon)\partial_{\mathcal{Y}}\Theta = 0, \\ \partial_{\mathcal{X}}\Theta + \partial_{\mathcal{Y}}\Upsilon = 0, \end{cases} (\mathcal{X}, \mathcal{Y}) \in \Omega,$$

$$(1.14)$$

subject to the condition $\lim_{y\to 0} \Upsilon = 0$, on an open set $\Omega \subset \mathcal{H}$ (which might be different than \mathcal{H} , see below). The above equation (1.14) is nonlinear and nonlocal. Cassel, Smith and Walker [4] (see also [13]) give a change of variables to transform (1.14) into a nonlinear local equation, see (iii) in Lemma 3.1 here, proving the

¹ The MRS conditions are satisfied because of Definition 1.1 and because $\partial_y u_0(X_0, Y_0) = 0$ from (1.9) so that $\partial_y u(t, x(t), y(t)) = 0$ by conservation of vorticity. There is a Burgers type compression because $\partial_x u(t, x(t), y(t)) \to -\infty$ as $t \to T_a$ since the third equation in (1.8) becomes singular from the definition of T_a .

existence of solutions to (1.14) but without providing explicit formulas. We find here a new way to solve (1.14) and show, see (ii) in Lemma 3.1, that (1.14) is equivalent to the linear and local equation

$$(\alpha - 1)a\partial_{\alpha}\mathcal{X} + (1 + \beta)\theta\partial_{\theta}\mathcal{X} = \alpha\mathcal{X} - a, \qquad (a, \theta) \in \Omega', \tag{1.15}$$

where \mathfrak{X} is seen as a function of the variables (α, \mathfrak{k}) given by a volume preserving change of variables $(\mathfrak{X}, \mathfrak{Y}) \mapsto (\alpha, \mathfrak{k})$ with $\alpha = -\Theta$. A Lagrangian interpretation of this change of variables is given in Remark 1.5.

We obtain two important explicit solutions of Equation (1.15), with explicit changes of variables $(\alpha, \beta) \mapsto (\mathfrak{X}, \mathfrak{Y})$. Although these changes of variables appear from a different perspective in [37,38], it seems that the authors did not link them to solutions of (1.14). Classifying analytic solutions to (3.1), relying on (1.15), is an interesting open problem. The first solution we obtain, the generic self-similar profile, corresponds to $\alpha = 3/2$, $\beta = -1/4$ and is the one related to the so-called Van-Dommelen and Shen singularity [36]. The terminology "generic" is justified in the next Subsection. We introduce (Γ being the Gamma function)

$$p^* := \frac{4}{9\pi^3} \Gamma\left(\frac{1}{4}\right)^4. \tag{1.16}$$

We describe below the generic profile Θ , obtained from an explicit solution \mathcal{X} to (1.15) and an explicit change of variables $\Phi : (\alpha, \beta) \mapsto (\mathcal{X}, \mathcal{Y})$ relating (1.15) to (1.14).

Proposition 1. (Generic self-similar profile) *The mapping* $\Phi : (a, b) \mapsto (\mathfrak{X}, \mathcal{Y})$ *given by*

$$\Phi(a, \ell) = \left(a + \ell^2 + p^{*2}a^3, \int_{-\infty}^{\ell} \frac{d\tilde{\ell}}{1 + 3\Psi_1^2 \left(p^* \left(a + p^{*2}a^3 + \ell^2 - \tilde{\ell}^2\right)\right)}\right), \tag{1.17}$$

where Ψ_1 and p^* are defined by (1.4) and (1.16), satisfies the following properties:

(i) It is an analytic volume preserving diffeomorphism between \mathbb{R}^2 and the subset of the upper half plane $\{(\mathfrak{X}, \mathcal{Y}) \in \mathcal{H}, \ 0 < \mathcal{Y} < 2\mathcal{Y}^*(\mathfrak{X})\}$ where

$$\mathcal{Y}^*(\mathfrak{X}) = \int_0^\infty \frac{\mathrm{d}\tilde{\ell}}{1 + 3\Psi_1^2(p^*(\mathfrak{X} - \tilde{\ell}^2))}.$$
 (1.18)

The above curve \mathcal{Y}^* is analytic and satisfies

$$\mathcal{Y}^*(\mathcal{X}) = \frac{3\pi}{8} + \mathcal{X} + \frac{c_2}{2}\mathcal{X}^2 + O(|\mathcal{X}|^3), \quad \text{as } \mathcal{X} \to 0,$$
 (1.19)

$$\mathcal{Y}^*(\mathfrak{X}) = C_{\pm}|\mathfrak{X}|^{-\frac{1}{6}} + O\left(|\mathfrak{X}|^{-\frac{5}{6}}\right) \quad \text{as } \mathfrak{X} \to \pm \infty, \tag{1.20}$$

where $c_2 = -\frac{5\Gamma(1/4)}{72\pi^5}$, and $C_{\pm} = 2^{-1}p^{*-2/3}\int_{\mp 1}^{\infty} (z^3 \pm 1)^{-1/2} dz$ (see (3.19) for a formula).

(ii) The opposite of the first component of its inverse $\Phi^{-1} = (\Phi_1^{-1}, \Phi_2^{-1})$,

$$\Theta := -\Phi_1^{-1} : (\mathfrak{X}, \mathfrak{Y}) \mapsto -a, \tag{1.21}$$

is a self-similar profile, that is, the following is a solution of (1.12) on its support:

$$u(t, x, y) = (T - t)^{\frac{1}{2}} \Theta\left(\frac{x}{(T - t)^{\frac{3}{2}}}, \frac{y}{(T - t)^{-\frac{1}{4}}}\right).$$
(1.22)

- (iii) It enjoys the symmetry $\Theta(\mathfrak{X}, \mathcal{Y}^*(\mathfrak{X}) + \mathcal{Y}) = \Theta(\mathfrak{X}, \mathcal{Y}^*(\mathfrak{X}) \mathcal{Y})$ for $|\mathcal{Y}| < \mathcal{Y}^*(\mathfrak{X})$.
- (iv) The set of zero vorticity $\{\Theta_{\mathcal{Y}}=0\}$ is the curve $\{\mathcal{Y}=\mathcal{Y}^*(\mathfrak{X})\}$, where $\Theta(\mathfrak{X},\mathcal{Y}^*)$
 - (\mathfrak{X})) = $\Psi_1(p^*\mathfrak{X})/p^*$. On this curve, $\partial_{\mathfrak{X}}\Theta$ is minimal at $(0, 3\pi/8)$ with, as $(\mathfrak{X}, \mathfrak{Y}) \to 0$,

$$\Theta\left(\mathfrak{X}, \frac{3\pi}{8} + \mathcal{Y}\right) = -\mathfrak{X} + (\mathfrak{X} - \mathcal{Y})^2 + \left(p^{*2} + c_2\right)\mathfrak{X}^3$$
$$-c_2\mathfrak{X}^2\mathcal{Y} + O(\mathfrak{X}^4 + \mathcal{Y}^4). \tag{1.23}$$

(v) Θ has the following behaviour near the boundary of its domain:

$$\Theta(\mathfrak{X}, \mathcal{Y}) = p^{*-2} \mathcal{Y}^{-2} + O(|\mathcal{X}| \mathcal{Y}^4 + \mathcal{Y}^2) \qquad \text{for } 0 < \mathcal{Y} \leq \mathcal{Y}^*(\mathfrak{X})$$
(1.24)

$$\Theta(\mathfrak{X},2\mathcal{Y}^*(\mathfrak{X})-\mathcal{Y})=p^{*-2}\mathcal{Y}^{-2}+O(|\mathfrak{X}|\mathcal{Y}^4+\mathcal{Y}^2) \ \ \textit{for} \ 0<\mathcal{Y}\leqq\mathcal{Y}^*(\mathfrak{X}), \eqno(1.25)$$

and the following behaviour at infinity²: for any $\epsilon > 0$, for $0 < \mathcal{Y} < (2 - \epsilon)\mathcal{Y}^*(\mathfrak{X})$:

$$\Theta(\mathfrak{X}, \mathcal{Y}) = |\mathfrak{X}|^{\frac{1}{3}} \varphi_{\pm \infty}(\mathcal{Y}|\mathfrak{X}|^{1/6}) + O\left(|\mathfrak{X}|^{-\frac{2}{3}} \mathcal{Y}^{-2} + |\mathfrak{X}|^{-1} (2\mathcal{Y}^*(\mathfrak{X}) - \mathcal{Y})^4\right), \tag{1.26}$$

as $\mathfrak{X} \to \pm \infty$, where $\varphi_{\pm} \in C^{\infty}((0, 2C_{\pm}), \mathbb{R})$ is decreasing on $(0, C_{\pm})$, increasing on $(C_{\pm}, 2C_{\pm})$, with $\varphi_{\pm}(z) \sim p^{*-2}z^{-2}$ and $\varphi_{\pm}(2C_{\pm}-z) \sim p^{*-2}z^{-2}$ as $z \to 0$, and $\varphi_{\pm}(C_{\pm}) = \mp p^{*-2/3}$.

Remark 1.4. From the invariances (1.13) of the equation (1.12), Θ generates the full family of generic profiles $(\Theta_{\mu,\nu,\iota})_{(\mu,\nu,\iota)\in(0,\infty)^2\times\{-1,1\}}$ where $\Theta_{\mu,\nu,\iota}(\mathcal{X},\mathcal{Y})=\mu\iota\Theta(\iota\mathcal{X}/\mu,\mathcal{Y}/\nu)$, in that $u(t,x,y)=(T-t)^{1/2}\Theta_{\mu,\nu,\iota}(x/(T-t)^{3/2},y/(T-t)^{-1/4})$ also solves (1.12). The profile $\Theta_{\mu,\nu,\iota}$ is obtained from the mapping:

² The condition $\mathcal{Y}<(2-\epsilon)\mathcal{Y}^*$ ensures both quantities $\Theta(\mathfrak{X},\mathcal{Y})$ and $\varphi_{\pm\infty}(\mathcal{Y}|\mathcal{X}|^{1/6})$ are defined. Note that on $[(2-\epsilon)\mathcal{Y}^*,2\mathcal{Y}^*)$ the asymptotics (1.25) prevails.

$$\begin{split} & \Phi_{\mu,\nu,\iota}(\alpha, \delta) \\ & = \left(\alpha + \iota \frac{\mu}{\nu^2} \delta^2 + \frac{p^{*2}}{\mu^2} \alpha^3, \ \int_{-\infty}^{\delta} \frac{\mathrm{d}\tilde{\theta}}{1 + 3\Psi_1^2 \left(p^* \left(\frac{\alpha}{\mu} + \frac{p^{*2}}{\mu^3} \alpha^3 + \frac{\iota}{\nu^2} \delta^2 - \frac{\iota}{\nu^2} \tilde{\theta}^2 \right) \right)} \right) \end{split}$$

via $\Theta_{\mu,\nu,\iota} = -\Phi_{\mu,\nu,\iota,1}^{-1}$ where we wrote $\Phi_{\mu,\nu,\iota}^{-1} = (\Phi_{\mu,\nu,\iota,1}^{-1}, \Phi_{\mu,\nu,\iota,2}^{-1})$. Therefore, changing the value (1.16) of p^* in (1.17) would have defined another self-similar profile as well. The choice of p^* (1.16) was made to normalise the Taylor expansion (1.23).

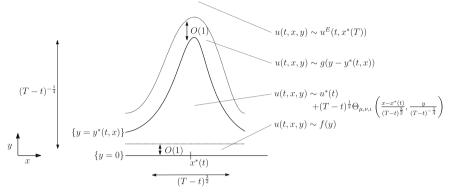
Remark 1.5. The variables (α, β) in (1.17) should be thought, asymptotically as $t \uparrow T$, as Lagrangian self-similar variables. Indeed, for the self-similar solution $u(t, x, y) = (1 - t)^{1/2}\Theta(x/(1 - t)^{3/2}, y/(1 - t)^{-1/4})$ of (1.12) with initial datum $u_0(x, y) = \Theta(x, y)$, let $(X, Y) \mapsto (x, y)$ be the Lagrangian to Eulerian map defined in Subsubsection 1.2.1, let $(x, y) \mapsto (\mathfrak{X}, \mathcal{Y}) = (x/(1 - t)^{3/2}, y/(1 - t)^{-1/4})$ be the Eulerian self-similar renormalisation, and let $(\mathfrak{X}, \mathcal{Y}) \mapsto (\alpha, \beta) = \Phi^{-1}(\mathfrak{X}, \mathcal{Y})$ be as in (1.17). Compositing these maps, we get a map $(X, Y) \mapsto (\alpha, \beta)$, allowing to interpret what the (α, β) variables represent for the Lagrangian variables (X, Y). A computation shows that they are related through: $(X, Y) = \Phi((1 - t)^{1/2}\alpha, (1 - t)^{3/4}\beta)$. Thus, for $(\alpha, \beta) = O(1)$, a Taylor expansion, using Proposition 1, produces

$$(X,Y) = \left(0, \frac{3\pi}{8}\right) + (1-t)^{\frac{1}{2}} \alpha \cdot (1,1) + (1-t)^{\frac{3}{4}} \beta \cdot (0,1) + O((1-t)).$$

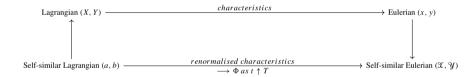
Asymptotically as $t \uparrow 1$, the change of variables $(X, Y) \mapsto (\alpha, \beta)$ is then a linear rescaling centred at $(0, 3\pi/8)$, namely, it is asymptotically a *self-similar* renormalisation centred at that point.

1.2.3. Generic singularity leading to boundary layer separation The self-similar profile Θ given by Proposition 1 is at the heart of the singularity formation for the inviscid Prandtl equations, triggering the separation of the boundary layer. In this paper we show the appearance of this self-similar profile from a generic set (dense, and open, among data producing singularities) of initial data u_0 . This shows that the effects of the outer Eulerian flow (u^E , p^E) might alter the position and time of appearance of the singularity, but not its structure (the profile Θ and the self-similar exponents 3/2 and -1/4), and hence are of lower order. The generic singularity is a consequence of a tangential generic Burgers-type compression occurring on a line of zero vorticity, and induces a normal expansion by volume preservation. We





The idea behind the generic appearance of Θ is the following. A shock is forming at a moving location (x^*, y^*) in Eulerian variables. This point corresponds in Lagrangian variables to a point (X_0, Y_0) , at which the characteristics map $(X, Y) \mapsto (x, y)$ becomes critical (i.e., the Jacobian vanishes) at blow-up time. Generically, the characteristics map will satisfy certain properties at this location, see Section 4, ensuring that the following holds true. Around that point, there exist self-similar Lagrangian variables (a, b) (see (5.2) for a precise definition) such that for appropriate self-similar Eulerian variables $(\mathfrak{X}, \mathfrak{Y})$ the renormalised characteristics map becomes asymptotically time independent as $t \uparrow T$, and converges to Φ .



Finding a solution to the transport equation (1.12) is equivalent to finding the characteristics. Thus, this knowledge of an asymptotic equivalent for the characteristics map, allows one to show the existence of an asymptotic equivalent for u: it is close to a rescaling of the self-similar profile Θ . Said differently, solutions of the inviscid Prandtl equations become asymptotically self-similar during singularity formation, because the characteristics become asymptotically self-similar.

The profile Θ cannot be an approximation of u away from the singularity; the support of Θ is finite, and there are two singular zones within its support, at infinity in space in the tangential variable (1.26), and close to the boundary (1.24)–(1.25). One thus needs else to describe the solution in these two zones, and above the support of Θ . We show that below the separating structure, u reconnects to a regular profile (f in the Theorem below and the picture above). Above the singularity, u reconnects to a less singular profile as well, but that undergoes a strong vertical motion created by the singularity underneath it (g in the Theorem and picture).

We denote by $d_{C^k_{loc}}$ the standard³ C^k_{loc} distance for functions on $\mathcal H$ that are k times continuously differentiable, and equip $\mathcal E^k$ with the topology associated to the distance

$$d_{\mathcal{E}^k}(u_0, u_0') = d_{C_{\text{loc}}^k}(u_0, u_0') + \|\nabla(u_0 - u_0')\|_{L^{\infty}(\mathcal{H})}.$$

We define $\mathcal{Y}_{\mu,\nu,\iota}^*(\mathfrak{X}) = \nu \mathcal{Y}^*(\iota \mathfrak{X}/\mu)$.

Theorem 2. (Generic Separation) Let $(p_x^E, u^E) \in \mathcal{F}^4$. In the subset of \mathcal{E}^4 of initial data u_0 such that $T < \infty$ and $T < T_b$, there exists a dense open set for which the corresponding solution satisfies the following. There exist parameters $(\mu, \nu, \iota) \in (0, \infty)^2 \times \{-1, 1\}$ and two constants $\kappa, C > 0$ such that

- Location of the singularity. There exists $x^* \in C^4([0, T], \mathbb{R})$, regular up to time T such that $\nabla u(t)$ remains bounded in $\{(x, y, t), 0 \le t \le T, |x x^*(t)| \ge \epsilon\}$ for any $\epsilon > 0$.
- Displacement line. There exists $y^* \in C^3([0,T) \times \mathbb{R})$ for which the properties below hold true, with:

$$y^{*}(t,x) = \frac{2}{(T-t)^{\frac{1}{4}}} \mathcal{Y}_{\mu,\nu,\iota}^{*} \left(\frac{x-x^{*}}{(T-t)^{\frac{3}{2}}} \right)$$

$$\left(1 + O\left((1-t)^{\kappa} + |x-x^{*}(t)|^{\kappa} \right) \right).$$
(1.27)

• Self-similarity. Let $\eta(t, x, y) = ((T - t)^{\kappa} + |x - x^*(t)|^{\kappa} + y^{-\kappa} + |y^*(t, x) - y|^{-\kappa})$ and let $u^*(t) = \partial_t x^*(t)$. For any $\epsilon > 0$, there exists $\tilde{\epsilon} > 0$ such that for $|x - x^*| \le \tilde{\epsilon}$ and $y \le (1 - \epsilon)y^*(t, x)$:

$$u(t, x, y) = u^*(t) + (T - t)^{\frac{1}{2}} (\Theta_{u, y, t} + \tilde{u}) (\mathfrak{X}, \mathcal{Y}),$$

where $\mathfrak{X} = (T-t)^{-3/2}(x-x^*(t))$, $\mathcal{Y} = (T-t)^{1/4}y$, and where \tilde{u} satisfies:

$$|\tilde{u}(t, \mathfrak{X}, \mathcal{Y})| \leq C \left(|\mathfrak{X}|^{\frac{1}{3}} + |\mathcal{Y}|^{-2} + \left((T - t)^{\frac{1}{4}} y^{*}(t, x) - \mathcal{Y} \right)^{-2} \right)$$

$$\eta(t, x, y)$$

$$|\partial_{\mathfrak{X}} \tilde{u}(t, \mathfrak{X}, \mathcal{Y})| \leq C \left(|\mathcal{Y}|^{4} + (1 + |\mathfrak{X}|)^{-\frac{7}{6}} \left((T - t)^{\frac{1}{4}} y^{*}(t, x) - \mathcal{Y} \right)^{-3} \right)$$

$$\eta(t, x, y)$$

$$|\partial_{\mathcal{Y}} \tilde{u}(t, \mathfrak{X}, \mathcal{Y})| \leq C \left(|\mathcal{Y}|^{-3} + \left((T - t)^{\frac{1}{4}} y^{*}(t, x) - \mathcal{Y} \right)^{-3} \right)$$

$$\eta(t, x, y).$$

$$(1.29)$$

For example, $d_{C_{loc}^k}(u_0, u_0') = \sum_{l=0}^k \sum_{n=1}^\infty 2^{-n} \min(\|\nabla^l(u_0 - u_0')\|_{L^\infty(\mathcal{H}_n)}, 1)$ with $\mathcal{H}_n = \{(x, y) \in \mathcal{H}, |x| \le n \text{ and } |y| \le n\}$. Another choice for the covering of compact sets $(\mathcal{H}_n)_n$ would yield an equivalent distance.

• Close to the displacement line. Given any $K, \epsilon > 0$, there exists $\tilde{\epsilon} > 0$ such that for $(1 - \epsilon)y^*(t, x) \le y \le y^*(t, x) - K$ and $|x - x^*| \le \tilde{\epsilon}$,

$$u(t, x, y) = u^*(t) + \frac{\mu v^2}{p^{*2}(y - y^*(t, x))^2} + \tilde{v}(t, x, y),$$
(1.31)

where, for $\tilde{\eta}(t, x, y) = ((T - t)^{\kappa} + |x - x^*|^{\kappa} + (y^* - y)^{-\kappa} + (|y^* - y|/y^*)^{\kappa}),$

$$|\tilde{v}| \leq \frac{C\tilde{\eta}(t, x, y)}{|y - y^*(t, x)|^2}, \quad |\partial_x \tilde{v}| \leq \frac{C\tilde{\eta}(t, x, y)}{\left((T - t)^{\frac{3}{2}} + |x|\right)^{\frac{7}{6}} |y - y^*(t, x)|^3},$$

$$|\partial_y \tilde{v}| \leq \frac{C\tilde{\eta}(t, x, y)}{|y - y^*(t, x)|^3}.$$
(1.32)

• Reconnections below and above. There exist two functions $f \in C^3([0, \infty), \mathbb{R})$ and $g \in C^3(\mathbb{R}, \mathbb{R})$ depending on u_0 , u^E and p^E with

$$f(y) - u^* \underset{y \to \infty}{\sim} \frac{\mu v^2}{p^{*2}} y^{-2}, \qquad g(y) - u^* \underset{y \to -\infty}{\sim} \frac{\mu v^2}{p^{*2}} y^{-2},$$

$$g(y) \underset{y \to \infty}{\rightarrow} u^E(T, x^*(T)), \tag{1.33}$$

such that, for any K > 0, as $(t, x) \to (T, x^*(T))$,

$$u(t, x, y) \to f(y)$$
 uniformly for $y \le K$, (1.34)
 $u(t, x, y) \to g(y - y^*(t, x))$ uniformly for $y^*(t, x) - K \le y$. (1.35)

Let us make the following comments on the results of Theorem 2:

- 1. The set considered in the above Theorem is nonempty. Indeed, given any outer Eulerian flow (u^E, p^E) , there exist solutions blowing up outside the boundary, as negative enough initial data for the third equation in (1.8) will tend to $-\infty$ in finite time. However, the structure for unsteady separation described in this Theorem is not the only one occurring, and degenerate instable singularities also exist; see Proposition 2.
- 2. The estimates for the error in (1.28), (1.29), (1.30) and (1.32) should be interpreted as follows. The first term in the right hand side is the typical size of Θ , $\partial_{\mathcal{X}}\Theta$ and $\partial_{\mathcal{Y}}\Theta$ respectively. The $\eta(t,x,y)$ term then quantifies a gain as $T-t\ll 1$, $|x-x^*|\ll 1$ and $1\ll y\ll y^*$. For example, for $(\mathfrak{X},\mathcal{Y})$ in a compact set \mathcal{X} in the support of $\Theta_{\mu,nu,t}$, these estimates imply $\|\tilde{u}\|_{C^1(\mathcal{X})} = O((T-t)^{C(\kappa)}) \to 0$. We have to distinguish between below the displacement line and near it as in this latter region the solution is close to a displaced version of Θ . The identities (1.31) and (1.32) indeed show the solution is close to the asymptotic expansion (1.24) of Θ near the top part of its support, but with y^* replacing $2\mathcal{Y}^*$. From the asymptotic behaviour of Θ in Proposition $1, \tilde{u}$ is of lower order compared to Θ precisely in a size one zone in x around x^* , and up to a size one distance to the boundary and the displacement

curve. These estimates are then sharp since they precisely fail when the solution reconnect to another nonsingular behaviour.

- 3. Note that the asymptotic behaviour of Θ and that of the reconnection functions f and g, in (1.34) and (1.35) respectively, are compatible from Proposition (1.24)–(1.25).
- 4. This convergence result also holds for higher order derivatives, which is a direct consequence of the proof of the Theorem. In particular the weighted estimates adapt naturally.
- **1.2.4.** A Self-Similar Profile with Symmetry Other degenerate singular behaviours are also possible. The degeneracy can come from two distinct aspects: at the singular point, the set of zero vorticity can locally not be a line (for example the intersection of two lines), and the tangential compression can be induced by a degenerate shock formation for Burgers. There exist a large range of self-similar profiles corresponding to these (infinitely many) degenerate cases. Their properties can also be studied with the same strategy used in the proof of Proposition 1, and their stability similarly as in Theorem 2. As a particular interesting example, we study in this paper one of the least degenerate cases, corresponding to a Burgers generic shock happening at the crossing of two lines of zero vorticity. A particular self-similar profile corresponding to this case enjoys remarkable properties: it is odd in x, admits an analytic expansion beyond its support, and explicit formulas can be obtained on the vertical axis. In a forthcoming paper we shall show its stability for the full Prandtl system. The prime 'notation below is not a differential, it is simply to distinguish from Proposition 1.

Proposition 2. (Degenerate symmetric profile) *The mapping* $\Phi': (\alpha, \ell) \mapsto (\mathfrak{X}, \mathcal{Y})$ *defined by*

$$\Phi'(\alpha, \ell) = \left(a + \alpha^3 + \frac{\ell^2 a}{4}, 2 \int_{-\infty}^{\frac{\ell}{2}} \frac{d\tilde{\ell}}{\left(1 + \tilde{\ell}^2 \right) \left(1 + 3\Psi_1^2 \left(\frac{a + \alpha^3 + \frac{\ell^2 a}{4}}{\left(1 + \tilde{\ell}^2 \right)^{3/2}} \right) \right)} \right), \tag{1.36}$$

where Ψ_1 is defined by (1.4), satisfies the following properties:

(i) It is an analytic volume preserving diffeomorphism between \mathbb{R}^2 and the subset of the upper half plane $\{0 < \mathcal{Y} < 2\mathcal{Y}^{'*}(\mathfrak{X})\}$, where

$$\mathcal{Y}^{'*}(\mathfrak{X}) = \int_{-\infty}^{\infty} \frac{\mathrm{d}\tilde{\ell}}{\left(1 + \tilde{\ell}^2\right) \left(1 + 3\Psi_1^2 \left(\frac{\mathfrak{X}}{\left(1 + \tilde{\ell}^2\right)^{3/2}}\right)\right)} \tag{1.37}$$

is an analytic curve with asymptotic expansion (with B the Euler integral of the first kind)

$$\mathcal{Y}'^{*}(\mathfrak{X}) \underset{\mathfrak{X} \to 0}{=} \pi - \frac{15}{16} \pi \mathfrak{X}^{2} + O(\mathfrak{X}^{4}),$$

$$\mathcal{Y}'^{*}(\mathfrak{X}) \underset{\mathfrak{X} \to \pm \infty}{=} \frac{B\left(\frac{1}{6}, \frac{1}{2}\right)}{3} |\mathfrak{X}|^{-\frac{1}{3}} + O(|\mathfrak{X}|^{-1}). \tag{1.38}$$

(ii) The opposite of the first component of its inverse, extended by 0 on the upper half-space,

$$\Theta'(\mathfrak{X}, \mathcal{Y}) = \begin{cases} -\Phi_1^{'-1}(\mathfrak{X}, \mathcal{Y}) = \alpha & \text{if } 0 < \mathcal{Y} < 2\mathcal{Y}'^*(\mathfrak{X}), \\ 0 & \text{if } \mathcal{Y} = 0 \text{ or } 2\mathcal{Y}'^*(\mathfrak{X}) \leq \mathcal{Y}, \end{cases}$$
(1.39)

is a self-similar profile. Namely, the following is a solution of (1.12):

$$u(t, x, y) = (T - t)^{\frac{1}{2}} \Theta' \left(\frac{x}{(T - t)^{\frac{3}{2}}}, \frac{y}{(T - t)^{-\frac{1}{2}}} \right)$$
(1.40)

(iii) it holds that $\Theta' \in C^1(\mathcal{H})$. Moreover, Θ' , restricted to the set $\{0 \leq \mathcal{Y} \leq 2\mathcal{Y}^{'*}(\mathfrak{X})\}$ is analytic, including at the boundaries $\{\mathcal{Y}=0\} \cup \{\mathcal{Y}=2\mathcal{Y}^{'*}(\mathfrak{X})\}$. The following extension 4 :

$$\overline{\Theta}'(\mathfrak{X}, \mathcal{Y}) := \Theta'(\mathfrak{X}, \mathcal{Y} \bmod 2\mathcal{Y}^{'*}(\mathfrak{X})) \tag{1.41}$$

is analytic on the whole upper half space, and is also a self-similar profile, in the sense that $\overline{u}(t, x, y) = (T-t)^{1/2}\overline{\Theta}'(x/(T-t)^{\frac{3}{2}}, y/(T-t)^{-\frac{1}{2}})$ is a solution of (1.12).

- (iv) Θ' is odd in \mathfrak{X} , and satisfies $\Theta'(\mathfrak{X}, \mathcal{Y}'^*(\mathfrak{X}) + \mathcal{Y}) = \Theta'(\mathfrak{X}, \mathcal{Y}'^*(\mathfrak{X}) \mathcal{Y})$ for all $|\mathcal{Y}| < \mathcal{Y}'^*(\mathfrak{X})$. Θ' is positive on the set $\{\mathfrak{X} < 0, \ 0 < \mathcal{Y} < 2\mathcal{Y}'^*(\mathfrak{X})\}$ and negative on $\{\mathfrak{X} > 0, \ 0 < \mathcal{Y} < 2\mathcal{Y}'^*(\mathfrak{X})\}$.
- (v) The set $S = \{\partial_{\mathcal{Y}}\Theta' = 0\}$ is equal to $S_1 \cup S_2$ where $S_1 = \{\mathfrak{X} = 0\} \cup \{\mathcal{Y} = \mathcal{Y}'^*(\mathfrak{X})\}$ on which $\Theta'(\mathfrak{X}, \mathcal{Y}'^*(\mathfrak{X})) = \Psi_1(\mathfrak{X})$, and $S_2 = \{\mathcal{Y} = 0\} \cup \{\mathcal{Y} \geq 2\mathcal{Y}'^*(\mathfrak{X})\}$. The minimum of $\partial_{\mathfrak{X}}\Theta'$ on the set S is attained at $(0, \pi)$ where one has the expansion

$$\Theta'(\mathfrak{X}, \pi + \mathcal{Y}) = -\mathfrak{X} + \mathfrak{X}^3 + \frac{\mathcal{Y}^2}{4}\mathfrak{X} + O(|\mathfrak{X}|^5 + |\mathcal{Y}|^4 |\mathfrak{X}|)$$

$$as (\mathfrak{X}, \mathcal{Y}) \to (0, 0). \tag{1.42}$$

(vi) The trace of the first order tangential derivative on the vertical axis is given by:

$$\partial_{\mathcal{X}}\Theta'(0,\mathcal{Y}) = -\sin^2\left(\frac{\mathcal{Y}}{2}\right)\mathbb{1}_{0 \le \mathcal{Y} \le 2\pi}.\tag{1.43}$$

⁴ Where for $z \ge 0$ and z' > 0, we write $z = kz' + z \mod z'$, $k \in \mathbb{N}$, $0 \le z \mod z' < z'$. At each fixed \mathfrak{X} , this is a periodic extension along \mathcal{Y} with period $2\mathcal{Y}^{'*}(\mathfrak{X})$.

(vii) The trace of the third order derivative on the vertical axis is given by:

$$\begin{split} & \partial_{\mathcal{X}}^{3} \Theta'(0,Y) \\ & = \frac{1}{576} \left[\frac{96 \sin^{8} \left(\frac{\mathcal{Y}}{2} \right)}{\cos^{2} \left(\frac{\mathcal{Y}}{2} \right) + \frac{1}{6}} \right. \\ & \left. - \sin(\mathcal{Y}) \left(270\mathcal{Y} - 80 \sin(\mathcal{Y}) + 3 \sin(2\mathcal{Y}) - \frac{686 \sin(\mathcal{Y})}{3 \cos^{2} \left(\frac{\mathcal{Y}}{2} \right) + \frac{1}{2}} \right) \right] \\ & \mathbb{1}_{0 \le \mathcal{Y} \le 2\pi}. \end{split}$$

The above function is positive on $(0, 2\pi)$. It admits the expansions as $\mathcal{Y} \to 0$:

$$\partial_{\mathfrak{T}}^{3}\Theta'(0,\mathcal{Y}) = c\mathcal{Y}^{8} + O(\mathcal{Y}^{10}), \ \partial_{\mathfrak{T}}^{3}\Theta'(0,2\pi - \mathcal{Y}) = c'\mathcal{Y} + O(\mathcal{Y}^{2}), \ c,c' > 0.$$

Remark 1.6. • Note the difference in the scaling exponents when comparing (1.40) with the generic profile (1.22). The above degenerate profile yields a slower expansion along the normal direction.

• In [6], we show that there is a stable blow-up pattern for equation 1.3, for which solutions converge to $(T-t)^{-1}\sin^2\left(y/(\nu 2(T-t)^{-1/2})\right)\mathbb{1}_{0\leq y\leq \nu 2\pi(T-t)^{-1/2}}$. This partially shows that the profile of Proposition 2 is the stable attractor for solutions that are odd in x when the singularity is located on the transversal axis.

1.3. Ideas of the Proofs and Organisation of the Paper

The proof of the local well-posedness result in Theorem 1 for regular initial data relies on a careful study of the characteristics (1.6) and of the ODEs for tangential displacement (1.7) underlying them, which then permits to retrieve the normal displacement by volume preservation (Lemma A.1). The sharp expression we find for the maximal time of existence is a consequence of two volume preserving dynamics: that of the characteristics map from Lagrangian to Eulerian variables, and that of the ODE for tangential displacement (1.7) in the (x, u) phase space.

In the study of the self-similar profiles, the transformation of (1.14) into (1.15) uses a modified Crocco transform relying on the fact that the vector field in (1.14) has constant divergence. The solutions (1.17) and (1.36) are found by solving (1.15), and all the properties of the profiles can be obtained from computations on these explicit formulas.

To obtain the generic appearance of the generic self-similar profile during separation/singularity formation, we first define (Definition 4.1) a condition for the characteristics at their first critical point at time T. This condition is stable under perturbations, by standard ODE stability arguments. Using a control argument, we moreover show an initial datum u_0 leading to blow-up can always be perturbed to ensure this condition is met at time T. Roughly speaking, this means that the map $u_0 \mapsto u(T)$ is invertible, which relies on the fact that (1.7) is volume preserving in the (x, u) phase space. We then reconstruct the solution around the point at which

the shock is forming using the characteristics map. We prove this map, since satisfying the aforementioned condition, after suitable self-similar renormalisations both in Lagrangian and Eulerian variables, converge to Φ defined by (1.17). We invert the characteristics, by a uniform application of the local inversion Theorem for $(x, y) \in [x^* - \epsilon, x^* + \epsilon] \times [0, \infty)$, and show it is close to Φ^{-1} in the self-similar zone. This part is lengthy and technical since, as the characteristics map becomes degenerate and has distinct asymptotic behaviours in various zones, each requiring a specific treatment, and since we track precisely all error terms to obtain an optimal picture (in an Eulerian zone of optimal $O(1) \times [0, \infty)$ size). The solution u is then retrieved from the characteristics, and explicit computations end the proof of Theorem 2.

The paper is Section 2 is devoted to the proof of Theorem 1, showing local existence of solutions and computing the maximal time of existence. Self-similar profiles are studied in Section 3. Subsection 3.1 transforms the self-similar profile equation (1.14) into the linear and local equation (1.15). The generic profile is studied in Subsection 3.2 where Proposition 1 is proved, the degenerate one in Subsection 3.3 where Proposition 2 is proved. The rest of the article is devoted to the proof of Theorem 2. The Definition 4.1 of generic singularity for the characteristics is given in Subsection 4 where it is proved to hold generically. Section 5 then establishes the conclusions of Theorem 2 for solutions satisfying this condition. Appendix A shows how to retrieve one component of a 2-d volume preserving map from the other, and Appendix B contains computations for the characteristics used in the proof of Theorem 2.

Notations

We write $x \lesssim y$ if there exists a constant C > 0 independent of the context such that $x \leq Cy$. We write $x \approx y$ if $x \lesssim y$ and $y \lesssim x$. We use Lagrangian variables (X,Y) and Eulerian variables (x,y). As they are equal at the initial time, we might use one notation or the other in several places, but in this context only. We use the notations ∂_x , ∂/∂_x or the subscript \cdot_x to indicate partial differentiation. In some contexts, we write $\frac{\partial f}{\partial x}|_y$ to indicate partial differentiation with respect to x with the variable y being kept fixed.

2. Local Well-Posedness and Time of Existence

This section is devoted to the proof of Theorem 1. We establish here local-existence of solutions to the inviscid Prandtl system (1.1), prove that T given by (1.9) is the maximal time of existence, and that separation occurs if T is finite.

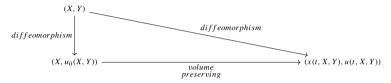
Proof of Theorem 1. The proof relies on the special structure of the characteristics and uses the Crocco transformation. The existence follows from their nondegeneracy until time T, while the regularity follows from standard regularity theory for level sets of functions. We denote by $\nabla = (\partial_X, \partial_Y)$ the nabla operator in Lagrangian variables.

Step 1 Existence. We aim at establishing the existence and a formula for the characteristics, $\phi[t]:(X,Y)\mapsto(x,y)$ with $\phi=(\phi_1,\phi_2)$. We first solve, for the tangential displacement,

$$x(t, X, Y) = \phi_1[t](X, Y),$$
 (2.1)

where x above is the solution of (1.7). Notice that (1.7) can always be solved *globally* in time, so that x(t, X, Y) is well-defined for all $(t, X, Y) \in \mathbb{R}_+ \times \mathcal{H}$. We next study the level sets x = Cte in Lagrangian variables. Let us show first that they are non-degenerate, in that $\nabla x \neq 0$.

In the first case, we assume that (X_0, Y_0) is such that $u_{0Y}(X_0, Y_0) \neq 0$. We then claim that $\nabla x(t, X_0, Y_0) \neq 0$ for any t > 0, as obtained from the following diagram that we explain below.



Indeed, the Crocco transformation $(X, Y) \mapsto (X, u_0(X, Y))$ is in this case a well defined local diffeomorphism near (X_0, Y_0) . The vector field $(x, u) \mapsto (u, -p_x^E(t, x))$ in the ODE (1.7) is divergence free in the (x, u) phase space. Hence, the mapping $(x, u) \mapsto (x(t), u(t))$ is volume preserving in the (x, u) phase space, hence a diffeomorphism. By composition, $(X, Y) \mapsto (x(t, X, Y), u(t, X, Y))$ is a local diffeomorphism near (X_0, Y_0) implying that $\nabla x(t, X_0, Y_0) \neq 0$.

In the second case, we assume that $u_{0Y}(X_0, Y_0) = 0$ or $Y_0 = 0$. The couple (x, u) solves (1.7), so that, in particular,

$$\partial_t(\partial_X x) = \partial_X u$$
, implying $\partial_{tt}(\partial_X x) = \partial_X(-p_X^E(t,x)) = -(\partial_X x)p_{XX}^E(t,x)$.

This shows that at each fixed (X, Y), as long as $\partial_X x$ does not vanish,

$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial_t \partial_X x}{\partial_X x} \right) = -\left(\frac{\partial_t \partial_X x}{\partial_X x} \right)^2 - p_{xx}^E(t, x), \quad \frac{\partial_t \partial_X x}{\partial_X x}(0) = \partial_X u_0.$$

At the point (X_0, Y_0) , the quantity $\partial_t \partial_X x / \partial_X x$ is precisely the third component of the ODE system (1.8). Because of the definition of T (1.9), the solution to the above differential equation is well defined for t < T. Hence $\partial_t \log(\partial_X x)$ is well-defined for t < T, implying $\partial_X x(t, X_0, Y_0) > 0$ after integration. Hence, $\nabla x(t, X_0, Y_0) \neq 0$ for t < T in this second case as well.

We just showed that $\nabla x \neq 0$ everywhere on $\mathbb{R}_+ \times \mathbb{R}$, as long as t < T. Hence, in Lagrangian variables, the level sets x = Cte are non-degenerate. At the boundary, as showed in the second case above: $\partial_X x_{|Y=0} \neq 0$. Therefore, the upper half plane is foliated by curves corresponding to the level sets $\Gamma[t, x] = \{(X, Y) \text{ such that } x(t, X, Y) = x\}$. Since u_0, u^E, p_x^E are C^2 , solving the ODE (1.7) produces a solution map that is also of class C^2 , and x(t, X, Y) is a C^2 function. Hence the curves $\Gamma[t, x]$ are C^2 . We then define an arclength parametrisation s for each of these curves, $\Gamma[t, x] = \{\gamma[t, x](s), s \geq 0\}$ where s = 0 corresponds to the

point at the boundary Y = 0. Denoting by $X^E \mapsto x^E$ the Lagrangian to Eulerian map of the Bernouilli equation (1.2) (with $\dot{x}^E = u^E(t, x^E)$ and $x^E(0, X^E) = X^E$) then there holds $\gamma[t, x](s) \to X^E(t, x)$ as $s \to \infty$.

We now apply (i) in Lemma A.1. Since $x = \phi_1[t]$ is non-degenerate in that $\nabla \phi_1[t] \neq 0$, and that γ is an arclength parametrisation its level curves, then the second component of the characteristics $y = \phi_2[t]$ is such that $\phi_2[t] = 0$ at the boundary and $\phi[t] = (\phi_1[t], \phi_2[t])$ is volume preserving if and only if

$$y(t, X, Y) = \phi_2[t](X, Y) = \int_0^{s[t, x](X, Y)} \frac{d\tilde{s}}{|\nabla \phi_1[t](\gamma[t, x](\tilde{s}))|}.$$
 (2.2)

Note that before T, the denominator in the above integral is uniformly away from 0. The function y above is of class C^1 because y, s and $\nabla \phi_1$ are. The mapping $(t, X, Y) \mapsto (t, x, y)$ is thus a C^1 diffeomorphism from $[0, T) \times \mathcal{H}$ onto itself. We finally define the solution as u(t, x, y) = u(t, X, Y) where the right hand side is the solution to (1.7) (abusing notations). Clearly,

$$\frac{\partial x}{\partial t \mid X \mid Y} = u_0(X, Y) = u(t, x, y).$$

Since the mapping $(X, Y) \mapsto (x, y)$ is C^1 and preserves the measure, $\partial_x \frac{\partial x}{\partial t}|_{X,Y} + \partial_y \frac{\partial y}{\partial t}|_{X,Y} = 0$, yielding

$$\frac{\partial y}{\partial t}_{|X,Y} = -\int_0^y \partial_x u(t,x,\tilde{y}) d\tilde{y}.$$

Since $\partial_t u(t, x(t), y(t)) = -p_x^E(x(t))$ and u is C^1 , one deduces that u solves the inviscid Prandtl equations. Note that the matching condition at infinity in (1.1) are indeed satisfied for the following reason. Initially as $y \to \infty$, $u_0 \to u_0^E$. u^E solves the Bernouilli equation (1.2) that has a global solution, and whose characteristics correspond to the tangential displacement (1.7) of the characteristics for u. This gives the desired compatibility.

Step 2 *Regularity*. Assume $u_0 \in C^k$. The formula (2.1) for x(t, X, Y) defines a C^k function since x is obtained as the solution of the ODE (1.7) with a C^k vector field. In the formula (2.2), $\nabla \phi_1[t]$ is C^{k-1} , and s and γ come from the parametrisation of the level sets of a C^k function, hence are also C^k . Therefore, u is of class C^{k-1} . The continuity of the flow follows from similar arguments.

Step 3 *Uniqueness*. If u is a C^2 solution then uniqueness is straightforward as the characteristics are well defined and have to produce the diffeomorphism constructed above from the uniqueness property (i) in Lemma A.1. In the case where $u \in C^1$ only, let us detail how the normal component of the characteristics and the volume preservation can be obtained. Define the characteristics (x(t), y(t)) through

$$\frac{\partial x}{\partial t} = u(t, x, y), \quad x(0) = X, \quad \frac{\partial y}{\partial t} = -\int_0^{y(t)} u_x(t, x, y), \quad y(0) = Y.$$

One can indeed solve the second equation because the function $\int_0^y u_x(t, x, y)$ is C^1 in the third variable. One obtains characteristics (x, y) such that x is C^1 in

(X,Y) and y is only C^1 in t and continuous in the other variables. u then solves $\dot{u}=-p_x^E(x)$ along the characteristics, implying that x is given by the formula (2.1). Moreover, since x is a C^1 function, and y is a C^1 function in t, with $\partial_t y$ being C^1 in y, such that $\partial_y(\partial_t y(t))=-\partial_x(\partial_t(x(t)))$, an approximation argument using a regularisation procedure gives that the characteristics must preserve volume. The mapping $(X,Y)\mapsto (x,y)$ is then a bijection preserving volume with $x\in C^1$ and y continuous, which can be showed to be necessarily of the form described in Step 1.

Step 4 Blow-up and separation. Assume that $T < \infty$. Then by definition of T one solution to the ODEs (1.8) must blow up at time T, which is only possible if $u_x \to -\infty$ as $t \to T$. If moreover $T = T_a$, then from Step 1, there exists a point $(X_0, Y_0) \in \mathcal{H}$ with $Y_0 > 0$, such that $\nabla x(t, X_0, Y_0) \to 0$ as $t \uparrow T$. Set $(x_s(t), y_s(t)) = (x(t, X_0, Y_0), y(t, X_0, Y_0))$. Then x_s is a regular up to T solution to (1.7) and has a finite limit x_0 as $t \uparrow T$, and $\lim_{t \uparrow T} y_s = \infty$ from (2.2) and the vanishing of ∇x . Hence there is boundary layer separation in the sense of Definition 1.1. \square

3. Construction of Self-Similar Profiles

3.1. The Equation for Self-Similar Profiles

We study self-similar profiles Θ such that $u(t, x, y) = (T - t)^{\alpha - 1} \Theta(x/(T - t)^{\alpha}, y/(T - t)^{\beta})$, for some $\alpha, \beta \in \mathbb{R}$, solves (1.12). Dropping the boundary condition for the normal velocity, this amounts to solving the stationary equation

$$\begin{cases} (1 - \alpha)\Theta + (\alpha \mathcal{X} + \Theta)\partial_{\mathcal{X}}\Theta + (\beta \mathcal{Y} + \Upsilon)\partial_{\mathcal{Y}}\Theta = 0, \\ \partial_{\mathcal{X}}\Theta + \partial_{\mathcal{Y}}\Upsilon = 0. \end{cases}$$
(3.1)

A first method, due to Cassel, Smith and Walker [4] (see also [13]) transforms the nonlinear nonlocal equation (3.1) into a nonlinear local equation (3.3). It relies on the Crocco change of variables $(\mathfrak{X}, \mathcal{Y}) \mapsto (\mathfrak{X}, \Theta)$. We find a new change of variables that transforms (3.1) into the linear and local equation (3.2). This change of variable can be thought of as a volume preserving Crocco transform, and the variables (α, β) should be thought of as Lagrangian self-similar variables as explained in Remark 1.5. We include the proof of (iii) for the sake of completeness.

We use statement (ii) to find explicit solutions to (3.1). While (iii) is not useful to solve (3.1) explicitly, the knowledge of the solution to (3.3), i.e. $\partial_y \Theta$ as a function of $\mathfrak X$ and Θ , is useful for certain computations. We mention that the classification of analytic solutions to (3.1), relying on (3.2), is an interesting open problem.

Lemma 3.1. Let $\alpha, \beta \in \mathbb{R}$, $\alpha \neq 1$, $\Omega \subset \mathcal{H}$ open, $\Theta \in C^3(\Omega)$, $\alpha = -\Theta$ and assume $\Theta \neq 0$ on Ω . Then the following statements are equivalent:

(i) There exists $\Upsilon \in C^1(\Omega)$ such that (Θ, Υ) solves (3.1). One has $\nabla \Theta \neq 0$ on Ω and for each q in the range of Θ the level set $\Gamma_q = \{(\mathfrak{X}, \mathcal{Y}) \in \Omega, \ \Theta(\mathfrak{X}, \mathcal{Y}) = q\}$ is diffeomorphic to \mathbb{R} .

(ii) There exists $\mathfrak{b} \in C^2(\Omega)$ such that the mapping $(\mathfrak{X}, \mathcal{Y}) \mapsto (a, \mathfrak{b})$ is a volume preserving diffeomorphism between Ω and an open set $\Omega' \subset \mathbb{R}^2$, and, writing $\mathfrak{X}(a, b)$ as a function on Ω' , it satisfies

$$(\alpha - 1)a\partial_{\alpha}\mathcal{X} + (1+\beta)b\partial_{\beta}\mathcal{X} = \alpha\mathcal{X} - a. \tag{3.2}$$

One has that for every $\alpha \in \mathbb{R}$, the set $\{ \ell \in \mathbb{R}, (\alpha, \ell) \in \Omega' \}$ is either an interval or empty.

If, moreover, $\partial_{\mathcal{U}}\Theta \neq 0$ on Ω these statements are equivalent to the following one:

(iii) The change of variables $(\mathfrak{X}, \mathcal{Y}) \mapsto (\mathfrak{X}, \Theta)$ maps Ω onto an open set Ω'' . Writing $\tau(\mathfrak{X}, \Theta)$ as a function on Ω'' , that satisfies

$$(\alpha - 1)\Theta \frac{\partial}{\partial \Theta_{|\mathcal{X}}} \tau + (\alpha \mathcal{X} + \Theta) \frac{\partial}{\partial \mathcal{X}_{|\Theta}} \tau = (\alpha - 1 - \beta)\tau. \tag{3.3}$$

One has that for every q in the range of Θ , the set $\{\mathfrak{X} \in \mathbb{R}, (\mathfrak{X}, q) \in \Omega''\}$ is an interval.

Remark 3.2. The hypothesis $\Theta \neq 0$ is not necessary. The implications between (i), (ii), (iii) would hold, provided additional regularity assumptions near the set $\{\Theta = 0\}$, see the proof.

The hypothesis $\nabla\Theta \neq 0$ is necessary for (ii). For a solution to (3.1), there should be a different change of variables $(\mathfrak{X}, \mathcal{Y}) \mapsto (\alpha_{\mathfrak{C}}, \ell_{\mathfrak{C}})$ for each connected component \mathfrak{C} of the set $\{\nabla\Theta \neq 0\}$. For example, for $\overline{\Theta}'$ defined by (1.41), for each component $\mathfrak{C}_n = \{2(n-1)\mathcal{Y}'^*(\mathfrak{X}) < \mathcal{Y} < 2n\mathcal{Y}'^*(\mathfrak{X})\}$, a change of variables for (ii) is given by $(\mathfrak{X}, \mathcal{Y}) \mapsto (\alpha_{\mathfrak{C}_n}, \ell_{\mathfrak{C}_n})$ with $(\alpha_{\mathfrak{C}_n}, \ell_{\mathfrak{C}_n}) = \Phi'^{-1}(\mathfrak{X}, \mathcal{Y} - 2(n-1)\mathcal{Y}'^*(\mathfrak{X}))$, where Φ' is given by (1.36).

The assumption $\partial_{\mathcal{Y}}\Theta \neq 0$ is necessary for (iii). For a solution to (3.1), there should be a different change of variables $(\mathfrak{X},\mathcal{Y})\mapsto (\mathfrak{X},\Theta)$ for each connected component \mathfrak{C} of the set $\{\partial_{\mathcal{Y}}\Theta \neq 0\}$. For Θ given by (1), there is a different change of variables on $\{0<\mathcal{Y}<\mathcal{Y}^*(\mathfrak{X})\}$ and $\{0<\mathcal{Y}<\mathcal{Y}^*(\mathfrak{X})\}$, yielding different solutions to (3.3), see Lemma 3.3.

Proof. Step 1 (i) implies (ii). Assume (i) and let $\mathbf{v} = (\alpha \mathcal{X} + \Theta)\partial_{\mathcal{X}} + (\beta \mathcal{Y} + \Upsilon)\partial_{\mathcal{Y}}$ and write $\mathbf{v} \cdot f = (\alpha \mathcal{X} + \Theta)\partial_{\mathcal{X}} f + (\beta \mathcal{Y} + \mathcal{V})\partial_{\mathcal{Y}} f$ to denote the differentiation along \mathbf{v} on Ω . Then, the second equation in (3.1) implies, with $\nabla_{\mathcal{X},\mathcal{Y}}$. denoting the divergence in $(\mathcal{X},\mathcal{Y})$ variables, that

$$\nabla_{\mathfrak{X},\mathfrak{Y}}.\mathsf{V} = \alpha + \beta. \tag{3.4}$$

Assume first that Ω is connected. As Θ is C^3 with $\nabla\Theta \neq 0$, and given the hypothesis on its level sets, we use one of the formulas provided by Lemma A.1 and get the existence of $\emptyset \in C^2(\Omega)$ such that the mapping $\phi: (\mathfrak{X}, \mathcal{Y}) \mapsto (\alpha, \emptyset)$ is a C^2 volume preserving diffeomorphism onto some open set $\Omega' \subset \mathbb{R}^2$. Let $V' = g(\alpha, \emptyset)\partial_\alpha + h(\alpha, \emptyset)\partial_\delta$ denote the push forward of V from Ω to Ω' , that is, the vector field such that for any $f \in C^1(\Omega')$, $V' \cdot f = V \cdot (f \circ \phi)$.

Since ϕ is C^2 and V is C^1 , one has that V' is C^1 , that is, g and h are C^1 . The first equation in (3.1) gives $V \cdot \Theta = (\alpha - 1)\Theta$, so that $V' \cdot \alpha = (\alpha - 1)\alpha$, and we get

$$g(\alpha, \ell) = (\alpha - 1)\alpha, \tag{3.5}$$

so g is in fact smooth. As ϕ is C^2 and preserves volume, we get conservation of divergence so that: $\nabla_{\alpha,\beta} . V' = \nabla_{\mathfrak{X},\mathcal{Y}} . V = \alpha + \beta$ where we used (3.4). This gives, using (3.5),

$$\partial_{\theta} h = 1 + \beta. \tag{3.6}$$

Consequently, there exists $\varphi(a)$ a C^1 function such that $h(a, \emptyset) = (1+\beta)\emptyset + \varphi(a)$. We change variables and set $\tilde{\ell}(a, \emptyset) = \emptyset + \xi(a)$ for ξ a C^1 function to be determined. Let us denote by V" the pushforward of V' by $(a, \emptyset) \mapsto (a, \tilde{\ell})$, so that

$$\mathbf{V}'' = (\alpha - 1)a\frac{\partial}{\partial a_{|\beta}} + ((1 + \beta)\tilde{b} + (\alpha - 1)a\xi'(a) - (1 + \beta)\xi(a) + \varphi(a))\frac{\partial}{\partial \tilde{b}_{|\alpha}}.$$

Since $\alpha \neq 0$ on Ω' because $\Theta \neq 0$ on Ω , since φ is C^1 and $\alpha \neq 1$, there exists ξ a C^2 solution of $(\alpha - 1)\alpha\xi'(\alpha) - (1 + \beta)\xi(\alpha) + \varphi(\alpha) = 0$, producing $\mathbf{V}'' = (\alpha - 1)\alpha\partial_\alpha + (1 + \beta)\tilde{\delta}\partial_{\tilde{\delta}}$. Note that the change of variables $(\alpha, \ell) \mapsto (\alpha, \ell)$ is C^1 and volume preserving. Therefore, up to relabelling $\tilde{\ell}$ as ℓ , we can always choose ℓ such that

$$h(\alpha, \theta) = (1 + \beta)\theta. \tag{3.7}$$

Hence $V' = (\alpha - 1) \alpha \partial_{\alpha} + (1 + \beta) \theta \partial_{\theta}$ by (3.5) and (3.7). Since $V.\mathfrak{X} = \alpha \mathfrak{X} + \Theta$, we get that $V'.\mathfrak{X} = \alpha \mathfrak{X} - \alpha$, which is shows (3.2). Due to the assumptions on the level sets of Θ , for each α , the set $\{\theta \in \mathbb{R}, (\alpha, \theta) \in \Omega'\}$ is either an interval or empty. Hence (ii) is established.

In case Ω is not connected, we partition it into connected components $\Omega = \bigcup_n \Omega_n$, and denote by $\theta_n \in C^1(\Omega_n)$ the function we just obtained and $\Omega'_n = (\alpha, \theta_n)(\Omega_n)$. From the properties of the level sets of Θ , as $\alpha = -\Theta$, $\Omega'_n \cap \Omega'_{n'} = \emptyset$ whenever $n \neq n'$. Hence, the function $\theta(\mathfrak{X}, \mathfrak{Y}) = \sum_n \delta_{(\mathfrak{X}, \mathfrak{Y}) \in \Omega_n} \theta_n(\mathfrak{X}, \mathfrak{Y})$ and $\Omega' = \bigcup_n \Omega'_n$ give (ii) in that case.

Step 2 (ii) implies (i). Assume (ii) and let $\mathbf{v}' = (\alpha - 1) \cdot \alpha \partial_{\alpha} + (1 + \beta) \cdot \theta \cdot \partial_{\theta}$. Let the pullback of the vector field $\mathbf{v} = i(\mathfrak{X}, \mathcal{Y}) \partial_{\mathfrak{X}} + j(\mathfrak{X}, \mathcal{Y}) \partial_{\mathcal{Y}}$ by the mapping $(\mathfrak{X}, \mathcal{Y}) \mapsto (\alpha, \theta)$ be \mathbf{v}' . Then:

$$i(\mathfrak{X}, \mathfrak{Y}) = \alpha \mathfrak{X} + \Theta. \tag{3.8}$$

because of (3.2). Exploiting as in Step 1 the preservation of divergence by the mapping $(\alpha, \beta) \mapsto (\mathfrak{X}, \mathfrak{Y})$, we get that j is C^1 with $\partial_{\mathfrak{X}} i + \partial_{\mathfrak{Y}} j = \alpha + \beta$. Injecting (3.8) yields $\partial_{\mathfrak{Y}} j = \beta - \partial_{\mathfrak{X}} \Theta$. Hence there exists $\Upsilon \in C^0$ continuously differentiable with respect to \mathfrak{Y} such that

$$j(\mathfrak{X}, \mathcal{Y}) = \beta \mathcal{Y} + \Upsilon(\mathfrak{X}, \mathcal{Y}), \quad \text{with} \quad \partial_{\mathfrak{X}} \Theta + \partial_{\mathcal{Y}} \Upsilon = 0.$$
 (3.9)

The definition of V' gives V'. $\alpha = (\alpha - 1)\alpha$, which, combined with $\alpha = -\Theta$, (3.8) and (3.9) shows that (3.1) is satisfied. As $(\mathfrak{X}, \mathfrak{Y}) \mapsto (\alpha, \mathfrak{b})$ preserves volume and

 $\alpha = -\Theta$, we get $\nabla \alpha \neq 0$ on Ω . For q in the range of Θ , the identity $\{(\mathfrak{X}, \mathfrak{Y}) \in \Omega, \ \Theta(\mathfrak{X}, \mathfrak{Y}) = q\} = (\mathfrak{X}, \mathfrak{Y})(\{(q, \mathfrak{k}) \in \Omega'\})$, and the fact that $\{(q, \mathfrak{k}) \in \Omega'\}$ is a non-empty interval, imply that this set is diffeomorphic to \mathbb{R} . Hence (i) is established.

Step 3 (ii) implies (iii). Assume (ii) and that $\partial_{\mathcal{Y}} \Theta \neq 0$ on Ω . The mapping $(\mathcal{X}, \mathcal{Y}) \mapsto (\alpha, \mathfrak{k})$ is a C^1 volume preserving diffeomorphism, hence the determinant of the Jacobian matrices is either -1 or 1. Up to changing \mathfrak{k} into $-\mathfrak{k}$, we assume that it is 1, so that

$$\begin{pmatrix} \frac{\partial \mathcal{Y}}{\partial \hat{c}} & -\frac{\partial \mathcal{X}}{\partial \hat{c}} \\ -\frac{\partial \mathcal{Y}}{\partial a} & \frac{\partial \mathcal{X}}{\partial a} \end{pmatrix} = \begin{pmatrix} \frac{\partial a}{\partial \mathcal{X}} & \frac{\partial a}{\partial \mathcal{Y}} \\ \frac{\partial c}{\partial \mathcal{X}} & \frac{\partial c}{\partial \mathcal{Y}} \end{pmatrix}. \tag{3.10}$$

In particular, using $\alpha = -\Theta$, we get $\tau = \partial_{\theta} \mathcal{X}$. Plugging this identity in (3.2), then differentiating with respect to θ yields

$$(\alpha - 1)\alpha \partial_{\alpha} \tau + (1 + \beta)\theta \partial_{\beta} \tau = (\alpha - 1 - \beta)\tau. \tag{3.11}$$

The change of variables $(a, b) \mapsto (a, \mathfrak{X})$ produces

$$\frac{\partial}{\partial a_{|\ell|}} \tau = \frac{\partial}{\partial a_{|\mathfrak{A}}} \tau + \frac{\partial}{\partial a_{|\mathfrak{A}}} \mathfrak{X} \frac{\partial}{\partial \mathfrak{X}|_{\mathfrak{A}}} \tau, \qquad \frac{\partial}{\partial \ell|_{\mathfrak{A}}} \tau = \frac{\partial}{\partial \ell} \mathfrak{X} \frac{\partial}{\partial \mathfrak{X}|_{\mathfrak{A}}} \tau.$$

Injecting the above identities in (3.11) gives

$$(\alpha-1)a\frac{\partial}{\partial a_{|\mathcal{X}}}\tau + \left((\alpha-1)a\frac{\partial}{\partial a_{|\mathcal{S}}}\mathfrak{X} + (1+\beta)\theta\frac{\partial}{\partial \theta_{|a}}\mathfrak{X}\right)\frac{\partial}{\partial \mathfrak{X}_{|a}}\tau = (\alpha-1-\beta)\tau.$$

Above, $(\alpha-1)\alpha\frac{\partial}{\partial\alpha}{}_{|\beta}\mathcal{X}+(1+\beta)\theta\frac{\partial}{\partial\theta}{}_{|\alpha}\mathcal{X}=\alpha\mathcal{X}-\alpha$ from (3.2), which proves (3.3) since $\alpha=-\Theta$. Since the statement (i) is satisfied from Step 2, for each q in the range of Θ , the set $\{(\mathcal{X},\mathcal{Y})\in\Omega,\ \Theta(\mathcal{X},\mathcal{Y})=q\}$ is diffeomorphic to \mathbb{R} . This set being diffeomorphic to $\{(\mathcal{X},q)\in\Omega''\}$, this latter set is diffeomorphic to \mathbb{R} , and (iii) is established.

Step 4 (iii) implies (ii). Assume (iii) and $\partial_{\mathcal{Y}}\Theta \neq 0$ on Ω . For q in the range of Θ , the set $\{(\mathcal{X},\mathcal{Y}) \in \Omega, \ \Theta(\mathcal{X},\mathcal{Y}) = q\}$ is diffeomorphic to the nonempty open interval $\{\mathcal{X} \in \mathbb{R}, \ (\mathcal{X},q) \in \Omega''\}$, hence is diffeomorphic to \mathbb{R} . As in the beginning of Step 1, there then exists a function $\mathcal{E} \in C^2(\Omega)$ be such that $(\mathcal{X},\mathcal{Y}) \mapsto (\alpha,\mathcal{E})$ is volume preserving, with determinant 1. Change variables $(\mathcal{X},\Theta) \mapsto (\alpha,\mathcal{E})$. Then, as $\alpha = -\Theta$, using (3.10) and the definition of τ (recall $\tau \neq 0$), we get

$$\begin{split} \frac{\partial}{\partial \Theta}_{|\mathcal{X}} &= \frac{\partial \alpha}{\partial \Theta}_{|\mathcal{X}} \frac{\partial}{\partial \alpha}_{|\ell} + \frac{\partial \ell}{\partial \Theta}_{|\mathcal{X}} \frac{\partial}{\partial \ell}_{|\alpha} = -\frac{\partial}{\partial \alpha}_{|\ell} + \frac{\partial \ell}{\partial \mathcal{Y}}_{|\mathcal{X}} \frac{\partial \mathcal{Y}}{\partial \Theta}_{|\mathcal{X}} \frac{\partial}{\partial \ell}_{|\alpha} \\ &= -\partial_{\alpha} + \frac{\partial_{\alpha} \mathcal{X}}{\tau} \partial_{\ell}, \\ \frac{\partial}{\partial \mathcal{X}}_{|\Theta} &= \frac{\partial \alpha}{\partial \mathcal{X}}_{|\Theta} \frac{\partial}{\partial \alpha}_{|\ell} + \frac{\partial \ell}{\partial \mathcal{X}}_{|\Theta} \frac{\partial}{\partial \ell}_{|\alpha} = \frac{\partial \ell}{\partial \mathcal{X}}_{|\alpha} \frac{\partial}{\partial \ell}_{|\alpha} = \frac{1}{\frac{\partial \mathcal{X}}{\partial \ell}}_{|\alpha} \frac{\partial}{\partial \ell}_{|\alpha} = \frac{1}{\tau} \partial_{\ell}, \end{split}$$

where in the last terms, and from now on, partial derivatives are taking in (α, β) coordinates. Injecting these identities in (3.3), using that $\tau = \partial_{\theta} \mathcal{X}$ we get

$$(\alpha - 1)a \partial_{\alpha \ell} \mathfrak{X} + \left((1 - \alpha)a \frac{\partial_{\alpha} \mathfrak{X}}{\partial_{\ell} \mathfrak{X}} - \frac{\alpha \mathfrak{X} + a}{\partial_{\ell} \mathfrak{X}} \right) \partial_{\ell \ell} \mathfrak{X} = (\beta + 1 - \alpha)\partial_{\ell} \mathfrak{X}.$$

Dividing by $\partial_{\theta} \mathfrak{X}$, the above identity yields

$$\partial_{\theta} \left((\alpha - 1) \alpha \frac{\partial_{\alpha} \mathfrak{X}}{\partial_{\theta} \mathfrak{X}} + \frac{\alpha \mathfrak{X} + \alpha}{\partial_{\theta} \mathfrak{X}} \right) = \beta + 1.$$

Thus, there exists a C^1 function $\varphi(\alpha)$ such that

$$(\alpha - 1) a \partial_{\alpha} \mathfrak{X} + \alpha \mathfrak{X} + a = (\beta + 1 + \varphi(\alpha)) \partial_{\beta} \mathfrak{X}.$$

There exists a C^1 change of variables of the form $\tilde{\ell} = \ell + \xi(\alpha)$ that transforms the above equation into (3.2), by applying verbatim the same reasoning made in Step 1. For every $\alpha \in \mathbb{R}$, the set $\{\ell \in \mathbb{R}, (\alpha, \ell) \in \Omega'\}$ is diffeomorphic to $\{\mathfrak{X} \in \mathbb{R}, (\mathfrak{X}, q) \in \Omega''\}$, hence is either empty or an interval. We have established (ii). \square

3.2. Generic Self-Similar Profile

It is convenient to decompose the proof of Proposition 1 in two parts. The first part is a Lagrangian approach, using formula (1.21) and certain transformations on the Lagrangian side; some properties are directly showed out of this formula. First we study the curve $\mathfrak{X}\mapsto \mathcal{Y}^*(\mathfrak{X})$ and prove (i). This shows Θ is well-defined, and allows to prove that it is a self-similar profile, which is (ii). The symmetry (iii), the set $\{\partial_{\mathcal{Y}}\Theta=0\}$ and the Taylor expansion (1.23) in (iv) can be studied directly from the formula (1.21). Note that although this profile diverges to infinity as $\mathcal{Y}\to 0$ or $2\mathcal{Y}^*(\mathfrak{X})$, it still makes sense to speak of (1.22) as a solution of Prandtl's equations on its support: we show that the quantity $\int_0^y u_X(t,x,\tilde{y})d\tilde{y}$ is well defined.

To establish (v) however, we rely on different techniques. The second part presents another approach for the study of self-similar profiles. It is an Eulerian one since it relies on the study of the equation (3.3), following [4,13]. The study of (3.3) can indeed complement that of (3.2).

We shall use at many locations that Ψ_1 is the inverse of the function $\mathfrak{X} \mapsto -\mathfrak{X} - \mathfrak{X}^3$ (i.e. $-\Psi_1(\mathfrak{X}) - \Psi_1^3(\mathfrak{X}) = \mathfrak{X}$), that it is analytic and odd, that $\partial_{\mathfrak{X}} \Psi_1$ attains its minimum at 0 where $\partial_{\mathfrak{X}} \Psi_1(0) = -1$ and that

$$u + p^{*2}u^3 = v$$
 \Leftrightarrow $u = -\frac{1}{p^*}\Psi_1\left(p^*v\right)$ for all $(u, v) \in \mathbb{R}^2$, (3.12)

$$\Psi_1(\mathfrak{X}) = -\mathfrak{X} + \mathfrak{X}^3 + O(|\mathfrak{X}^5|) \quad \text{as } \mathfrak{X} \to 0, \tag{3.13}$$

$$\Psi_1(\mathfrak{X}) = \mp |\mathfrak{X}|^{\frac{1}{3}} \pm \frac{1}{3} |\mathfrak{X}|^{-\frac{1}{3}} + O(\mathfrak{X}^{-1}) \quad \text{as } \mathfrak{X} \to \pm \infty.$$
 (3.14)

We will write $\Phi = (\Phi_1, \Phi_2)$ for the components of Φ .

Proof of (i) in Proposition 1. These identities are obtained through direct computations. First, the identity (3.12) implies after a direct computation that the determinant of the differential of Φ is 1. It is thus a volume preserving diffeomorphism onto its image.

Fixing any $\mathfrak{X} \in \mathbb{R}$ and parametrising the curve of equation $\Phi_1(\alpha, \beta) = \alpha + \beta^2 + p^{*2}\alpha^3 = \mathfrak{X}$ with the variable β , we get that $\Phi_2 = \int_{-\infty}^{\beta} (1 + 3\Psi_1^2(p(\mathfrak{X} - \tilde{\theta}^2)))^{-1}d\tilde{\theta}$ on this curve from (1.18). Recalling (1.18), the set $\{\Phi_2(\alpha, \beta), \Phi_1 = \mathfrak{X}\}$ is then equal to the interval $(0 < \mathcal{Y} < 2\mathcal{Y}^*(\mathfrak{X}))$. Therefore, the image of Φ is indeed the set $\{(\mathfrak{X}, \mathcal{Y}), 0 < \mathcal{Y} < 2\mathcal{Y}^*(\mathfrak{X})\}$.

We next establish (1.19). After two successive changes of variable $\Psi_1(p^*(\mathfrak{X} - \tilde{\ell}^2))/p^* = \Theta$ and $\Theta = z + \Psi_1(p^*\mathfrak{X})/p^*$, and using (3.12), we can rewrite (1.18) as

$$\mathcal{Y}^{*}(\mathfrak{X}) = \int_{\frac{\Psi_{1}(p^{*}\mathfrak{X})}{p^{*}}}^{\infty} \frac{d\Theta}{2\sqrt{\Theta + p^{*2}\Theta^{3} + \mathfrak{X}}}$$

$$= \int_{0}^{\infty} \frac{dz}{2\sqrt{z}\sqrt{1 + p^{*2}z^{2} + 3zp^{*}\Psi_{1}(p^{*}\mathfrak{X}) + 3\Psi_{1}^{2}(p^{*}\mathfrak{X})}}. \quad (3.15)$$

We compute that $\mathcal{Y}^*(0) = \frac{1}{2} \int_0^\infty (z + p^{*2}z^3)^{-1/2} dz = 4\Gamma(\frac{5}{4})^2 (\pi p^*)^{-\frac{1}{2}} = \frac{3\pi}{8}$ for the specific value $p = p^*$ given by (1.16). Other direct computations using (3.15) then give

$$\begin{split} \partial_{\mathcal{X}}\mathcal{Y}^*(0) &= \sqrt{p^*} \frac{3}{4} \int_0^\infty \frac{\sqrt{z} \, \mathrm{d}z}{(1+z^2)^{\frac{3}{2}}} = \frac{3\sqrt{p^*}}{4\sqrt{\pi}} \Gamma\left(\frac{3}{4}\right)^2 = 1, \\ \partial_{\mathcal{X}}^2 \mathcal{Y}^*(0) &= -\frac{3}{2} p^{*\frac{3}{2}} \int_0^\infty \frac{\mathrm{d}z}{\sqrt{z}(1+z^2)^{\frac{3}{2}}} + \frac{27}{8} p^{*\frac{3}{2}} \int_0^\infty \frac{z^{\frac{3}{2}} \, \mathrm{d}z}{(1+z^2)^{\frac{5}{2}}} = -\frac{5\Gamma\left(\frac{1}{4}\right)}{72\pi^5}, \end{split}$$

which concludes the proof of (1.19). We finish by proving (1.20). If $\mathfrak{X} > 0$, we change variables in (3.15), setting $z = -\tilde{z}\Psi_1(p^*\mathfrak{X})/p^*$ (note that $\Psi_1(p^*\mathfrak{X}) < 0$ in this case) so that

$$\mathcal{Y}^{*}(\mathcal{X}) = \frac{1}{2\sqrt{p^{*}}|\Psi_{1}(p^{*}\mathcal{X})|^{\frac{1}{2}}} \int_{0}^{\infty} \frac{\mathrm{d}\tilde{z}}{\sqrt{\tilde{z}}\sqrt{3 + \Psi_{1}^{-2}(p^{*}\mathcal{X}) - 3\tilde{z} + \tilde{z}^{2}}}.$$
 (3.16)

We use the asymptotic behaviour (3.14) of Ψ_1 to deduce that

$$\mathcal{Y}^*(\mathcal{X}) = C_+ \mathcal{X}^{-\frac{1}{6}} + O\left(\mathcal{X}^{-\frac{5}{6}}\right) = C_+ \mathcal{X}^{-\frac{1}{6}} + O\left(\mathcal{X}^{-\frac{5}{6}}\right) \text{ as } \mathcal{X} \to \infty \quad (3.17)$$

where $C_+=2^{-1}p^{*-2/3}\int_{-1}^{\infty}(z^3+1)^{-1/2}\,\mathrm{d}z$. The same computation in the case $\mathfrak{X}\to-\infty$ gives

$$\mathcal{Y}^*(\mathfrak{X}) = C_- |\mathfrak{X}|^{-\frac{1}{6}} + O\left(|\mathfrak{X}|^{-\frac{5}{6}}\right) \text{ as } \mathfrak{X} \to -\infty, \tag{3.18}$$

where $C_- = 2^{-1} p^{*-2/3} \int_1^\infty (z^3 - 1)^{-1/2} dz$. The constants C_{\pm} can be computed explicitly as

$$C_{+} = \frac{3\left(\frac{3}{2}\right)^{\frac{1}{3}}\pi^{\frac{5}{2}}\Gamma\left(\frac{1}{3}\right)}{4\Gamma\left(\frac{1}{4}\right)^{\frac{8}{3}}\Gamma\left(\frac{5}{6}\right)}, \quad C_{-} = \frac{3\left(\frac{3}{2}\right)^{\frac{1}{3}}\pi^{\frac{5}{2}}\Gamma\left(\frac{7}{6}\right)}{2\Gamma\left(\frac{1}{4}\right)^{\frac{8}{3}}\Gamma\left(\frac{2}{3}\right)}.$$
 (3.19)

This ends the proof of (1.20). \Box

Proof of (ii) in Proposition 1. This is a consequence of (ii) in Lemma 3.1. Indeed, \mathfrak{X} given by (1.17) solves (3.2) with $\alpha=3/2$ and $\beta=-1/4$ by a direct computation. Moreover, we have already proved (i) in Proposition 1, so that the mapping $(\mathfrak{X},\mathcal{Y})\mapsto (a,b)$ is volume preserving. Applying Lemma 3.1, we get that, on the set $\{(\mathfrak{X},\mathcal{Y}),\Theta(\mathfrak{X},\mathcal{Y})\neq 0\}$, there exists Υ such that (Θ,Υ) solves (3.1). Moreover, from Step 1 in the proof of Lemma 3.1, we have that $\frac{1}{2}a\partial_a+\frac{3}{4}b\partial_b$ is the pushforward of $(\frac{3}{2}\mathfrak{X}+\Theta)\partial_{\mathfrak{X}}+(-\frac{1}{4}\mathcal{Y}+\Upsilon)\partial_{\mathcal{Y}}$ by the mapping $(\mathfrak{X},\mathcal{Y})\mapsto (a,b)$. Applying these vector fields to \mathcal{Y} gives the equality

$$-\frac{1}{4}\mathcal{Y} + \Upsilon = \frac{1}{2}\alpha\partial_{\alpha}\mathcal{Y} + \frac{3}{4}\theta\partial_{\theta}\mathcal{Y}. \tag{3.20}$$

Therefore, Υ is analytic since all other terms above are, and (3.1) is in fact satisfied everywhere on the set $\{0 < \mathcal{Y} < 2\mathcal{Y}^*(\mathfrak{X})\}$. Let us show $\Upsilon = -\partial_y^{-1}\partial_{\mathfrak{X}}\Theta$. First, we show that the right hand side is well-defined. Recall $\partial_{\mathfrak{X}}\Theta = -\partial_{\theta}\mathcal{Y}$ from (3.10). Differentiating (1.17), using (3.12), gives

$$\partial_{\alpha} \mathcal{Y} = -6p^{*}(1+3p^{*2}\alpha^{2}) \int_{-\infty}^{\theta} g(p^{*}(\mathfrak{X}-\tilde{\theta}^{2}))d\tilde{\theta},$$

$$\partial_{\theta} \mathcal{Y} = \frac{1}{1+3p^{*2}\alpha^{2}} - 12p^{*}\theta \int_{-\infty}^{\theta} g(p^{*}(\mathfrak{X}-\tilde{\theta}^{2}))d\tilde{\theta},$$
(3.21)

where $g(z)=(\frac{\Psi_1\Psi_1'}{(1+3\Psi_1^2)^2})(z)$. Fix $\mathfrak{X}\in\mathbb{R}$ and let $\mathcal{Y}\to 0$. The constraint $a+p^{*2}a^3+b^2=\mathfrak{X}$ and (1.17) imply that $a,b\to -\infty$ with $|a|^3\approx b^2$. Using the bounds $g(z)=O(z^{-5/3})$ as $z\to \infty$ from (3.14), we get from (3.21) that $|a\partial_a\mathcal{Y}|+|b\partial_b\mathcal{Y}|\to 0$ and $\partial_{\mathfrak{X}}\Theta=\partial_b\mathcal{Y}\to 0$ as $\mathcal{Y}\to 0$. Thus $\partial_{\mathcal{Y}}^{-1}\partial_{\mathfrak{X}}\Theta$ is well defined, and injecting this in (3.20) gives $\Upsilon(\mathfrak{X},\mathcal{Y})\to 0$ as $\mathcal{Y}\to 0$. Since $\partial_{\mathcal{Y}}\Upsilon=-\partial_{\mathfrak{X}}\Theta$, we obtain

$$\Upsilon = \partial_{\mathcal{Y}}^{-1} \partial_{\mathfrak{X}} \Theta.$$

The fact that (Θ, Υ) solves (3.1) with Υ given as above implies that $(T-t)^{1/2}\Theta(x/(T-t)^{3/2}, y/(T-t)^{-1/4})$ solves (1.12), and (ii) in Proposition 1 is proved. \Box

Proof of (iii) and (iv) in Proposition 1. Step 1 *Symmetry.* From (1.17) and (1.18) we have the following symmetries: that $\Phi_1(a, -\theta) = \Phi_1(a, \theta)$ and that $\Phi_2(a, \theta) - \mathcal{Y}^*(\Phi_1(a, \theta)) = \mathcal{Y}^*(\Phi_1(a, \theta)) - \Phi_2(a, -\theta)$. This implies that $\Phi^{-1}(\mathfrak{X}, \mathcal{Y}^*(\mathfrak{X}) + \mathcal{Y}) = (\Phi_1^{-1}(\mathfrak{X}, \mathcal{Y}^*(\mathfrak{X}) - \mathcal{Y}), -\Phi_2^{-1}(\mathfrak{X}, \mathcal{Y}^*(\mathfrak{X}) - \mathcal{Y}))$. This implies in particular (iii).

Step 2 The set of zero vorticity. Since the mapping $(\alpha, \beta) \mapsto (\mathfrak{X}, \mathcal{Y})$ is volume preserving, (3.10) gives $\partial_{\theta} \mathfrak{X} = \partial_{\mathcal{Y}} \Theta$. Since $\partial_{\theta} \mathfrak{X} = 2\theta$ from (1.17), the zero set of $\partial_{\mathcal{Y}} \Theta$ is $\{\theta = 0\}$ or equivalently $\{\mathcal{Y} = \mathcal{Y}^*\}$. On this set, $\mathfrak{X} = \alpha + p^{*2}\alpha^3$, so that $\Theta = -\alpha = \Psi_1(p^*\mathfrak{X})/p^*$ applying (3.12).

Step 3 Taylor expansion. This is a direct consequence of the Taylor expansion of the fonction Φ at (0,0). Let us write $\Theta_{ij}=\partial_{\mathfrak{X}}^{i}\partial_{\mathcal{Y}}^{j}\Theta(0,\mathcal{Y}^{*}(0))$. We first look at the set $\{\mathfrak{X}=0=\alpha+\ell^2+p^{*2}\alpha^3\}$, or equivalently $\alpha=\Psi_1(p^*\ell^2)/p^*$ from (3.12). One has, from the Taylor expansion (3.13) of Ψ_1

$$\mathcal{Y} = \int_{-\infty}^{\ell} \frac{\mathrm{d}\tilde{\ell}}{1 + 3\Psi_1^2 \left(p^*\tilde{\ell}^2\right)} = \mathcal{Y}^*(0) + \ell + O(|\ell|^5),$$

so that $\ell(0, \mathcal{Y}^*(0) + \mathcal{Y}) = \mathcal{Y} + O(|\mathcal{Y}|^5)$ as $\mathcal{Y} \to 0$. As $\alpha = \Psi_1(p^*\ell^2)/p^* = -\ell^2 + O(\ell^6)$ from (3.13), and $\alpha = -\Theta$, one deduces the information on the vertical derivatives of Θ :

$$\Theta(0, \mathcal{Y}^*(0)) = 0, \ \Theta_{01} = 0, \ \Theta_{02} = 2, \ \Theta_{03} = 0.$$
 (3.22)

Let us secondly look at the set $\{\emptyset = 0\}$, corresponding to $\{\mathcal{Y} = \mathcal{Y}^*(\mathfrak{X})\}$. Recall that there holds $\partial_{\mathcal{Y}}\Theta(\mathfrak{X},\mathcal{Y}^*(\mathfrak{X})) = 0$ from Step 2. Differentiating with respect to \mathfrak{X} once and twice this identity, setting $\mathfrak{X} = 0$, using the Taylor expansion (1.19) of \mathcal{Y}^* and (3.22) gives

$$\Theta_{11} = -2, \ \Theta_{21} + 2c_2 + 2\Theta_{12} = 0.$$
 (3.23)

Still on the set $\theta = 0$, one has $\Theta = -p^*\Psi_1(\mathfrak{X})/p^*$. We differentiate once, twice and three times this identity with respect to \mathfrak{X} , and set $\mathfrak{X} = 0$. Using (3.13), (3.22), (3.23) and (1.19) this gives

$$\Theta_{10} = -1$$
, $\Theta_{20} = 2$, $\Theta_{30} + 3\Theta_{21} + 3\Theta_{12} = 6p^{*2}$.

We need one last information. We take the identity $\partial_{\mathfrak{X}}a=\partial_{\theta}\mathcal{Y}$ from (3.10). Consider the set $\{\mathfrak{X}=a+b^2+p^{*2}a^3=0\}$. Then on this set, from (1.17), since $\Psi_1(0)=0$ and $\Psi_1'=-1/(1+3\Psi_1^2)$,

$$\begin{split} \frac{\partial \mathcal{Y}}{\partial \hat{u}} &= \frac{1}{1+3p^{*2}a^2} - \hat{u} \int_{-\infty}^{\hat{u}} \frac{12p^*\Psi_1(p^*\tilde{u}^2)}{(1+3\Psi_1^2(p^*\tilde{u}^2))^3} d\tilde{u} \\ &= 1 + O(\hat{u}^4) - \hat{u} \int_{-\infty}^{0} \frac{12p^*\Psi_1(p^*\tilde{u}^2)}{(1+3\Psi_1^2(p^*\tilde{u}^2))^3} d\tilde{u} + O(\hat{u}^3) \\ &= 1 - \hat{u} \sqrt{p^*} \int_{0}^{\infty} \frac{1}{\left(\sqrt{\frac{x}{3}} + \sqrt{\frac{x}{3}}^3\right)^{\frac{1}{2}} (1+x)^2} d\tilde{u} + O(\hat{u}^3), \end{split}$$

where we changed variables $x = 3p\Psi_1(p\tilde{\ell}^2)$. Hence as $\ell(0, \mathcal{Y}^*(0) + \mathcal{Y}) = \mathcal{Y} + O(|\mathcal{Y}|^5)$ on this set, $\partial_{\mathcal{X}}\Theta(0, \mathcal{Y}^*(0) + \mathcal{Y}) = -1 + C\mathcal{Y} + O(|\mathcal{Y}|^3)$. This implies $\Theta_{12} = 0$, and we obtain the desired Taylor expansion (1.23) for Θ using the previous information. \square

To finish the proof of Proposition 1, there remains to prove item (v). We first establish that Θ solves a *local* ODE in the Lemma below. This was, before our discovery of formula (1.21), the way the existence and some properties of the profile Θ had been showed.

Lemma 3.3. [4,13] Θ defined by (1.21) solves:

$$\begin{cases}
\frac{\partial \Theta}{\partial \mathcal{Y}} = -2\sqrt{\mathfrak{X} + \Theta + p^{*2}\Theta^{3}}, & \text{for } 0 < \mathcal{Y} \leq \mathcal{Y}^{*}(\mathfrak{X}), \\
\frac{\partial \Theta}{\partial \mathcal{Y}} = 2\sqrt{\mathfrak{X} + \Theta + p^{*2}\Theta^{3}}, & \text{for } \mathcal{Y}^{*} \leq \mathcal{Y} < 2\mathcal{Y}^{*}(\mathfrak{X}).
\end{cases} (3.24)$$

Proof of Lemma 3.3. From (3.10) we have that $\partial_y \Theta = \partial_{\ell} \mathcal{X}$. From (1.17), $\partial_{\ell} \mathcal{X} = 2\ell$ and $\ell^2 = \mathcal{X} - \alpha - p^{*2} \alpha^3$. Since $\alpha = -\Theta$, this gives

$$(\partial_{\mathcal{Y}}\Theta)^2 = 4(\mathcal{X} + \Theta + p^{*2}\Theta^3).$$

Since $\partial_{\mathcal{Y}}\Theta=2\mathcal{B}$, we get $\partial_{\mathcal{Y}}\Theta\geq0$ for $\mathcal{B}\geq0$, and $\partial_{\mathcal{Y}}\Theta\leq0$ for $\mathcal{B}\leq0$. As $\mathcal{B}\geq0$ and $\mathcal{B}\leq0$ correspond respectively to $\mathcal{Y}^*(\mathfrak{X})<2\mathcal{Y}^*$ and $0<\mathcal{Y}<\mathcal{Y}^*(\mathfrak{X})$ from (1.17) and (1.18), we obtain (3.24) from the above equation and these sign considerations.

Proof of (v) in Proposition 1. Step 1 *Proof of* (1.24) *and* (1.25) Let $\mathfrak{X} \in \mathbb{R}$ be fixed. Using the ODE's (3.24), we express \mathcal{Y} as a function of Θ and expand, for $\Theta \gg \langle \mathfrak{X} \rangle^{1/3}$,

$$\mathcal{Y} = \int_{\Theta}^{\infty} \frac{d\tilde{\Theta}}{2\sqrt{\mathfrak{X} + \tilde{\Theta} + p^{*2}\tilde{\Theta}^{3}}} = \int_{\Theta}^{\infty} d\tilde{\Theta} \left(\frac{1}{2p^{*}\tilde{\Theta}^{\frac{3}{2}}} + O\left(\frac{|\mathfrak{X}|}{\tilde{\Theta}^{\frac{9}{2}}} + \frac{1}{\tilde{\Theta}^{\frac{7}{2}}}\right) \right)$$
$$= \frac{1}{p^{*2}\Theta^{\frac{1}{2}}} + O\left(\frac{|\mathfrak{X}|}{\Theta^{\frac{7}{2}}} + \frac{1}{\Theta^{\frac{5}{2}}}\right). \tag{3.25}$$

After inversion this gives

$$\Theta = -\frac{1}{p^{*2}\mathcal{Y}^2} + O\left(|\mathfrak{X}|\mathcal{Y}^4 + |\mathcal{Y}|^2\right),\,$$

which is exactly (1.24). Note that we have only established it for $\Theta \gg \langle \mathfrak{X} \rangle^{1/3}$, which from the above expansion, corresponds to $\mathcal{Y} \ll \langle \mathfrak{X} \rangle^{-1/6}$. The validity of the O() in the whole region $\{\mathcal{Y} \leq \mathcal{Y}^*(\mathfrak{X})\}$ is a consequence of step 2 below. Note finally that (1.25) is obtained from (1.24) using the symmetry (iii) in Proposition 1. **Step 2** *Proof of* (1.26). We only prove the expansion in the case $\mathfrak{X} \to -\infty$, as the other case can be handled with similar ideas. Let $\psi_-:[p^{*-2/3},\infty)$ be the following function:

$$\psi_{-}(z) = \frac{1}{2} \int_{z}^{\infty} \frac{\mathrm{d}z}{\sqrt{-1 + p^{*2}z^{3}}}.$$

By definition (3.19) of C_- , the range of ψ_- is $(0, C_-]$. Denote by $\psi_-^{-1}: (0, C_-] \to [p^{*-2/3}, \infty)$ its inverse, and define φ_- to be its extension on $(0, 2C_-)$ by even symmetry about C_- , so that

$$\varphi_{-}(\tilde{\mathcal{Y}}) := \begin{cases} \psi^{-1}(\mathcal{Y}) \text{ if } 0 < \tilde{\mathcal{Y}} \leq C_{-}, \\ \psi^{-1}(2C_{-} - \tilde{\mathcal{Y}}) \text{ if } C_{-} \leq \tilde{\mathcal{Y}} < 2C_{-}. \end{cases}$$

The properties of φ_{-} listed in (v) of Proposition 1 are verified by a direct check. It remains to prove the convergence. For this we use the first equality in (3.25). Let first $0 < \mathcal{Y} \leq \mathcal{Y}^{*}(\mathfrak{X})$. Then,

$$\mathcal{Y}(\Theta) = \frac{1}{2} \int_{\Theta}^{\infty} \frac{\mathrm{d}\tilde{\Theta}}{\sqrt{\mathfrak{X} + \tilde{\Theta} + p^{*2}\tilde{\Theta}^{3}}}.$$

We change variables and set $\tilde{\Theta} = zp^{*-1/3}\Psi_1(p^*\mathfrak{X})$, and use $\mathfrak{X} = -\Psi_1(p^*\mathfrak{X})/p^* - \Psi_1^3(p^*\mathfrak{X})/p^*$, so that after some rewriting,

$$\begin{split} \frac{\Psi_{1}^{\frac{1}{2}}(p^{*}\mathfrak{X})}{p^{*\frac{1}{6}}}\mathcal{Y}(\Theta) &= \frac{1}{2} \int_{\frac{p^{*1/3}\Theta}{\Psi_{1}(p^{*}\mathfrak{X})}}^{\infty} \frac{\mathrm{d}z}{\sqrt{-1+p^{*2}z^{3}}} \\ & \left(1 + \frac{1}{z^{2}p^{*\frac{4}{3}} + zp^{*\frac{2}{3}} + 1} \Psi_{1}^{-2}(p^{*}\mathfrak{X})\right)^{-\frac{1}{2}} \\ &= \psi_{-} \left(\frac{p^{*\frac{1}{3}}\Theta}{\Psi_{1}(p^{*}\mathfrak{X})}\right) - \frac{1}{2} \int_{\frac{p^{*1/3}\Theta}{\Psi_{1}(p^{*}\mathfrak{X})}}^{\infty} \frac{\mathrm{d}z}{\sqrt{-1+p^{*2}z^{3}}} \\ & \left(1 - \left(1 + \frac{1}{z^{2}p^{*\frac{4}{3}} + zp^{*\frac{2}{3}} + 1} \Psi_{1}^{-2}(p^{*}\mathfrak{X})\right)^{-\frac{1}{2}}\right) \\ &= \psi_{-} \left(\frac{p^{*\frac{1}{3}}\Theta}{\Psi_{1}(p^{*}\mathfrak{X})}\right) + O\left(|\mathfrak{X}|^{-\frac{2}{3}} \left(\frac{\Theta}{\Psi_{1}(p^{*}\mathfrak{X})}\right)^{-\frac{5}{2}}\right), \end{split}$$

where we used (3.14) and that $\Theta \ge \Psi_1(p^*\mathfrak{X})/p^*$ for all $\mathcal{Y} < \mathcal{Y}^*(\mathfrak{X})$. Given that uniformly on $[p^{*-2/3},\infty)$ one has $|\psi'_-| \approx (z-p^{*-2/3})^{-1/2}z^{-1}$, we can invert the above equation for all Θ such that $\frac{p^{*1/3}\Theta}{\Psi_1(p^*\mathfrak{X})} - p^{*-2/3} \gg |\mathfrak{X}|^{-4/3}$, with

$$\frac{p^{*\frac{1}{3}}\Theta}{\Psi_{1}(p^{*}\mathfrak{X})} = \psi^{-1}\left(\frac{\Psi_{1}^{\frac{1}{2}}(p^{*}\mathfrak{X})}{p^{*\frac{1}{6}}}\mathcal{Y}(\Theta)\right) + O\left(|\mathfrak{X}|^{-\frac{2}{3}}\left(\frac{\Theta}{\Psi_{1}(p^{*}\mathfrak{X})}\right)^{-1}\right)$$

which, given that $\psi_-^{-1}(\tilde{\Theta}) \approx \tilde{\Theta}^{-2}$ uniformly on $(0, C_-]$, and that $\Psi_1(\mathfrak{X}) = |\mathfrak{X}|^{1/3} + O(|\mathfrak{X}|^{-1/3})$ finally gives

$$\begin{split} \Theta &= p^{*\frac{1}{3}} \Psi_{1}(p^{*} \mathfrak{X}) \psi^{-1} \left(\frac{\Psi_{1}^{\frac{1}{2}}(p^{*} \mathfrak{X})}{p^{\frac{1}{6}}} \mathcal{Y} \right) + p^{*\frac{1}{3}} \Psi_{1}(p^{*} \mathfrak{X}) O\left(|\mathfrak{X}|^{-\frac{1}{3}} |\mathcal{Y}|^{2} \right) \\ &= |\mathfrak{X}|^{\frac{1}{3}} \varphi_{-} \left(|\mathfrak{X}|^{\frac{1}{3}} \mathcal{Y} \right) + O\left(|\mathfrak{X}|^{-\frac{2}{3}} \mathcal{Y}^{-2} \right), \end{split}$$

where we used the fact that $|\mathcal{Y}| \lesssim |\mathcal{X}|^{-1/6}$ as $\mathcal{X} \to -\infty$ and $\mathcal{Y} \subseteq \mathcal{Y}^*$. For $\mathcal{Y}^* < \mathcal{Y} \subseteq (2 - \epsilon)\mathcal{Y}^*$ we write

$$\mathcal{Y} = \mathcal{Y}^* + \frac{p^{*\frac{1}{6}}}{\Psi_1^{\frac{1}{2}}(p^*\mathfrak{X})} \frac{1}{2} \int_{\frac{\Psi_1(p^*\mathfrak{X})}{p^*}}^{\Theta} \frac{\mathrm{d}\tilde{\Theta}}{\sqrt{\mathfrak{X} + \tilde{\Theta} + p^{*2}\tilde{\Theta}^3}},$$

so that changing variables with $\tilde{\Theta} = zp^{*-1/3}\Psi_1(p^*\mathfrak{X})$ as previously,

$$\frac{\Psi_{1}^{\frac{1}{2}}(p^{*}\mathfrak{X})}{p^{*\frac{1}{6}}}\mathcal{Y} = \frac{\Psi_{1}^{\frac{1}{2}}(p^{*}\mathfrak{X})}{p^{*\frac{1}{6}}}\mathcal{Y}^{*} + \frac{1}{2} \int_{1}^{\frac{p^{*1/3}\Theta}{\Psi_{1}(p^{*}\mathfrak{X})}} \frac{dz}{\sqrt{-1 + p^{*2}z^{3}}}
\left(1 + \frac{1}{z^{2}p^{*\frac{4}{3}} + zp^{*\frac{2}{3}} + 1} \Psi_{1}^{-2}(p^{*}\mathfrak{X})\right)^{-\frac{1}{2}}
= C_{-} + \frac{1}{2} \int_{1}^{\frac{p^{*1/3}\Theta}{\Psi_{1}(p^{*}\mathfrak{X})}} \frac{dz}{\sqrt{-1 + p^{*2}z^{3}}} + O\left(|\mathfrak{X}|^{-\frac{2}{3}}\right).$$

As we are restricting to the range $\mathcal{Y}^* < \mathcal{Y} \leq (2 - \epsilon)\mathcal{Y}^*$ the above equation, using the asymptotic behaviour of φ_- , gives

$$\Theta = \frac{\Psi_1(p\mathfrak{X})}{p^{\frac{1}{3}}} \varphi_- \left(\frac{\Psi_1^{\frac{1}{2}}(p\mathfrak{X})}{p^{\frac{1}{6}}} \mathcal{Y} \right) + O\left(|\mathfrak{X}|^{-1}\Theta^2\right)$$
$$= |\mathfrak{X}|^{\frac{1}{3}} \varphi_- \left(|\mathfrak{X}|^{\frac{1}{6}} \mathcal{Y}\right) + O\left(\frac{\mathfrak{X}^{-1}}{(2\mathcal{Y}^*(\mathfrak{X}) - \mathcal{Y})^4}\right).$$

This shows the desired asymptotic behaviour (v) in Proposition 1 at $-\infty$. The behaviour at ∞ can be proved along similar lines. \square

3.3. Degenerate Self-Similar Profile

In this subsection, we prove Proposition 2. In order to simplify notations, we drop the prime 'notation for Φ' , Θ' and $\mathcal{Y}^{'*}$ and simply write Φ , Θ and \mathcal{Y}^{*} instead.

We construct an odd in \mathfrak{X} self-similar profile that is the two dimensional version of the profile found for the full viscous Prandtl system in [6] on the transversal axis. Again, we proceed in two parts. In the first part, we use a Lagrangian approach, and the explicit formula (1.39) to study the curve \mathcal{Y}^* , the symmetries of Θ , and the set of zero vorticity, and to prove it defines a self-similar profile.

In the second part, we perform an Eulerian study of the self-similar equation. Namely, we solve (3.3). This allows us to prove the analyticity at the boundary of Θ , and to study the derivatives on the axis. This shows how the two studies of (3.2) and (3.3) can complement one another.

Proof of (i) in Proposition 2. The fact that Φ preserves volume is a direct computation from the formula (1.36). Its analyticity and that of \mathcal{Y}^* are direct consequences of the analyticity of Ψ_1 . By fixing $\mathfrak{X} \in \mathbb{R}$, and so fixing the relation $\alpha + \alpha^3 + \ell^2 \alpha/4 = \mathfrak{X}$, the vertical component of the image is

$$\mathcal{Y}(\alpha, \mathfrak{E}) = 2 \int_{-\infty}^{\frac{\delta}{2}} \left(1 + \tilde{\mathfrak{E}}^2 \right)^{-1} \left(1 + 3 \Psi_{\mathrm{I}}^2 \left(\frac{\mathfrak{X}}{(1 + \tilde{\mathfrak{E}}^2)^{3/2}} \right) \right)^{-1} d\tilde{\mathfrak{E}}.$$

Hence, using the formula (1.37), the set $\{\Phi(\alpha, \ell), \Phi_1 = \mathfrak{X}\}$ consists of the interval $(0 < \mathcal{Y} < 2\mathcal{Y}^*(\mathfrak{X}))$ where \mathcal{Y}^* is indeed defined by (1.37). The range of Φ is thus the set $\{0 < \mathcal{Y} < 2\mathcal{Y}^*(\mathfrak{X})\}$.

For $\mathfrak{X}>0$, we change variables twice in (1.37), first with $\Theta=(1+\tilde{\ell}^2)^{1/2}\Psi_1(\mathfrak{X}/(1+\tilde{\ell}^2)^{3/2})$ using (3.12), and then with $\Theta=z\Psi_1(\mathfrak{X})$ to get

$$\begin{split} \mathcal{Y}^*(\mathfrak{X}) &= \int_{\Psi_1(\mathfrak{X})}^0 \frac{\mathrm{d}z}{\sqrt{|\Theta|}\sqrt{\mathfrak{X} + \Theta + \Theta^3}} \\ &= \sqrt{\frac{-\Psi_1(\mathfrak{X})}{\mathfrak{X}}} \int_0^1 \frac{\mathrm{d}z}{\sqrt{z}\sqrt{1 + z\frac{\Psi_1(\mathfrak{X})}{\mathfrak{X}} + z^3\frac{\Psi_1^3(\mathfrak{X})}{\mathfrak{X}}}}. \end{split}$$

The expansion of \mathcal{Y}^* near the origin (1.38) then comes as a direct consequence of (3.13) and of

$$\int_0^1 \frac{\mathrm{d}z}{\sqrt{z}\sqrt{1-z}} = B(\frac{1}{2}, \frac{1}{2}) = \pi, \quad \int_0^1 \frac{\sqrt{z}(1+z)}{\sqrt{1-z}} \, \mathrm{d}z = \frac{7}{8}\pi.$$

We now turn to the expansion at infinity. We write

$$\begin{split} \mathcal{Y}^*(\mathfrak{X}) &= \sqrt{\frac{-\Psi_1(\mathfrak{X})}{\mathfrak{X}}} \int_0^1 \frac{\mathrm{d}z}{\sqrt{z}\sqrt{1 + z\frac{\Psi_1(\mathfrak{X})}{\mathfrak{X}} + z^3\frac{\Psi_1^3(\mathfrak{X})}{\mathfrak{X}}}} \\ &= \sqrt{\frac{-\Psi_1(\mathfrak{X})}{\mathfrak{X}}} \int_0^1 \frac{(1 + g(\mathfrak{X}, z))^{-1/2}}{\sqrt{z}\sqrt{1 - z^3}} \, \mathrm{d}z, \end{split}$$

where, using that $\Psi_1(\mathfrak{X}) + \Psi_1^3(\mathfrak{X}) + \mathfrak{X} = 0$,

$$g(\mathfrak{X},z) = \frac{z\frac{\Psi_1(\mathfrak{X})}{\mathfrak{X}} + z^3 \left(\frac{\Psi_1^3(\mathfrak{X})}{\mathfrak{X}} + 1\right)}{1 - z^3} = \frac{z - z^3}{1 - z^3} \frac{\Psi_1(\mathfrak{X})}{\mathfrak{X}}$$
$$= \frac{z(1+z)}{1+z+z^2} \frac{\Psi_1(\mathfrak{X})}{\mathfrak{X}} = O\left(\mathfrak{X}^{-\frac{2}{3}}\right)$$

uniformly on [0,1] as $\mathfrak{X}\to\infty$ from (3.14). This, the integral value $\int_0^1 \frac{\mathrm{d}z}{\sqrt{z}\sqrt{1-z^3}} = 2\sqrt{\pi}\frac{\Gamma(7/6)}{\Gamma(2/3)}$ and (3.14) then imply (1.20) as $\mathfrak{X}\to\infty$. The same limit holds at $-\infty$ as \mathscr{Y}^* is an even function. \square

Now that Θ is well defined, we can study some properties directly from its formula.

Proof of (iv) and (v) in Proposition 2. Step 1 *Symmetries.* We have the first symmetry that $\Phi_1(\alpha, -b) = \Phi_1(\alpha, \theta)$ and that $\Phi_2(\alpha, \theta) - \mathcal{Y}^*(\Phi_1(\alpha, \theta)) = \mathcal{Y}^*(\Phi_1(\alpha, \theta)) - \Phi_2(\alpha, -b)$, from (1.36) and (1.37). This implies $\Phi^{-1}(\mathfrak{X}, \mathcal{Y}^*(\mathfrak{X}) + \mathcal{Y}) = (\Phi_1^{-1}(\mathfrak{X}, \mathcal{Y}^*(\mathfrak{X}) - \mathcal{Y}), -\Phi_2^{-1}(\mathfrak{X}, \mathcal{Y}^*(\mathfrak{X}) - \mathcal{Y}))$, hence $\Theta(\mathfrak{X}, \mathcal{Y}^* - \mathcal{Y}) = \Theta(\mathfrak{X}, \mathcal{Y}^* + \mathcal{Y})$ for $\mathcal{Y} < \mathcal{Y}^*$.

We have the second symmetry that $\Phi_1(-a, \ell) = -\Phi_1(a, \ell)$ and that $\Phi_2(-a, \ell) = \Phi_2(a, \ell)$. This implies that $\Phi^{-1}(-\mathfrak{X}, \mathfrak{Y}) = (-\Phi_1^{-1}(\mathfrak{X}, \mathfrak{Y}), \Phi_2^{-1}(\mathfrak{X}, \mathfrak{Y}))$, so that Θ is odd in \mathfrak{X} .

Finally, $\Phi_1 = \mathfrak{X}$ is negative on $\{a < 0\}$, positive on $\{a > 0\}$. Hence, on the set $\{0 < \mathcal{Y} < \mathcal{Y}^*(\mathfrak{X})\}$, $\Theta = -a$ is positive for $\mathfrak{X} < 0$ and negative for $\mathfrak{X} > 0$. This concludes the proof of (iv).

Step 2 The set of zero vorticity. We assume the regularity properties of (iii) and the identity (1.43) of (vi) in Proposition 2, which are proved later on in this Subsection. Since $\Theta = 0$ on the set $\{\mathcal{Y} \geq 2\mathcal{Y}^*(\mathfrak{X})\}$, and is C^1 , we deduce that $\partial_{\mathcal{Y}}\Theta = 0$ on $\{\mathcal{Y} \geq 2\mathcal{Y}^*(\mathfrak{X})\}$. Using the symmetry property (iv) proved in Step 1, this shows that $\partial_{\mathcal{Y}}\Theta = 0$ as well at the boundary $\{\mathcal{Y} = 0\}$.

We now restrict ourselves to the set $\{0<\mathcal{Y}<2\mathcal{Y}^*(\mathfrak{X})\}$. Since the mapping $(a, b)\mapsto (\mathfrak{X}, \mathcal{Y})$ is volume preserving, one inverts the Jacobian matrix to find that

$$\begin{pmatrix} \frac{\partial \mathcal{Y}}{\partial \hat{g}} & -\frac{\partial \mathcal{X}}{\partial \hat{g}} \\ -\frac{\partial \mathcal{Y}}{\partial a} & \frac{\partial \mathcal{X}}{\partial a} \end{pmatrix} = \begin{pmatrix} \frac{\partial a}{\partial \mathcal{X}} & \frac{\partial a}{\partial \mathcal{Y}} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial x} \end{pmatrix}. \tag{3.26}$$

One has $\partial_{\theta} \mathfrak{X} = \theta \cdot \alpha/2$ from (1.36), so that $\partial_{\mathcal{Y}} \Theta(\mathfrak{X}, \mathcal{Y}^*(\mathfrak{X})) = -\theta \cdot \alpha/2$. Hence the set where $\partial_{\mathcal{Y}} \Theta$ is zero is equal to $\{\alpha = 0\} \cup \{\theta = 0\}$, which corresponds to $\{\mathfrak{X} = 0\} \cup \{\mathcal{Y} = \mathcal{Y}^*(\mathfrak{X})\}$. On the set $\{\mathcal{Y} = \mathcal{Y}^*(\mathfrak{X})\} = \{\theta = 0\}$, we have $\alpha + \alpha^3 = \mathfrak{X}$ so that $\Theta(\mathfrak{X}, \mathcal{Y}^*(\mathfrak{X})) = -\alpha = \Psi_1(\mathfrak{X})$ using (3.12).

On the line $\{\mathcal{Y}=\mathcal{Y}^*(\mathfrak{X})\}$, as $\Theta(\mathfrak{X},\mathcal{Y}^*(\mathfrak{X}))=\Psi_1(\mathfrak{X})$ and $\partial_{\mathcal{Y}}\Psi_1(\mathfrak{X},\mathcal{Y}^*(\mathfrak{X}))=0$, one gets that $\partial_{\mathfrak{X}}\Theta(\mathfrak{X},\mathcal{Y}^*(\mathfrak{X}))=\partial_{\mathfrak{X}}\Psi_1(\mathfrak{X})$. Hence, as $\partial_{\mathfrak{X}}\Psi_1$ attains its minimum at the origin, the minimum of $\partial_{\mathfrak{X}}\Theta$ on $\{\mathcal{Y}=\mathcal{Y}^*\}$ is attained at $(0,\mathcal{Y}^*(0))=(0,\pi)$. From (1.43), as $\partial_{\mathfrak{X}}\Theta=-\sin^2(\mathcal{Y}/2)\mathbf{1}_{0\leqq\mathcal{Y}\leqq2\pi}$, the minimum on the vertical axis is also attained at $(0,\pi)$.

We now show the Taylor expansion (1.42). We write $\Theta_{ij} = \partial_{\mathfrak{X}}^{i} \partial_{\mathfrak{Y}}^{j} \Theta(0, \pi)$. As Θ is odd in \mathfrak{X} , we obtain that

$$\Theta_{00} = \Theta_{01} = \Theta_{02} = \Theta_{03} = 0, \ \Theta_{20} = \Theta_{21} = 0$$

We proved above that $\partial_{\mathcal{Y}}\Theta(\mathfrak{X},\mathcal{Y}^*(\mathfrak{X}))=0$. Differentiating with respect to \mathfrak{X} this identity, setting $\mathfrak{X}=0$, using the Taylor expansion (1.38) of \mathcal{Y}^* and the coefficients computed above,

$$\Theta_{11} = 0.$$

We differentiate once and three times this identity with respect to \mathcal{X} , and set $\mathcal{X}=0$. Using $\Psi_1(\mathcal{X})=-\mathcal{X}+\mathcal{X}^3+O(|\mathcal{X}|^5)$, the coefficients computed above and the Taylor expansion of \mathcal{Y}^* at 0 (1.38) this gives

$$\Theta_{10} = -1, \ \Theta_{30} = 6.$$

We now set $\alpha = 0$. Then,

$$\mathcal{Y}(0, \ell) = \int_{-\infty}^{\ell} \frac{\mathrm{d}\tilde{\ell}}{1 + \frac{\tilde{\ell}^2}{4}}$$

so that $\partial_{\theta} \mathcal{Y}(0,0) = 1$, $\partial_{\theta\theta} \mathcal{Y}(0,0) = 0$ and $\partial_{\theta\theta\theta} \mathcal{Y}(0) = -\frac{1}{2}$. Inverting this relation one gets $\partial_{\mathcal{Y}} \theta(0,\pi) = 1$, $\partial_{\mathcal{Y}} \mathcal{Y}(0,\pi) = 0$. We now use the relation (3.26) to write

 $\partial_{\mathcal{X}\mathcal{Y}\mathcal{Y}}a(0,\pi) = \partial_{\mathcal{Y}\mathcal{Y}|\mathcal{X}}(\partial_{\theta}\mathcal{Y})(0,0)$, which, injecting all values of the coefficients already found, gives

$$\Theta_{12} = 2$$

and ends the proof of (1.42). This closes the proof of (v).

Proof of (ii) in Proposition 2. This is, as in the previous Subsection, a consequence of (ii) in Lemma 3.1. First, an elementary computation gives that $\mathfrak X$ given by (1.36) solves (3.2) with $\alpha=3/2$ and $\beta=-1/2$. We have already proved that the mapping $(\mathfrak X,\mathcal Y)\mapsto (a,\ell)$ is volume preserving. Applying Lemma 3.1, there exists a function Υ on the set $\{(\mathfrak X,\mathcal Y),\Theta(\mathfrak X,\mathcal Y)\neq 0\}$ such that (Θ,Υ) solves (3.1). Moreover, from Step 1 in the proof of Lemma 3.1, we have that $\frac{1}{2}a\partial_a+\frac{1}{2}\ell\partial_{\ell}$ is the pushforward of $(\frac{3}{2}\mathfrak X+\Theta)\partial_{\mathfrak X}+(-\frac{1}{2}\mathcal Y+\Upsilon)\partial_{\mathcal Y})$ by the mapping $(\mathfrak X,\mathcal Y)\mapsto (a,\ell)$. We apply both vector fields to $\mathcal Y$, and the equality of the results shows

$$-\frac{1}{2}\mathcal{Y} + \Upsilon = \frac{1}{2}a\partial_a\mathcal{Y} + \frac{1}{2}b\partial_b\mathcal{Y}. \tag{3.27}$$

The change of variables $(\alpha, \ell) \mapsto (\mathfrak{X}, \mathcal{Y})$ being analytic, Υ given by the above formula is also analytic. The identity (3.1) is in fact satisfied everywhere on the set $\{0 < \mathcal{Y} < 2\mathcal{Y}^*(\mathfrak{X})\}$. We now show $\Upsilon = -\partial_{\mathcal{Y}}^{-1}\partial_{\mathcal{X}}\Theta$. Recall $\partial_{\mathcal{X}}\Theta = -\partial_{\ell}\mathcal{Y}$ from (3.10). Differentiating (1.36), using (3.12), we have

$$\partial_{a} \mathcal{Y} = -12 \left(1 + 3a^{2} + \frac{\ell^{2}}{4} \right) \int_{-\infty}^{\frac{\ell}{2}} \frac{d\tilde{\ell}}{(1 + \tilde{\ell}^{2})^{\frac{5}{2}}} g \left(\frac{\mathfrak{X}}{(1 + \tilde{\ell}^{2})^{\frac{3}{2}}} \right) d\tilde{\ell}, \quad (3.28)$$

$$\partial_{\ell} \mathcal{Y} = \frac{1}{\left(1 + \frac{\ell^{2}}{4} \right) (1 + 3\Psi_{1}^{2} \left(\frac{\mathfrak{X}}{(1 + \tilde{\ell}^{2}/4)^{3/2}} \right)}$$

$$- 6\ell \cdot a \int_{-\infty}^{\frac{\ell}{2}} \frac{d\tilde{\ell}}{(1 + \tilde{\ell}^{2})^{\frac{5}{2}}} g \left(\frac{\mathfrak{X}}{(1 + \tilde{\ell}^{2})^{\frac{3}{2}}} \right) d\tilde{\ell}, \quad (3.29)$$

where $g(z)=(\frac{\Psi_1\Psi_1'}{(1+3\Psi_1^2)^2})(z)$. We now fix $\mathfrak{X}\in\mathbb{R}$ and let $\mathcal{Y}\to 0$. The constraint $a+a^3+b^2a/4=\mathfrak{X}$ and (1.17) imply that $b\to -\infty$ and $a\to 0$ with $|b|\approx |a|^{-1/2}$. Using that g is bounded, we get from (3.21) that $|a\partial_a\mathcal{Y}|+|b\partial_b\mathcal{Y}|\to 0$ and $\partial_{\mathfrak{X}}\Theta=\partial_b\mathcal{Y}\to 0$ as $\mathcal{Y}\to 0$. Thus $\partial_{\mathcal{Y}}^{-1}\partial_{\mathfrak{X}}\Theta$ is well defined, and injecting this in (3.27) gives $\Upsilon(\mathfrak{X},\mathcal{Y})\to 0$ as $\mathcal{Y}\to 0$. Since $\partial_{\mathcal{Y}}\Upsilon=-\partial_{\mathfrak{X}}\Theta$, we obtain

$$\Upsilon = \partial_{\mathcal{V}}^{-1} \partial_{\mathfrak{X}} \Theta.$$

The fact that (Θ, Υ) solves (3.1) with Υ given as above implies that $(T-t)^{1/2}\Theta(x/(T-t)^{3/2}, y/(T-t)^{-1/2})$ solves (1.12), and (ii) in Proposition 2 is proved. \Box

We can now end the proof of Proposition 2 which we will do by solving equation (3.3).

Lemma 3.4. Continue writing Θ instead of $\tilde{\Theta}$ for the function defined by (1.39), and it satisfies

$$\begin{cases} \partial_{\mathcal{Y}}\Theta = \sqrt{\Theta}\sqrt{-\Theta^{3} - \Theta - \mathfrak{X}} & \text{for } \mathfrak{X} < 0 \text{ and } 0 \leq \mathcal{Y} \leq \mathcal{Y}^{*}(\mathfrak{X}) \\ \partial_{\mathcal{Y}}\Theta = -\sqrt{\Theta}\sqrt{-\Theta^{3} - \Theta - \mathfrak{X}} & \text{for } \mathfrak{X} < 0 \text{ and } \mathcal{Y}^{*}(\mathfrak{X}) \leq \mathcal{Y} \leq 2\mathcal{Y}^{*}(\mathfrak{X}) \\ \partial_{\mathcal{Y}}\Theta = -\sqrt{-\Theta}\sqrt{\Theta^{3} + \Theta + \mathfrak{X}} & \text{for } \mathfrak{X} > 0 \text{ and } 0 \leq \mathcal{Y} \leq \mathcal{Y}^{*}(\mathfrak{X}) \\ \partial_{\mathcal{Y}}\Theta = \sqrt{\Theta}\sqrt{\Theta^{3} + \Theta + \mathfrak{X}} & \text{for } \mathfrak{X} > 0 \text{ and } \mathcal{Y}^{*}(\mathfrak{X}) \leq \mathcal{Y} \leq 2\mathcal{Y}^{*}(\mathfrak{X}). \end{cases}$$
(3.30)

Proof. From (3.10) we have that $\partial_{\mathcal{Y}}\Theta = \partial_{\ell}\mathfrak{X}$. From (1.17), $\partial_{\ell}\mathfrak{X} = \ell \cdot a/2$ and $a^2\ell^2 = 4a(\mathfrak{X} - a - a^3)$. Since $a = -\Theta$ this gives:

$$(\partial_{\mathcal{Y}}\Theta)^2 = -\Theta(\mathfrak{X} - \Theta - \Theta^3).$$

Using $\partial_y \Theta = \theta \cdot \alpha/2$ and $\alpha = -\Theta$, we get the signs of α and $\partial_y \Theta$ via (iv) in Proposition 2 that has already been proved. Combined with the fact that $\theta < 0$ and $\theta > 0$ correspond respectively to $\mathcal{Y}^*(\mathcal{X}) < 2\mathcal{Y}^*$ and $0 < \mathcal{Y} < \mathcal{Y}^*(\mathcal{X})$ from (1.36) and (1.37), we obtain (3.24) by solving the above equation for $\partial_y \Theta$. \square

With the local ODEs (3.30), we can now end the proof of Proposition 2.

Proof of (iii), (vi) and (vii) in Proposition 2. Step 1 *Analyticity at the boundary.* The analyticity of Θ in the interior of its domain could be proved by studying the ODEs (3.30), but note that it is a direct consequence of the formula (1.39), as the diffeomorphism defined by (1.36) is analytic. We now prove the existence of an analytic extension by solving periodic manner in \mathcal{Y} the ODEs (3.30). To do this, we will show that these ODEs can be used to prove the analyticity at the boundary $\{\mathcal{Y}=0\}$ (where the natural extension of Θ is 0).

We will establish that an extension of the mapping $(\mathfrak{X},\sqrt{-\Theta})\mapsto (\mathfrak{X},\mathcal{Y})$ is an analytic diffeomorphism, implying the result by taking the inverse transformation. Without loss of generality we consider the case $\mathfrak{X}>0$. From (3.30) we infer that there is a one-to-one relation between $(\mathfrak{X},\mathcal{Y})$ and $(\mathfrak{X},\Theta(\mathfrak{X},\mathcal{Y}))$ between the sets $\{\mathfrak{X}>0,\ 0\leq\mathcal{Y}\leq\mathcal{Y}^*\}$ and $\{\mathfrak{X}>0,\ \Psi_1(\mathfrak{X})\leq\Theta\leq0\}$ with the formula

$$\mathcal{Y}(\mathcal{X},\Theta(\mathcal{X},\mathcal{Y})) = \int_0^{-\Theta(\mathcal{X},\mathcal{Y})} \frac{\mathrm{d}z}{\sqrt{z}\sqrt{\mathcal{X}-z-z^3}}.$$

We change variables and define $U = \sqrt{-\Theta}$. Then the above formula becomes

$$\mathcal{Y}(\mathfrak{X}, U) = 2 \int_0^U \frac{\mathrm{d}u}{\sqrt{\mathfrak{X} - u^2 - u^6}}.$$

This formula also makes sense for $-\sqrt{-\Psi_1(\mathfrak{X})} \leq U < 0$, since $\mathfrak{X} - u^2 - u^6 > 0$ for $|u| \leq \sqrt{-\Psi_1(\mathfrak{X})}$, and the mapping $(\mathfrak{X}, U) \mapsto (\mathfrak{X}, \mathcal{Y})$ is one-to-one from $\{\mathfrak{X} > 0, \ |U| < \sqrt{-\Psi_1(\mathfrak{X})}\}$ onto $\{\mathfrak{X} > 0, \ |\mathcal{Y}| < \mathcal{Y}^*\}$, such that its restriction to nonnegative \mathcal{Y} satisfies $U(\mathfrak{X}, \mathcal{Y}) = \sqrt{-\Theta(\mathfrak{X}, \mathcal{Y})}$. Let $\mathfrak{X}_0 > 0$. For (\mathfrak{X}, u) close to $(\mathfrak{X}_0, 0)$, the function under the integral sign is analytic

$$\frac{1}{\sqrt{\mathfrak{X}-u^2-u^6}} = \sum_{\alpha \in \mathbb{N}^2} a_{\alpha} (\mathfrak{X} - \mathfrak{X}_0)^{\alpha_1} u^{2\alpha_2},$$

with $a_{(0,0)}=1/\sqrt{\mathfrak{X}_0}>0$ and $a_{(0,1)}=1/(2\mathfrak{X}_0^{3/2})>0$, and hence the integral is also analytic

$$\mathcal{Y}(\mathfrak{X}, U) = 2\sum_{\alpha \in \mathbb{N}^2} \frac{a_{\alpha}}{2\alpha_2 + 1} (\mathfrak{X} - \mathfrak{X}_0)^{\alpha_1} U^{2\alpha_2 + 1}.$$

Therefore, the mapping $(\mathfrak{X}, U) \mapsto (\mathfrak{X}, \mathcal{Y})$ is an analytic diffeomorphism near $(\mathfrak{X}_0, 0)$. Its inverse is then analytic of the form (since odd in \mathcal{Y})

$$U(\mathfrak{X}, \mathcal{Y}) = \sum_{\alpha \in \mathbb{N}^2} b_{\alpha} (\mathfrak{X} - \mathfrak{X}_0)^{\alpha_1} \mathcal{Y}^{1 + 2\alpha_2}$$

Since U coincides with $\sqrt{-\Theta}$ for $Y \ge 0$ this means that Θ is analytic of the form

$$\Theta = -U^2 = \sum_{\alpha \in \mathbb{N}^2} c_{\alpha} (\mathfrak{X} - \mathfrak{X}_0)^{\alpha_1} \mathcal{Y}^{2\alpha_2 + 2}.$$

This proves that $\tilde{\Theta}$, restricted to the set $\{0 \leq \mathcal{Y} \leq 2\tilde{\mathcal{Y}}^*(\mathfrak{X})\}$ is analytic in its interior, and also at the lower boundary $\{\mathcal{Y}=0\}$. The symmetry property (iv) in Proposition 2 implies that this restriction is also analytic at the upper boundary $\{\mathcal{Y}=2\mathcal{Y}^*(\mathfrak{X})\}$. From the ODEs (3.30), this restriction satisfies $\partial_{\mathfrak{X}}\Theta=\partial_{\mathcal{Y}}\Theta=0$ at the upper boundary $\{\mathcal{Y}=2\mathcal{Y}^*(\mathfrak{X})\}$. Hence, extending Θ by 0 on the set $\{\mathcal{Y}\geq 2\mathcal{Y}^*(\mathfrak{X})\}$ maintains the C^1 regularity.

Finally, the other extension (1.41) is, by the above analysis of the ODEs (3.30), analytic on the whole upper half space \mathcal{H} . Since it solves (3.1) with $\alpha = 3/2$ and $\beta = -1/2$ on $\{0 < \mathcal{Y} < 2\mathcal{Y}^*(\mathfrak{X})\}$ it thus solves it on the whole upper half space by uniqueness of analytic expansions, and is therefore also a self-similar profile. This ends the proof of (iii).

Step 2 First derivative on the axis. Let us consider the zone $\mathfrak{X} > 0$ and $0 < \mathcal{Y} < \mathcal{Y}^*$. One has the following convergence result

$$\begin{split} \mathcal{Y}(\mathcal{X},\Theta) &= \int_0^{-\Theta} \frac{\mathrm{d}z}{\sqrt{z}\sqrt{\mathcal{X}-z-z^3}} = \int_0^{-\frac{\Theta}{\mathcal{X}}} \frac{\mathrm{d}u}{\sqrt{u}\sqrt{1-u-\mathcal{X}^2u^2}} \\ &\to \int_0^{-\partial_{\mathcal{X}}\Theta(0,\mathcal{Y})} \frac{\mathrm{d}u}{\sqrt{u}\sqrt{1-u}}, \end{split}$$

as $\mathfrak{X} \to 0$. Hence on the vertical axis \mathcal{Y} and $\partial_{\mathfrak{X}}\Theta(0,\mathcal{Y})$ are linked by

$$\mathcal{Y} = \int_0^{-\partial_{\mathcal{X}}\Theta(0,\mathcal{Y})} \frac{\mathrm{d}u}{\sqrt{u}\sqrt{1-u}} = 2\arcsin\left(\sqrt{-\partial_{\mathcal{X}}\Theta(0,\mathcal{Y})}\right).$$

This proves (vi) upon inverting the arcsin function.

Step 3 Third derivative on the axis Let $\phi(\mathcal{Y}) = -\partial_{\mathfrak{X}}\Theta(0,\mathcal{Y})$ and $\psi(\mathcal{Y}) = \partial_{\mathfrak{X}}^3\Theta(0,\mathcal{Y})$. Since Θ solves (3.1) with $\alpha = 3/2$ and $\beta = -1/4$ and vanishes on the vertical axis $\{\mathfrak{X} = 0\}$, differentiating 3 times yields the following equation for ψ :

$$4(1-\phi)\psi + \left(\partial_{\mathcal{Y}}^{-1}\phi - \frac{1}{2}\mathcal{Y}\right)\partial_{\mathcal{Y}}\psi + 3\partial_{\mathcal{Y}}^{-1}\psi\partial_{\mathcal{Y}}\phi = 0, \quad \psi(0) = 0$$

One computes from the formula of ϕ that

$$0 = 4\psi \left(\frac{1}{2} - \frac{1}{2}\cos(\mathcal{Y} - \pi)\right) + \frac{1}{2}\sin(\mathcal{Y} - \pi)\partial_{\mathcal{Y}}\psi - \frac{3}{2}\partial_{\mathcal{Y}}^{-1}\psi\sin(\mathcal{Y} - \pi)$$

$$\Leftrightarrow 0 = 4\psi\sin^{2}\left(\frac{\mathcal{Y} - \pi}{2}\right) + \frac{1}{2}\sin(\mathcal{Y} - \pi)\partial_{\mathcal{Y}}\psi - \frac{3}{2}\partial_{\mathcal{Y}}^{-1}\psi\sin(\mathcal{Y} - \pi)$$

$$\Leftrightarrow 0 = 4\psi\tan\left(\frac{\mathcal{Y} - \pi}{2}\right) + \partial_{\mathcal{Y}}\psi - 3\partial_{\mathcal{Y}}^{-1}\psi.$$

We change variables and set $\psi(\mathcal{Y}) = \tilde{\psi}((\mathcal{Y} - \pi)/2)$, with $r = (\mathcal{Y} - \pi)/2$. One then has

$$8\tilde{\psi}\tan(r) + \partial_r \tilde{\psi} - 12 \int_{-\frac{\pi}{2}}^{r} \tilde{\psi} = 0.$$
 (3.31)

We finally change again variables by setting

$$\int_{-\frac{\pi}{2}}^{r} \tilde{\psi} = f(r),$$

and f finally solves

$$f'' + 8\tan(r)f' - 12f = 0$$
, $f\left(-\frac{\pi}{2}\right) = f'\left(-\frac{\pi}{2}\right) = 0$. (3.32)

A first solution (forgetting about the boundary conditions) is

$$f_1 = \sin^2 r + \frac{1}{6}.$$

The wronskian $W = f_1' f_2 - f_2' f_1$ between solutions solves

$$W' = -8W\tan(r),$$

and therefore is equal up to renormalisation to

$$W = (\cos(r))^8.$$

From the Wronskian relation we deduce that a second solution is given by

$$f_2(r) = \left(\sin^2(r) + \frac{1}{6}\right) \left(540r + 80\sin(2r) + 3\sin(4r) + \frac{686}{3} \frac{\sin(2r)}{\sin^2(r) + \frac{1}{6}}\right).$$

The set of all solutions satisfying (3.32) with the boundary conditions is spanned by

$$f = \left(\sin^2(r) + \frac{1}{6}\right)U(r),$$

where

$$U(r) := \left(540\left(r + \frac{\pi}{2}\right) + 80\sin(2r) + 3\sin(4r) + \frac{686}{3}\frac{\sin(2r)}{\sin^2(r) + \frac{1}{6}}\right)$$

satisfies

$$\frac{d}{dr}(U) = 96 \frac{\cos^8(r)}{\left(\sin^2(r) + \frac{1}{6}\right)^2},$$

so that the function f and its derivatives up to order 8 vanish at $-\pi/2$. The solution to (3.31) is then $\tilde{\psi}(r) = \frac{d}{dr} f(r)$, hence,

$$\tilde{\psi}(r) = 96 \frac{\cos^8(r)}{\sin^2(r) + \frac{1}{6}} + \sin(2r)$$

$$\left(540 \left(r + \frac{\pi}{2}\right) + 80 \sin(2r) + 3 \sin(4r) + \frac{686 \sin(2r)}{3 \sin^2(r) + \frac{1}{2}}\right).$$

The original solution, using standard trigonometric identities, is then

$$\psi(\mathcal{Y}) = \frac{96\sin^8\left(\frac{\mathcal{Y}}{2}\right)}{\cos^2\left(\frac{\mathcal{Y}}{2}\right) + \frac{1}{6}} - \sin(\mathcal{Y})V(\mathcal{Y}),$$

$$V(\mathcal{Y}) := 270\mathcal{Y} - 80\sin(\mathcal{Y}) + 3\sin(2\mathcal{Y}) - \frac{686\sin(\mathcal{Y})}{3\cos^2\left(\frac{\mathcal{Y}}{2}\right) + \frac{1}{2}}.$$

The strict positivity of ψ comes from the equation. Indeed, assume that $\psi(\mathcal{Y}_0) = 0$ for some $0 < \mathcal{Y}_0 < 2\pi$, and that $\psi > 0$ on $(0, \mathcal{Y}_0)$. Then at \mathcal{Y}_0 it holds that

$$\partial_{\mathcal{Y}}\psi(\mathcal{Y}_0) = 3\int_0^{\mathcal{Y}_0} \psi > 0$$

which is a contradiction. The regularity properties and the limited development come from direct computations, and end the proof of (vi), namely,

$$\begin{split} & \partial_{\mathcal{Y}}^{j} \psi(0) = 0, \quad j = 0, ..., 7, \quad \partial_{\mathcal{Y}}^{8} \psi(0) > 0, \\ & \psi(2\pi) = 0, \quad \partial_{\mathcal{Y}} \psi(2\pi) = -V(2\pi) = -540\pi < 0. \end{split}$$

4. Generic singularity for the characteristics

We describe here a property that the characteristic map has generically at the singularity time. Definition 4.1 below can be found in the analysis of [37,38], but no argument is given to support that it would hold generically. We establish this in Lemma 4.4, and the ideas in its proof are new. In what follows, ∇ is the gradient in Lagrangian (X, Y) variables. We denote by ∇^{\perp} the orthogonal gradient, H the Hessian matrix and v^t the transposition

$$\nabla^{\perp} f = (-\partial_{y} f, \partial_{x} f), \quad H f = \begin{pmatrix} \partial_{xx} f & \partial_{xy} f \\ \partial_{xy} f & \partial_{yy} f \end{pmatrix}, \quad (v_{1}, v_{2})^{t} = (v_{2}, v_{1}).$$

We recall that T and T_b are defined by (1.9), and that x[t] is defined by (1.7).

Definition 4.1. (Generic condition). Let $(p_x^E, u^E) \in \mathcal{F}^4$ and $u_0 \in \mathcal{E}^4$ be such that $T < \infty$ and $T < T_b$. We say that the singularity of the characteristics is generic if the mapping $x[t]: (X, Y) \mapsto x(t, X, Y)$ satisfies the following:

- (i) Uniqueness of the singular point. At time T, there exists a unique point $(X_0, Y_0) \in \mathbb{R} \times (0, \infty)$ such that $\nabla x[T](X_0, Y_0) = 0$. For any $(t, X, Y) \in [0, T] \times \mathcal{H}$ such that $(t, X, Y) \neq (T, X_0, Y_0)$ and $x_Y(t, X, Y) = 0$, it holds that $x_X(t, X, Y) > 0$.
- (ii) Local nondegeneracy of the set of zero vorticity. It holds that

$$x_Y(t, X_0, Y_0) = 0$$
 for all $t \in [0, T],$ (4.1)

$$\nabla x_Y(T, X_0, Y_0) \neq 0. {(4.2)}$$

(iii) Local nondegenerate minimality for x_X on the set of zero vorticity. It holds, where all quantities below are evaluated at (T, X_0, Y_0) , that

$$(\nabla x_Y)^t \nabla^{\perp} x_X = 0, \tag{4.3}$$

$$p_0^2 = (\nabla^{\perp} x_Y)^t \left(H x_X - \frac{(\nabla x_Y)^t \nabla x_X}{|\nabla x_Y|^2} H x_Y \right) \nabla^{\perp} x_Y > 0.$$
 (4.4)

(iv) First order Taylor expansion of u. It holds that

$$u_X(T, X_0, Y_0) < 0$$
, and $u_Y(t, X_0, Y_0) = 0$ for all $t \in [0, T]$. (4.5)

Remark 4.2. In the case of a trivial outer Eulerian flow $p^E = u^E = 0$, since $x = X + tu_0$, the above generic condition can be read on the initial datum u_0 . Thus is equivalent to the fact that at a point (X_0, Y_0) with $Y_0 > 0$ and $u_{0Y} = 0$, the restriction of u_{0X} to the set $\{u_{0Y} = 0\} \cup \{Y = 0\}$ attains a unique negative global minimum, that moreover $\nabla u_{0y}(X_0, Y_0) \neq 0$ so that the set $\{u_{0y} = 0\}$ is locally nondegenerate, and that

$$p^{2} = \frac{p_{0}^{2}}{T^{3}} = (\nabla^{\perp} u_{0Y})^{t} \left(H u_{0X} - \frac{(\nabla u_{0Y})^{t} \nabla u_{0X}}{|\nabla u_{0Y}|^{2}} H u_{0Y} \right) \nabla^{\perp} u_{0Y} > 0,$$

when evaluated at (X_0, Y_0) , so that this minimum is nondegenerate. The quantity p^2 is well defined in Eulerian coordinates, and a computation shows that it satisfies the following identity, when evaluated at the characteristics $(x(t, X_0, Y_0), y(t, X_0, Y_0))$ starting from (X_0, Y_0) :

$$p^2(t) = (\nabla^{\perp} u_y)^t \left(H u_x - \frac{(\nabla u_y)^t \nabla u_x}{|\nabla u_y|^2} H u_y \right) \nabla^{\perp} u_y = \frac{p^2}{\left(1 - \frac{t}{T}\right)^2}.$$

Hence p^2 should be thought of in this case as a conserved quantity that will help determine the parameters (μ, ν) of the asymptotic profile $\Theta_{\mu,\nu,\iota}$.⁵

Certain conditions in the above Definition 4.1 are always met, as the next Lemma shows.

⁵ Up to a fixed self-similar factor $\left(1 - \frac{t}{T}\right)^{-2}$

Lemma 4.3. Let $(p_x^E, u^E) \in \mathcal{F}^4$, $u_0 \in \mathcal{E}^4$ and $(X_0, Y_0) \in \mathcal{H}$ be such that $T < \infty$, $T < T_b$, and $\nabla x(T, X_0, Y_0) = 0$. Then for all $t \in [0, T]$ one has $x_Y(t, X_0, Y_0) = 0$ and $u_Y(t, X_0, Y_0) = 0$, and there holds $u_X(T, X_0, Y_0) < 0$ and $(\nabla x_Y(T, X_0, Y_0))^t \nabla^{\perp} x_X(T, X_0, Y_0) = 0.$

Proof. We define for each $(X, Y) \in \mathcal{H}$ the 2×2 matrices M = M(t, X, Y) and A = A(t, X, Y) by

$$\dot{M} = AM, \ M(0, X, Y) = Id, \ A(t, X, Y) := \begin{pmatrix} 0 & 1 \\ -p_{xx}^{E}(t, x(t, X, Y)) & 0 \end{pmatrix}.$$
 (4.6)

From the above equation (4.6), one obtains that M(t) is of determinant 1 (a consequence of the fact that the ODE (1.7) is volume preserving in the phase space (x, u)), and in particular invertible. From the ODE (1.7), one deduces that at any $(X, Y) \in \mathcal{H}, x_X, x_Y, u_X \text{ and } u_Y \text{ solve:}$

$$\begin{pmatrix} \dot{x}_X \\ u_X \end{pmatrix} = A \begin{pmatrix} x_X \\ u_X \end{pmatrix}, \quad \begin{pmatrix} \dot{x}_Y \\ u_Y \end{pmatrix} = A \begin{pmatrix} x_Y \\ u_Y \end{pmatrix},$$

and therefore that they are given by the formula

$$\begin{pmatrix} x_X(t) \\ u_X(t) \end{pmatrix} = M(t) \begin{pmatrix} 1 \\ u_{0X} \end{pmatrix}, \quad \begin{pmatrix} x_Y(t) \\ u_Y(t) \end{pmatrix} = M(t) \begin{pmatrix} 0 \\ u_{0Y} \end{pmatrix}. \tag{4.7}$$

We recover from this that the set $\{u_Y = 0\}$ is preserved with time t. At (T, X_0, Y_0) we get

$$\begin{pmatrix} 0 \\ u_X(T, X_0, Y_0) \end{pmatrix} = M(T, X_0, Y_0) \begin{pmatrix} 1 \\ u_{0X}(X_0, Y_0) \end{pmatrix},$$

$$\begin{pmatrix} 0 \\ u_Y(T, X_0, Y_0) \end{pmatrix} = M(T, X_0, Y_0) \begin{pmatrix} 0 \\ u_{0Y}(X_0, Y_0) \end{pmatrix},$$

$$(4.8)$$

$$\begin{pmatrix} 0 \\ u_Y(T, X_0, Y_0) \end{pmatrix} = M(T, X_0, Y_0) \begin{pmatrix} 0 \\ u_{0Y}(X_0, Y_0) \end{pmatrix}, \tag{4.9}$$

since $\nabla x(T, X_0, Y_0) = 0$. The first identity implies $u_X(T, X_0, Y_0) \neq 0$ using the invertibility of M. Next, $(1, u_{0X}(X, Y))$ and $(0, u_{0Y}(X_0, Y_0))$ must be collinear since their images by M are collinear and M is invertible. This is only possible if $u_{0Y}(X_0, Y_0) = 0$, and the second identity in (4.7) then implies $x_Y(t, X_0, Y_0) =$ $u_Y(t, X_0, Y_0) = 0$ for all $t \in [0, \infty)$.

We recall that from Step 1 in the proof of Theorem 1, T is characterised as the first time at which x_X touches zero on the set $\{u_{0Y} = 0\}$, which happens away from the boundary as $T < T_b$. Hence $x_X \ge 0$ on $\{u_{0Y} = 0\} \cap \{0 \le t \le T\}$, and so since $x_X(T, X_0, Y_0) = 0$ and $u_{0Y}(X_0, Y_0) = 0$, (T, X_0, Y_0) is a global minimizer of x_X on this set. As $u_Y(t, X_0, Y_0) = 0$ for all $t \in [0, T], \dot{x}_X = u_X$ from (1.7), and $u_X(T, X_0, Y_0) \neq 0$, necessarily $u_X(T, X_0, Y_0) < 0$. Finally, if one of the quantities in the product $(\nabla x_Y(T, X_0, Y_0))^t \nabla^{\perp} x_X(T, X_0, Y_0)$ is zero, then this product is zero. If both are nonzero, since $x_X[T]$ restricted to $\{x_Y[T] = 0\}$ attains a minimum at (X_0, Y_0) then this quantity is zero as well by Fermat's Theorem. This ends the proof of the Lemma.

The terminology of "generic" singularity is due to the next Lemma.

Lemma 4.4. Let $(p_x^E, u^E) \in \mathcal{F}^4$. In the subset of \mathcal{E}^4 of initial data u_0 such that $T < \infty$ and $T < T_b$, there exists a dense open set such that the singularity of the characteristics is generic in the sense of Definition 4.1.

Proof of Lemma 4.4. Fix $u_0 \in \mathcal{C}^4$ such that $T < \infty$ and $T < T_b$ a reference initial datum. Let $(\overline{x}, \overline{u})$ denote the solution to the ODE (1.7) with initial datum $\overline{u}(0, X, Y) = u_0(X, Y)$. For any $\delta > 0$ and $(u_0 + v) \in \mathcal{C}^4$ with $d_{\mathcal{C}^4}(v, 0) \leq \delta$ we let (x, u) denote the solution of (1.7) with initial datum $u(0, X, Y) = (u_0 + v)(X, Y)$. **Step 1** Evolution of the perturbation and of the derivatives. Differentiating (1.7) we find that the solution (x, u) can always be written under the following linearised form

$$\begin{pmatrix} x(t) \\ u(t) \end{pmatrix} = \begin{pmatrix} \overline{x}(t) \\ \overline{u}(t) \end{pmatrix} + M(t) \begin{pmatrix} 0 \\ v \end{pmatrix} + F(t)v^2,$$
 (4.10)

where the volume preserving matrix M is defined by (4.6), and where at a given δ , $F:[0,T]\times\mathcal{H}\to\mathbb{R}^2$ is a function such that $\|F\|_{C^3}\leq C$ is bounded independently of v. As at (T,X_0,Y_0) , M is invertible and sends the vector $(1,u_{0X})$ onto the vector $(0,u_X)$ from (4.8), one has that

$$M\begin{pmatrix} 0\\1 \end{pmatrix} = \begin{pmatrix} m\\n \end{pmatrix} \text{ with } m(T, X_0, Y_0) \neq 0. \tag{4.11}$$

Hence, we can rewrite the first line of the identity (4.10) as

$$x(t) = \overline{x}(t) + mv + fv^2, \tag{4.12}$$

where $m(T, X_0, Y_0) \neq 0$, \overline{x} is C^4 , and m and f are bounded C^3 functions (with C^3 norm independent of v). We end this first step by writing the ODEs for higher order derivatives

$$\begin{pmatrix}
\dot{x}_{YY} \\
u_{YY}
\end{pmatrix} = A \begin{pmatrix} x_{YY} \\
u_{YY}
\end{pmatrix} + \begin{pmatrix} 0 \\
-(x_Y)^2 p_{xxx}^E(x) \end{pmatrix},
\begin{pmatrix}
\dot{x}_{XY} \\
u_{XY}
\end{pmatrix} = A \begin{pmatrix} x_{XY} \\
u_{XY}
\end{pmatrix} + \begin{pmatrix} 0 \\
-x_X x_Y p_{xxx}^E(x) \end{pmatrix}.$$
(4.13)

Step 2 Generic singularities define an open set. We show in this step that if u_0 is such that the properties (i) to (iv) of Definition 4.1 are satisfied, then this is also the case for $u_0 + v$ for δ small enough. We use bars to denote quantities related to the initial datum u_0 , and no bars for those related to $u_0 + v$.

First, we make some computations for the unperturbed solution \overline{u} . At $(\overline{X}_0, \overline{Y}_0)$ one has $\overline{u}_Y = \overline{x}_Y = 0$ for all times $t \in [0, \infty)$ from (4.9). Next, one gets from (4.7) and (4.11) that

$$\overline{x}_{Y}(t, X_{0}, Y_{0}) = \overline{m}(t, X_{0}, Y_{0})u_{0Y}(X_{0}, Y_{0}),$$

and so since $\overline{m}(\overline{T}, \overline{X}_0, \overline{Y}_0) \neq 0$ from (4.11), one gets that the sets $\{\overline{x}_Y = 0\}$ and $\{\overline{u}_{0Y} = 0\}$ coincide locally near $(\overline{T}, \overline{X}_0, \overline{Y}_0)$. Since $\overline{x}_Y(t, \overline{X}_0, \overline{Y}_0) = 0$ for all times and $\nabla \overline{x}_Y(\overline{T}, \overline{X}_0, \overline{Y}_0) \neq 0$ from (4.2), from standard parametrisation methods we have that for t close to T the set $\{\overline{x}_Y(t) = 0\}$ is locally near $(\overline{X}_0, \overline{Y}_0)$ a curve $\overline{\Gamma}$

that can be parametrised as $\overline{\Gamma} = \{(\overline{X}(s), \overline{Y}(s)), |s| < \epsilon\}$ for some small enough ϵ , where (the derivatives being computed at $(t, \overline{X}_0, \overline{Y}_0)$)

$$\begin{split} (\overline{X}(s), \overline{Y}(s)) &= (\overline{X}_0, \overline{Y}_0) + s \nabla \overline{x}_Y^{\perp} + c s^2 \nabla \overline{x}_Y + O(|s|^3), \\ c &= -\frac{1}{2|\nabla \overline{x}_Y|^2} (\nabla \overline{x}_Y^{\perp})^t H \overline{x}_Y \nabla \overline{x}_Y^{\perp}. \end{split}$$

A direct consequence of the above parametrisation is that one has the following Taylor expansion for \overline{x}_X on $\overline{\Gamma}$ for t close to T, after some elementary computations, using that $\overline{x}_X(\overline{T}, \overline{X}_0, \overline{Y}_0) = 0$, $\dot{x}_X = u_X$, the identity (4.3) and the definition of \overline{p}_0 :

$$\overline{x}_X(t, \overline{X}(s), \overline{Y}(s)) = -(\overline{T} - t)\overline{u}_X(\overline{T}, \overline{X}_0, \overline{Y}_0)(1 + O(|\overline{T} - t| + |s|))
+ \frac{1}{2}s^2\overline{p}_0^2(1 + O(|\overline{T} - t|)) + O(|s|^3),
\frac{d^2}{ds^2}\overline{x}_X(t) = \overline{p}_0^2(1 + O(|\overline{T} - t| + |s|)).$$
(4.14)

Here $\overline{p}_0^2 > 0$ is defined by (4.3).

Next, we study the perturbed solution u. First, note that for the unperturbed solution, because of (i), outside any neighbourhood of $(\overline{T}, \overline{X}_0, \overline{Y}_0)$, there exists c > 0 such that $|\nabla \overline{x}| > c$ is uniformly far away from 0. Hence, for δ small enough, it at any time T close to \overline{T} the solution is such that $\nabla x[T] = 0$ somewhere, this has to be at a point near $(\overline{X}_0, \overline{Y}_0)$.

From the condition (4.2) for \overline{u} , for δ small enough, for all t close to \overline{T} , the set $\{x_Y = 0\}$ is near $(\overline{X}_0, \overline{Y}_0)$ a non-empty curve Γ . Since $x_Y(t, X_0, Y_0) = m(t, X_0, Y_0)u_{0Y}(X_0, Y_0)$, and that $\overline{m}(\overline{T}, \overline{X}_0, \overline{Y}_0) \neq 0$, we obtain moreover that for δ small enough and t close to \overline{T} , Γ is independent of time. From (4.14), for δ small enough, there exists on Γ , at time \overline{T} , a unique point (X_0, Y_0) at which x_X is minimal (non necessarily 0). From the nondegeneracy condition (4.2), one obtains that for t close to \overline{T} , the curve Γ can be parametrised by $\Gamma = \{(X(s), Y(s)), |s| < \epsilon'\}$ for some small enough ϵ' , where (the quantities below being computed at (t, X_0, Y_0))

$$(X(s), Y(s)) = (X_0, Y_0) + s \nabla x_Y^{\perp} + c s^2 \nabla x_Y + O(|s|^3),$$

$$c = -\frac{1}{2|\nabla x_Y|^2} (\nabla x_Y^{\perp})^t H x_Y \nabla x_Y^{\perp},$$

A direct consequence of the above parametrisation and of the definition of (X_0, Y_0) is that on Γ , close to (\overline{T}, X_0, Y_0) ,

$$\begin{aligned} x_X(t) &= x_X(\overline{T}, X_0, Y_0) - (\overline{T} - t)\overline{u}_X(\overline{T}, \overline{X}_0, \overline{Y}_0)(1 + O((\overline{T} - t) + |s| + \delta)) \\ &+ \frac{1}{2}s^2\overline{p}_0^2(1 + O((\overline{T} - t) + |s| + \delta)). \end{aligned}$$

As $x_X(\overline{T}, X_0, Y_0) = O(\delta)$ and $\overline{u}_X(\overline{T}, \overline{X}_0, \overline{Y}_0) < 0$, we infer from the above expansion that the first time x_X touches zero on the curve $\{x_Y = 0\}$ is $T = \overline{T} + O(\delta)$, at least at one location $s = O(\delta)$. The condition

$$\frac{\mathrm{d}^2}{\mathrm{d}s^2} x_X(t, X(s), Y(s)) = \overline{p}_0^2 (1 + O(|\overline{T} - t| + |s| + \delta),$$

ensures that this happens at a unique location. Hence (i) is satisfied. The inequality in (ii) is satisfied as at this point $\nabla x_Y = \nabla \overline{x}_Y + O(\delta) \neq 0$. The inequality in (iii) is satisfied as $p_0^2 = \overline{p}_0^2 + O(\delta) > 0$. Finally, all other conditions in Definition 4.1 are satisfied from Lemma 4.3. Hence for δ small enough, the solution u has a singularity of the characteristics that is generic in the sense of Definition 4.1.

Step 3 *Density of generic singularities.* We now assume that u_0 is such that $T < \infty$ and $T < T_b$, but that \overline{u} fails to meet the conditions of Definition 4.1. For any $\delta > 0$, we will find a suitable v with $d_{\mathscr{C}^4}(v,0) \leq \delta$ such that u does satisfy these conditions. As the generic condition involves several requirements, there are several cases to consider. We start with the first case: we assume that for \overline{u} the condition (ii) holds true (the equality is always holds true from Lemma 4.3, so only $\nabla \overline{x}_Y(\overline{T}, \overline{X}_0, \overline{Y}_0) \neq 0$ is real assumption), and that (iv) fails (the first equality always holds from Lemma 4.3 so the real assumption is that $\overline{p}^2 \leq 0$). We do not assume anything regarding (i), and we recall that (iv) is always true from Lemma 4.3.

From $\nabla \overline{x}_Y(\overline{T}, \overline{X}_0, \overline{Y}_0) \neq 0$, as in Step 2 we infer that for all t near T, near $(\overline{X}_0, \overline{Y}_0)$, the set $\{x_Y[t] = 0\}$ is a curve $\overline{\Gamma}$ that we can still parametrise as $\overline{\Gamma} = \{(\overline{X}(s), \overline{Y}(s)), |s| < \kappa\}$ for some small $\kappa > 0$ with

$$(\overline{X}(s), \overline{Y}(s)) = (\overline{X}_0, \overline{Y}_0) + s \nabla \overline{x}_Y^{\perp} + c s^2 \nabla \overline{x}_Y + O(s^3),$$

$$c = -\frac{1}{2|\nabla \overline{x}_Y|^2} (\nabla \overline{x}_Y^{\perp})^t J \overline{x}_{0Y} \nabla \overline{x}_Y^{\perp},$$
(4.15)

but this time,

$$\frac{\mathrm{d}^2}{\mathrm{d}s^2} \left(\overline{x}_X(\overline{T}, \overline{X}(s), \overline{Y}(s)) \right)_{|s=0} = \overline{p}_0^2 = 0. \tag{4.16}$$

This quantity cannot be negative by minimality of \overline{x}_X at $(\overline{X}_0, \overline{Y}_0)$, so indeed $\overline{p}_0^2 = 0$. We assume without loss of generality that the function m defined by (4.11) satisfies $\overline{m}(\overline{T}, \overline{X}_0, \overline{Y}_0) > 0$. We then perturb the initial datum u_0 by

$$v(\overline{X}_0 + X, \overline{Y}_0 + Y) = \epsilon^4 \Psi\left(\frac{K(X - \overline{X}_0)}{\epsilon}\right) \chi\left(\frac{K'(Y - \overline{Y}_0)}{\epsilon}\right),$$

$$0 < \epsilon \ll 1, \quad K \gg K' \gg 1,$$

where

- Ψ is odd in X and compactly supported in [-4, 4].
- $\Psi' \ge 0$ on [-4, -2], $\Psi' \le 0$ on [-2, 0], $\Psi' < 0$ on [-1, 0] with Ψ' attaining its minimum at the origin where $\Psi'(0) = -1$.
- $\Psi''' \ge 1$ on [-1, 0] with $\Psi'''(0) = 1$.
- χ is a standard smooth cutoff function $\chi=1$ on [-1,1] and $\chi=0$ outside [-2,2].

Note that for any value of K and K', v is indeed small in C^3 for ϵ small enough. Note also that as v vanishes for $|X - X_0| \ge 4\epsilon/K$ or $|Y - Y_0| \ge 2\epsilon/K'$ the solution

(x, u) remains unchanged there. In the modification zone, note first that one has the formula from (4.12):

$$x(t, X, Y) = \overline{x}(\overline{T}) - (\overline{T} - t)\overline{u}(T) + m(\overline{T})v + fv^{2} + gv(T - t) + h(T - t)^{2},$$

$$= \overline{x}(\overline{T}, X, Y) - (\overline{T} - t)\overline{u}(T, X, Y) + \overline{m}(\overline{T}, \overline{X}_{0}, \overline{Y}_{0})v$$

$$+v^{2}f_{1} + v(T - t)f_{2} + v(X - X_{0})f_{3}$$

$$+v(Y - Y_{0})f_{4} + (T - t)^{2}f_{5}.$$
(4.17)

Here all the functions f, g, h, f_1 , ..., f_5 are C^3 functions with O(1) size uniformly in δ . Note that for t close to T, the curve $\Gamma := \{x_Y[t] = 0\}$ is unchanged for $|Y - Y_0| \le \epsilon/K'$, hence it is still parametrised by (4.15). It holds on this part of the curve for $t = T + O(K\epsilon^3)$ and $|s| \le \epsilon/K$, writing (X, Y) instead of $(\overline{X}(s), \overline{Y}(s))$ to ease notation, that

$$\begin{split} x_X(t,X,Y) &= \overline{x}_X(\overline{T},X,Y) - (\overline{T}-t)\overline{u}_X(\overline{T},\overline{X}_0,\overline{Y}_0) \left(1 + O(|X-\overline{X}_0| + |Y-\overline{Y}_0|)\right) \\ &+ K\epsilon^3 \Psi' \left(\frac{K(X-\overline{X}_0)}{\epsilon}\right) \chi \left(\frac{K'(Y-\overline{Y}_0)}{\epsilon}\right) \overline{m}(\overline{T},\overline{X}_0,\overline{Y}_0) + O(\epsilon^4) \\ &= O(|s|^3) - (\overline{T}-t)\overline{u}_X(\overline{T},\overline{X}_0,\overline{Y}_0) \left(1 + O(|s|)\right) \\ &+ K\epsilon^3 \Psi' \left(\frac{K(X-\overline{X}_0)}{\epsilon}\right) \chi \left(\frac{K'(Y-\overline{Y}_0)}{\epsilon}\right) \overline{m}(\overline{T},\overline{X}_0,\overline{Y}_0) + O(\epsilon^4) \\ &= -(\overline{T}-t)\overline{u}_X + K\epsilon^3 \Psi' \left(\frac{K(X-\overline{X}_0)}{\epsilon}\right) \chi \left(\frac{K'(Y-\overline{Y}_0)}{\epsilon}\right) \overline{m} + O\left(\frac{\epsilon^3}{K^3}\right), \end{split}$$

where we wrote $\overline{u}_X < 0$ and $\overline{m} > 0$ for $\overline{u}_X(\overline{T}, \overline{X}_0, \overline{Y}_0)$ and $\overline{m}(\overline{T}, \overline{X}_0, \overline{Y}_0)$ to ease notation. We now restrict things further to the zone of this curve for which $|X - \overline{X}_0| \ll \epsilon/K$, hence $\chi = 1$, and we Taylor expand Ψ to get

$$x_X = \left(-1 + \frac{t - \overline{T}}{\epsilon^3 K} \frac{\overline{u}_X}{\overline{m}} + \left(\frac{K(X - \overline{X}_0)}{\epsilon}\right)^2 + O\left(\left|\frac{K(X - \overline{X}_0)}{\epsilon}\right|^3\right) + O\left(K^{-4}\right)\right)$$

$$\epsilon^3 K \overline{m}.$$

The above identity implies that the first time $\partial_X x$ touches 0 in the zone of the curve Γ for which $|X - X_0| \ll \epsilon/K$ is at a spacetime point (T, X_0, Y_0) with

$$T = \overline{T} + \frac{\epsilon^3 K \overline{m}}{\overline{u}_X} + O\left(\epsilon^3 K^{-3}\right) < \overline{T}, \quad X_0 = \overline{X}_0 + O\left(\frac{\epsilon}{K^3}\right).$$

At such a time, on the part of the curve for which $|X - \overline{X}_0| \ge \epsilon/K$ it holds for some c > 0 from the condition on Ψ that

$$\partial_X \widetilde{x}(T) \geqq (T - \overline{T}) \overline{u}_X + \epsilon^3 K \overline{m} (-1 + c) + O\left(\frac{\epsilon^3}{K^3}\right) \geqq c' \epsilon^3 K, \ c' > 0.$$

Hence at time T on $\{u_Y = 0\}$, x_X did not touch zero outside the part of Γ in the zone $|X - X_0| \le \epsilon/K$. From Lemma 4.3, the vectors ∇x_Y and ∇x_X are collinear at (T, X_0, Y_0) . From Step 2, the second derivative of $x_X(T, \overline{X}(s), \overline{Y}(s))$ with respect to s is positively proportional to p^2 computed at this point. The collinearity of ∇x_Y and ∇x_X implies the simplification for p_0 defined by (4.3):

$$\frac{p_0^2}{x_{YY}} = x_{XXX}x_{YY} - 3x_{XXY}x_{XY} + 3x_{XYY}x_{XX} - \frac{x_{XY}^3}{x_{YY}^2}x_{YYY}.$$
 (4.18)

From (4.17) we infer that, introducing the notation $\overline{P} = (\overline{T}, \overline{X}_0, \overline{Y}_0)$,

$$\begin{aligned} x_{XXX} &= \overline{x}_{XXX} + O(|T - \overline{T}|) + \overline{m}K^3 \epsilon \Psi''' \left(\frac{K(X - \overline{X}_0)}{\epsilon}\right) + O(\epsilon^2) \\ &= \overline{x}_{XXX}(\overline{P}) + \overline{m}K^3 \epsilon \Psi''' \left(\frac{K(X - \overline{X}_0)}{\epsilon}\right) + O(\epsilon/K) \\ x_{YY} &= \overline{x}_{YY}(\overline{P}) + O(\frac{\epsilon}{K}), \quad x_{XXY} &= \overline{x}_{XXY}(\overline{P}) + O\left(\frac{\epsilon}{K}\right), \\ x_{YYY} &= \overline{x}_{XXY}(\overline{P}) + O\left(\frac{\epsilon}{K}\right) \\ x_{XY} &= \overline{x}_{XY}(\overline{P}) + O\left(\frac{\epsilon}{K}\right), \quad x_{XYY} &= \overline{x}_{XYY}(\overline{P}) + O\left(\frac{\epsilon}{K}\right), \\ x_{XX} &= \overline{x}_{XX}(\overline{P}) + O\left(\frac{\epsilon}{K}\right). \end{aligned}$$

The condition $\nabla \overline{x}_Y \neq 0$ and the fact that $\nabla^{\perp} \overline{x}_Y . \nabla \overline{x}_X = 0$ ensure $\overline{x}_{YY} \neq 0$, and therefore,

$$p_0^2 = \overline{p}_0^2 + (\overline{x}_{YY})^2 \overline{m} K^3 \epsilon \Psi''' \left(\frac{K(X - \overline{X}_0)}{\epsilon} \right) + O(\epsilon/K)$$
$$= (\overline{x}_{YY})^2 \overline{m} K^3 \epsilon \Psi''' \left(\frac{K(X - \overline{X}_0)}{\epsilon} \right) + O(\epsilon/K) \ge c K^3 \epsilon$$

for some c>0, where we used (4.16). This ensures that the zero we found for x_X on the curve was unique in the part $|X-\overline{X}_0| \le \epsilon/K$, and hence is globally unique, proving (i) in Definition 4.1. The second inequality (4.2) is true as $\nabla x_Y = \nabla \overline{x}_Y + O(\epsilon)$ and since we assumed $\nabla \overline{x}_Y(\overline{T}, \overline{X}_0, \overline{Y}_0) \ne 0$). We proved that $p_0^2 > 0$ above. Using Lemma 4.3 u thus meets the requirements of Definition 4.1.

Step 4 Other cases Step 3 does not cover all cases. One also has to treat the case $\nabla \overline{x}_Y = 0$, for which (ii) fails. The set $\{\overline{x}_Y = 0\}$ is degenerate. As the parameter p depends on third order derivatives, one has to consider three subcases, wether the symmetric Hessian matrix $H\overline{x}_Y(\overline{T}, \overline{X}_0, \overline{Y}_0)$ has eigenvalues with the same sign, different signs, or if it is degenerate. In each of these cases we can perform a similar analysis as in Step 3, so we only explain the strategy and leave the details to the reader.

In the case for which $H\overline{x}_Y(\overline{T}, \overline{X}_0, \overline{Y}_0)$ has two eigenvalues with different signs, the set $\{\overline{x}_Y[\overline{T}] = 0\}$ is locally two crossing curves. Hence as at time \overline{T} , on the set

 $\{\overline{x}_Y = 0\}$, as the quantity $\overline{x}_X(\overline{T})$ has to be minimal at $(\overline{X}_0, \overline{Y}_0)$, one gets that $Hu_X(\overline{T}, \overline{X}_0, \overline{Y}_0)$ must be a nonnegative matrix. We can thus perturb the initial datum to separate the two crossing curves in two non-crossing curves, while making a minimum for \overline{x}_X appear on one of these curves.

In the case for which $H\overline{x}_Y(\overline{T},\overline{X}_0,\overline{Y}_0)$ has two eigenvalues with the same sign, the set $\{\overline{x}_Y[\overline{T}]=0\}$ is locally a point. As $\overline{u}_X(\overline{T},\overline{X}_0,\overline{Y}_0)<0$, by perturbing the initial datum one can transform this point into a circle, which makes us go back to Step 3. In the case of a degenerate matrix $H\overline{x}_Y(\overline{T},\overline{X}_0,\overline{Y}_0)$ with at least a zero eigenvalue, one perturbs the initial data to make these eigenvalues nonzero, which makes us go back to the two previous cases. \square

5. Generic Self-Similar Separation

5.1. Strategy of the Proof and Renormalised Variables

This section is devoted to the proof of Theorem 2. We fix throughout this section $(u^E, p_x^E) \in \mathcal{F}^4$ and $u_0 \in \mathcal{E}^4$ such that the solution u to (1.1) has a singularity of the characteristics that is generic in the sense of Definition 4.1. We recall that this happens for a dense subset of initial data in \mathcal{E}^4 such that $T < \infty$ and $T < T_b$ thanks to Lemma 4.4. We will show that u satisfies the conclusion of Theorem 1. The proof is decomposed in several steps:

- We define below self-similar Lagrangian and Eulerian variables, (a, b) and $(\mathfrak{X}, \mathfrak{Y})$.
- We compute $\mathfrak{X}[t](a, b)$ in Subsection 5.2, and show that $\mathfrak{X}[t](a, b) \approx \Phi_1(a, b)$ (where $\Phi = (\Phi_1, \Phi_2)$ is defined in (1.17)).
- We compute $\mathcal{Y}[t](a, b)$ in Subsection 5.3 using incompressibility, from the formula for \mathfrak{X} and the relation (A.1). We show that $\mathcal{Y}[t](a, b) \approx \Phi_2(a, b)$. The technical difficulty is the parametrisation of the level curves $\{\mathfrak{X} = c\}$, which is done differently in the three zones Z_0^c , Z_1 and Z_2 defined by (5.8), (5.9) and (5.10).
- Theorem 2 is proved in Subsection 5.4 in two parts. In the first one, we invert the characteristics and compute $(a[t](\mathcal{X}, \mathcal{Y}), b[t](\mathcal{X}, \mathcal{Y}))$ and show that $(a, b) \approx \Phi^{-1}(\mathcal{X}, \mathcal{Y})$. The technical difficulty is that one performs this inversion simultaneously at all points in an unbounded zone, and that Φ becomes degenerate at infinity and at the boundary of its support. We introduce several zones, each with an associated renormalisation, so that the error terms are uniformly estimated in each zone. In the second part, the explicit formula for the mapping $(\mathcal{X}, \mathcal{Y}) \mapsto (a, b)$ allows to retrieve u and to end the proof of Theorem 2.

The identity (4.3) implies at (T, X_0, Y_0) that $x_{XY}^2 = x_{XX}x_{YY}$, and (4.4) implies that $x_{XY} \neq 0$. There are thus four cases to consider, depending on the sign of x_{XX}

⁶ The mapping $(\mathfrak{X}, \mathfrak{Y}) \mapsto (a, b)$ will be showed to be close to the mapping $(\mathfrak{X}, \mathfrak{Y}) \mapsto (a, b) = \Phi^{-1}(\mathfrak{X}, \mathfrak{Y})$ given by the inverse of Φ defined in (1.17), hence this (a, b) notation.

(which is the same as that of x_{YY}), and the sign of x_{XY} . We make the hypothesis that

$$x_{XX}(T, X_0, Y_0) > 0$$
 and $x_{XY}(T, X_0, Y_0) < 0.$ (5.1)

It is clear from the proof that the sign of x_{XY} does not matter for the result (i.e. does not change the parameters μ , ν , ι of the profile), and that the case $x_{XX} < 0$ would lead to a singularity with profile $-\Theta(-\mathcal{X}, \mathcal{Y})$, i.e. $\iota = -1$. First, we define centred variables, and for notational convenience,

$$t = T - t > 0$$
, $X = X - X_0$, $Y = Y - Y_0$.

Second, we define self-similar Lagrangian variables (a, b) near (X_0, Y_0) as

$$\begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} k_1 t^{-\frac{1}{2}} & k_2 t^{-\frac{1}{2}} \\ -k_3 t^{-\frac{3}{4}} & k_4 t^{-\frac{3}{4}} \end{pmatrix} \begin{pmatrix} X \\ Y \end{pmatrix},
\begin{pmatrix} X \\ Y \end{pmatrix} = \begin{pmatrix} X_0 \\ Y_0 \end{pmatrix} + \begin{pmatrix} \overline{k}_1 t^{\frac{1}{2}} - \overline{k}_2 t^{\frac{3}{4}} \\ \overline{k}_3 t^{\frac{1}{2}} & \overline{k}_4 t^{\frac{3}{4}} \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix},$$
(5.2)

where the constants are given by (all expressions below being computed at (T, X_0, Y_0) and p_0 being given by (4.4))

$$k_{1} = \frac{1}{\sqrt{-u_{X}}\sqrt{6}(x_{XX} + x_{YY})} \frac{p_{0}}{p^{*}}, \quad k_{2} = \sqrt{\frac{x_{XX}}{x_{YY}}} k_{1}, \quad k_{4} = \sqrt{\frac{1}{2\sqrt{6}(-u_{X})^{\frac{3}{2}}} \frac{p_{0}}{p^{*}}},$$

$$k_{3} = \sqrt{\frac{x_{XX}}{x_{YY}}} k_{4}$$

$$\overline{k}_{1} = x_{YY}\sqrt{6}\sqrt{-u_{X}} \frac{p^{*}}{p_{0}}, \quad \overline{k}_{3} = \sqrt{\frac{x_{XX}}{x_{YY}}} \overline{k}_{1}, \quad \overline{k}_{2} = \frac{\sqrt{2\sqrt{6}(-u_{X})^{\frac{3}{2}}x_{XX}x_{YY}}}{x_{XX} + x_{YY}} \sqrt{\frac{p^{*}}{p_{0}}},$$

$$\overline{k}_{4} = \sqrt{\frac{x_{YY}}{x_{YX}}} \overline{k}_{2}.^{7}$$
(5.3)

The reader should keep in mind that there are the variables (a, b) given by (5.2), and that there are the variables (a, b) of Proposition 1 (that will be showed to be asymptotically equivalent). We denote by $(\mathfrak{X}^{\Theta}, \mathcal{Y}^{\Theta})$ and (a, b) the change of variables related to the unperturbed profile Θ :

$$\begin{aligned} (a, \ell) &\mapsto (\mathfrak{X}^{\Theta}(a, \ell), \mathcal{Y}^{\Theta}(a, \ell)) = \Phi(a, \ell) \text{ is the mapping } \Phi \text{ defined in (1.17)}, \\ (\mathfrak{X}, \mathcal{Y}) &\mapsto (a(\mathfrak{X}, \mathcal{Y}), \ell(\mathfrak{X}, \mathcal{Y})) \text{ is the inverse of the mapping } \Phi \text{ defined in (1.17)}. \end{aligned}$$

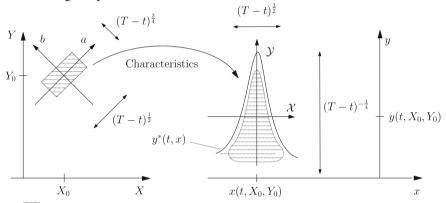
The two line vectors in the above matrices in (5.2) are orthogonal. We renormalise the Eulerian side and use Eulerian self-similar variables $(\mathfrak{X}, \mathfrak{Y})$ according to

$$x^*(t) = x(t, X_0, Y_0), \qquad \mathcal{X} = k_5 \frac{x - x^*(t)}{t^{\frac{3}{2}}}, \qquad \mathcal{Y} = k_6 \frac{y}{t^{-\frac{1}{4}}},$$
 (5.5)

where

$$k_5 = \frac{1}{-u_X \bar{k}_1}, \quad k_6 = \sqrt{\frac{\sqrt{-u_X p_0}}{2\sqrt{6}p^*}},$$

so that the mapping $(a, b) \mapsto (\mathfrak{X}, \mathcal{Y})$ preserves volume. Note that in (5.5) a slight abuse of notation is made, as these are the $(\mathfrak{X}, \mathcal{Y})$ variables of Theorem 2, but up to some fixed renormalisation factors. This is only to simplify notations in the forthcoming analysis.



Core of Lagrangian and Eulerian self-similar zones

Our analysis will prove that the parameters (μ, ν, ι) of Theorem 2 are

$$\mu = -u_X \overline{k}_1, \quad \nu = k_6^{-1}, \quad \iota = 1.8$$
 (5.6)

5.2. Tangential Displacement

We compute here $(a, b) \mapsto \mathfrak{X}(t, a, b)$, with detailed estimates to parametrise the level curves $\{\mathfrak{X} = Cte\}$ in the next Subsection. We describe two zones Z_1 and Z_2 near (X_0, Y_0) , in (a, b) variables, for which the curve $\mathfrak{X} = Cte$ can be parametrised either with the variable b in Z_1 , or the variable a in Z_2 (the Taylor expansion is not precise enough to allow for a single parametrisation). For this purpose, we assume for a small parameter $0 < \delta \ll 1$ that

$$0 < T - t \le \delta^2, \tag{5.7}$$

⁸ We recall that the value $\iota = 1$ has been ensured by the sign assumption (5.1), see the comments there.

(equivalently $0 < t \le \delta^2$) and for a large constant $L \gg 1$ we define

$$Z_0 := \mathcal{H} \setminus \left\{ |a| \le \delta^{\frac{1}{3}} \mathsf{t}^{-\frac{1}{2}} \text{ and } |b| \le \delta \mathsf{t}^{-\frac{3}{4}} \right\},\tag{5.8}$$

$$Z_1 = Z_1[L] := Z_0^c \cap \left\{ |b| \le L \left(1 + |a|^{\frac{3}{2}} \right) \right\},\tag{5.9}$$

$$Z_2 = Z_2[L] := Z_0^c \cap Z_1^c = Z_0^c \cap \left\{ |b| > L\left(1 + |a|^{\frac{3}{2}}\right) \right\}.$$
 (5.10)

The zone Z_0^c defines a size one neighbourhood of (X_0, Y_0) in Lagrangian variables (X, Y), and so Z_0 is an exterior zone where the dynamics remains regular. The following two Lemmas give all estimates we will use later on. The precise value of the constants L above do not matter, we simply will take them large enough to ensure a dichotomy for the level curves $\{x = Cte\}$, see next Lemma 5.3. We introduce

$$r = \frac{\overline{k}_2}{\overline{k}_1}$$

Lemma 5.1. For L large enough, then δ small enough, the following holds true: for $(X, Y) \in Z_0^c$, it holds, with constants in the O()'s depending on L, that

$$\mathcal{X} = a + p^{*2}a^{3}\left(1 + O\left(\mathsf{t} + |a|\mathsf{t}^{\frac{1}{2}}\right)\right) + b^{2}\left(1 + O\left(\mathsf{t} + |b|\mathsf{t}^{\frac{3}{4}} + |a|\mathsf{t}^{\frac{1}{2}}\right)\right) + \mathsf{t}^{\frac{1}{4}}rb + O\left(a^{2}|b|\mathsf{t}^{\frac{1}{4}} + a^{2}\mathsf{t}^{\frac{1}{2}} + |b|\mathsf{t}^{\frac{1}{2} + \frac{3}{4}}\right). \tag{5.11}$$

Moreover, if $(X, Y) \in Z_1$, then it holds that

$$\mathcal{X} = \left(a + p^{*2}a^{3}\right) \left(1 + O\left(\mathsf{t}^{\frac{1}{4}} + |a|^{\frac{1}{2}}\mathsf{t}^{\frac{1}{4}}\right)\right) + b^{2} + O(\mathsf{t}^{\frac{1}{4}}), \tag{5.12}$$

$$a = -\frac{1}{p^{*}}\Psi_{1}\left(p^{*}\left(\mathcal{X} - b^{2}\right)\right) \left(1 + O\left(\mathsf{t}^{\frac{1}{4}} + |\mathcal{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}} + |b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right)\right)$$

$$+ O\left(\mathsf{t}^{\frac{1}{12}}\right). \tag{5.13}$$

Also, if $(X, Y) \in \mathbb{Z}_2$, then it holds that

$$\mathfrak{X} = \left(a + p^{*2}a^3 + b^2\right) \left(1 + O\left(\mathsf{t}^{\frac{1}{4}}|b|^{\frac{1}{3}}\right)\right),\tag{5.14}$$

$$a = -\frac{1}{p^*} \Psi_1 \left(p^* (\mathfrak{X} - b^2) \right) + O\left(|\mathfrak{X}|^{\frac{1}{3} + \frac{1}{18}} \mathsf{t}^{\frac{1}{12}} \right), \tag{5.15}$$

$$b = \pm \sqrt{\mathfrak{X} - a - p^{*2}a^{3}} \left(1 + O\left(|b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right) \right)$$
$$= \pm \sqrt{\mathfrak{X} - a - p^{*2}a^{3}} \left(1 + O\left(|\mathfrak{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}}\right) \right). \tag{5.16}$$

Proof. The proof uses the Taylor expansion of x near (T, X_0, Y_0) and the algebraic identities of Definition 4.1. In what follows, all symbols of functions without arguments denote the evaluation of these functions at the point (T, X_0, Y_0) . From Lemma 4.4, for all t it holds that $x_Y(t, X_0, Y_0) = 0$ and at the point (T, X_0, Y_0)

there holds $x_X = 0$, $x_{Xt} = u_X$, and $x_{XX}x_{YY} = x_{XY}^2$ with the assumption $x_{XX} > 0$ and $x_{XY} < 0$ from (5.1). Thus the Taylor expansion of x at (T, X_0, Y_0) gives

$$x(T - t, X_0 + X, Y_0 + Y) = x^*(t) - u_X t X + \left(\sqrt{\frac{x_{XX}}{2}} X - \sqrt{\frac{x_{YY}}{2}} Y\right)^2 + \frac{x_{XXX}}{6} X^3 + \frac{x_{XXY}}{2} X^2 Y + \frac{x_{XYY}}{2} X Y^2 + \frac{x_{YYY}}{6} Y^3 + O\left(|X|^4 + |Y|^4 + t|X|^2 + t|Y|^2 + t^2|X|\right).$$
(5.17)

We use now the variables (a, b), for $(X, Y) \in Z_0^c$, which means that $|a| \le \delta^{1/3} t^{-1/2} \ll t^{-1/2}$ and $|b| \le \delta t^{-3/4} \ll t^{-3/4}$. From the identities (4.18), (5.2) and (5.3), the above expression becomes

$$x - x^*(t) = (-u_X)\overline{k}_1$$

$$\left(t^{\frac{3}{2}}a + t^{\frac{3}{2}}p^{*2}a^3\left(1 + O\left(t + |a|t^{\frac{1}{2}}\right)\right) + t^{\frac{3}{2}}b^2\left(1 + O\left(t + t^{\frac{3}{4}}|b| + t^{\frac{1}{2}}|a|\right)\right) + t^{\frac{7}{4}}rb + O\left(a^2|b|(1-t)^{\frac{7}{4}} + t^2|a|^2 + t^{2+\frac{3}{4}}|b|\right)\right)$$

which, using (5.5), shows (5.11). Consider now (5.11) in the zone Z_1 where $|b| \le L(1+|a|^{3/2})$. As a and a^3 share the same sign, and since $|a|t^{1/2} \ll 1$ and $|b|t^{3/4} \ll 1$ we can write

$$\begin{split} \mathcal{X} &= \left(a + p^{*2}a^3\right) \left(1 + O\left(\mathsf{t} + |a|\mathsf{t}^{\frac{1}{2}}\right)\right) + b^2 \left(1 + O\left(\mathsf{t}^{\frac{3}{4}} + \mathsf{t}^{\frac{1}{2}}|a|\right)\right) \\ &+ \mathsf{t}^{\frac{1}{4}}rb + O\left(|a|^{3 + \frac{1}{2}}\mathsf{t}^{\frac{1}{4}} + |a|^2\mathsf{t}^{\frac{1}{4}} + \mathsf{t}^{\frac{1}{2} + \frac{3}{4}}|a|^{\frac{3}{2}} + \mathsf{t}^{\frac{1}{2} + \frac{3}{4}}\right) \\ &= \left(a + p^{*2}a^3\right) \left(1 + O\left(\mathsf{t}^{\frac{1}{4}} + |a|^{\frac{1}{2}}\mathsf{t}^{\frac{1}{4}}\right)\right) + b^2 + O(\mathsf{t}^{\frac{1}{4}}), \end{split}$$

where we used $|a|^2 + |a|^{3/2} \lesssim |a + a^3|$. This proves (5.12). We rewrite the above identity as

$$\left(\mathcal{X} - b^2 + O(\mathsf{t}^{\frac{1}{4}})\right) \left(1 + O\left(\mathsf{t}^{\frac{1}{4}} + |a|^{\frac{1}{2}}\mathsf{t}^{\frac{1}{4}}\right)\right) = a + p^{*2}a^3$$

Note that the solution to $a + p^{*2}a^3 = f$ is $a = -\Psi_1(p^*f)/p^*$. Hence

$$a = -\frac{1}{p^*} \Psi_1 \left(p^* \left(\mathcal{X} - b^2 + O(\mathsf{t}^{\frac{1}{4}}) \right) \left(1 + O\left(\mathsf{t}^{\frac{1}{4}} + |a|^{\frac{1}{2}} \mathsf{t}^{\frac{1}{4}} \right) \right) \right)$$

Now, for t close to T_0 , and (X, Y) in Z_0^c , there holds $O\left(\mathsf{t}^{\frac{1}{4}} + |a|^{\frac{1}{2}}\mathsf{t}^{\frac{1}{4}}\right) = o(1)$, hence using (B.1) the above identity gives

$$a = -\frac{1}{p^*} \Psi_1\left(p^*\left(\mathfrak{X} - b^2 + O(\mathfrak{t}^{\frac{1}{4}})\right)\right) \left(1 + O\left(\mathfrak{t}^{\frac{1}{4}} + |a|^{\frac{1}{2}}\mathfrak{t}^{\frac{1}{4}}\right)\right).$$

Hence, from (B.1) $|a| \lesssim |\Psi_1\left(p^*\left(\mathfrak{X}-b^2+O(\mathsf{t}^{\frac{1}{4}})\right)\right)| \lesssim |\mathfrak{X}|^{1/3}+|b|^{2/3}+\mathsf{t}^{1/12}$. This, reinjected in the above identity and using (B.1), gives (5.13). Consider now

(5.11) in the zone Z_2 where $|a| \le L^{-2/3}|b|^{2/3} \ll b^{2/3}$ and $|b| \ge L \gg 1$. Then the dominant term in the right hand side of (5.11) is b^2 and we infer that $\mathfrak{X} \approx b^2 \gg 1$ and $\mathfrak{X} \gg |a|^3$. Injecting these bounds in (5.11) gives the desired identity (5.14) for \mathfrak{X} in Z_2 . Then we rewrite (5.14) as

$$b^{2} = \mathfrak{X}\left(1 + O\left(|b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right)\right) - a - p^{*2}a^{3} = (\mathfrak{X} - a - p^{*2}a^{3})\left(1 + O\left(|b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right)\right)$$

as $\mathfrak{X}^{1/3} \gg |a|$. Hence the solution is

$$\begin{split} b &= \pm \sqrt{(\mathfrak{X} - a - p^{*2}a^3) \left(1 + O\left(|b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right)\right)} \\ &= \pm \sqrt{\mathfrak{X} - a - p^{*2}a^3} \left(1 + O\left(|b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right)\right) \\ &= \pm \sqrt{\mathfrak{X} - a - p^{*2}a^3} \left(1 + O\left(|\mathfrak{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}}\right)\right), \end{split}$$

which shows (5.16). We also rewrite (5.14) as $a + p^{*2}a^3 = \mathcal{X} - b^2 + O\left(|\mathcal{X}|^{1+1/6}\mathsf{t}^{1/4}\right)$, so that, using (B.1),

$$a = -\frac{1}{p^*} \Psi_1 \left(p^* \left(\mathfrak{X} - b^2 + O\left(|\mathfrak{X}|^{1 + \frac{1}{6}} \mathsf{t}^{\frac{1}{4}} \right) \right) \right)$$
$$= -\frac{1}{p^*} \Psi_1 \left(p^* \left(\mathfrak{X} - b^2 \right) \right) + O\left(|\mathfrak{X}|^{\frac{1}{3} + \frac{1}{6}} \mathsf{t}^{\frac{1}{4}} \right)$$

This shows (5.15) and ends the proof of the Lemma. \Box

The next Lemma adapts Lemma 5.1 to higher order derivatives.

Lemma 5.2. For L large enough, then δ small enough, the following holds true. For $(X, Y) \in Z_0^c$, it holds, with constants in the O()'s depending on L, that

$$\partial_{a} \mathcal{X} = 1 + 3p^{*2}a^{2} + O\left(|a||b|t^{\frac{1}{4}} + |b^{2}|t^{\frac{1}{2}} + |a|^{3}t^{\frac{1}{2}} + t + t^{\frac{1}{2}}|a| + t^{\frac{1}{4}}|b|\right),$$
(5.18)

$$\partial_{b} \mathcal{X} = 2b + rt^{\frac{1}{4}} + O\left(t^{\frac{3}{4}}|b|^{2} + t^{\frac{1}{2}}|b||a| + t|a|^{2} + t^{\frac{5}{4}} + t|b| + t^{\frac{3}{4}}|a|\right).$$
(5.19)

Moreover, if $(X, Y) \in Z_1$, then it holds that

$$\partial_{a} \mathcal{X} = (1 + 3p^{*2}a^{2}) \left(1 + O\left(\mathsf{t}^{\frac{1}{4}} + |a|^{\frac{1}{2}}\mathsf{t}^{\frac{1}{4}}\right) \right) \\
= \left(1 + 3\Psi_{1}^{2} \left(p^{*} \left(\mathcal{X} - b^{2} \right) \right) \right) \left(1 + O\left(\mathsf{t}^{\frac{1}{12}} + |\mathcal{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}} + |b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right) \right), \tag{5.20}$$

$$\partial_{aa} \mathcal{X} = 6p^{*2}a \left(1 + O\left(\left(|a|^{\frac{1}{2}}\mathsf{t}^{\frac{1}{4}}\right) \right) \right) + O\left(\mathsf{t}^{\frac{1}{4}}\right) \\
= -6p^{*}\Psi_{1} \left(p^{*} \left(\mathcal{X} - b^{2} \right) \right) \left(1 + O\left(\mathsf{t}^{\frac{1}{4}} + |\mathcal{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}} + |b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}} \right) \right) \\
+ O\left(\mathsf{t}^{\frac{1}{12}} \right), \tag{5.21}$$

$$\partial_{b} \mathcal{X} = 2b \left(1 + O\left(\mathsf{t}^{\frac{3}{4}} + |a|\mathsf{t}^{\frac{1}{2}} \right) \right) + O\left(\mathsf{t}^{\frac{1}{4}} + \mathsf{t}|a|^{2} \right). \tag{5.22}$$

Furthermore, if $(X, Y) \in \mathbb{Z}_2$, then it holds that

$$\partial_b \mathcal{X} = 2b \left(1 + O\left(|b|^{\frac{1}{3}} t^{\frac{1}{4}} \right) \right)$$

$$= \pm 2\sqrt{\mathcal{X} - a - p^{*2} a^3} \left(1 + O\left(|\mathcal{X}|^{\frac{1}{6}} t^{\frac{1}{4}} \right) \right), \tag{5.23}$$

$$\partial_{bb} \mathcal{X} = 2\left(1 + O\left(|b|^{\frac{2}{3}} t^{\frac{1}{2}}\right)\right) = 2\left(1 + O\left(|\mathcal{X}|^{\frac{1}{3}} t^{\frac{1}{2}}\right)\right),$$
 (5.24)

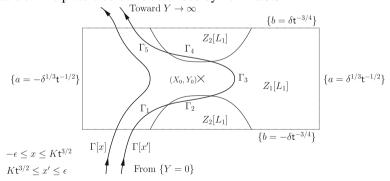
$$\partial_a \mathcal{X} = 1 + 3p^{*2}a^2 + O\left(|b|^{\frac{5}{3}}t^{\frac{1}{4}}\right) = 1 + 3p^{*2}a^2 + O\left(|\mathcal{X}|^{\frac{5}{6}}t^{\frac{1}{4}}\right).$$
 (5.25)

Proof. We omit the proof, relying only on explicit manipulation of the Taylor expansion of x, and which is verbatim the same as that of Lemma 5.1. \square

5.3. Normal Displacement

The function $(a, b) \mapsto \mathfrak{X}(t, a, b)$ has been computed in the previous Subsection, what allows us to compute $(a, b) \mapsto \mathcal{Y}(t, a, b)$, relying on Lemma A.1. Let $\Gamma[x]$ denote the curve $\{x[t](X,Y)=x\}$ in Lagrangian variables, with starting point at $\{Y=0\}$. The proof of Lemma 5.3 below ensures $\Gamma[x]$ enters Z_0^c either from the bottom side $\{b=-\delta t^{-3/4}\}$ or from the upper side $\{b=\delta t^{-3/4}\}$. By a continuity argument, for δ small, then $\epsilon>0$ small enough, all such curves with $|x-x^*| \leq \epsilon$ enter from the same side. Without loss of generality we assume it to be the bottom side. This assumption is harmless: if they enter from the upper side the same conclusions would hold from the symmetry (iii) in Proposition 1.

With the control of the behaviour of \mathfrak{X} in the zones Z_1 and Z_2 obtained in Lemma 5.1, a parametrisation of these level curves as graphs over the b variable is possible most of the time, but there is a case for which this is impossible, and we then cut in several zones, each parametrised with either the variable a or the variable b. The picture below is described by Lemma 5.3.



Lemma 5.3. (Lagrangian structure of the curves $\{x = Cte\}$). For all \tilde{L} large enough, for any $L_1 \geq \tilde{L}$, there exists $K^* \geq \tilde{L}$ such that for $K \geq K^*$, there exists $L_2^* \geq \tilde{L}$ such that for $L_2 \geq L_2^*$, for δ small enough and then ϵ small enough, the following holds. For any $|x - x^*| \leq \epsilon$ the set $\Gamma[x] \cap Z_0^c$ consists of a curve entering and exiting at the points (a_{in}, b_{in}) and (a_{out}, b_{out}) with $b_{in} = -\delta t^{-3/4}$ and $b_{out} = \delta t^{-3/4}$. In addition,

- (i) For $-\epsilon \le x x^* \le Kt^{3/2}$ this set can be parametrised with the variable b, via a = a(x, b), and is contained in $Z_1[L_2]$.
- (ii) For $Kt^{3/2} \le x x^* \le \epsilon$ this set consists on the concatenation of five curves $\Gamma_1, \Gamma_2, \Gamma_3, \Gamma_4, \Gamma_5$ with starting and end points $(a_{in}, b_{out}), (a_1, b_1), (a_2, b_2), (a_3, b_3), (a_4, b_4), and <math>(a_{out}, b_{out})$ where

$$b_1 = -L_1 \left(1 + |a_1|^{\frac{3}{2}} \right), \ b_2 = -L_1 \left(1 + |a_2|^{\frac{3}{2}} \right),$$

 $b_3 = L_1 \left(1 + |a_3|^{\frac{3}{2}} \right), \ b_4 = L_1 \left(1 + |a_4|^{\frac{3}{2}} \right).$

 Γ_1 lies in $Z_1[L_1]$ with $a, b \ll -1$, and can be parametrised as a curve a = a(x,b). Γ_2 lies in $Z_2[L_1]$ with b < 0, and can be parametrised as a curve b = b(x,a). Γ_3 lies in $Z_1[L_1]$ with a > 0, and can be parametrised as a curve a = a(x,b). Γ_4 lies in $Z_2[L_1]$ with b > 0, and can be parametrised as a curve b = b(x,a). Γ_5 lies in $Z_1[L_1]$ with a < 0 and b > 0, and can be parametrised as a curve a = a(x,b).

Proof. Step 1 The in and out points Fix $|x| \le \epsilon$, we show the existence of the in and out points and show that they are the only points at the boundary of Z_0^c . The in point is the point of the curve belonging to the lower boundary $\{b = -\delta t^{-3/4}\}$ of Z_0^c . We fix $b_{in} = -\delta t^{-3/4}$ and look for the corresponding parameter a_{in} . For $(a,b) \in Z_2[L_1]$ one has $|b| \gtrsim L_1$, $|a| \ll |b|^{2/3}$ and $t^{\frac{3}{4}}|b| = o(1)$ as $\delta \to 0$. Hence, from (5.14),

$$\mathfrak{X} \geq |b|^2$$
.

In particular, if $(a, b_{in}) \in Z_2[L_1]$ then $x(a, b_{in}) - x^* \gtrsim \delta^2 > \epsilon \ge x - x^*$. Hence there are no solutions in $Z_2[L_1]$. As $(0, b_{in}) \in Z_2[L_1]$, one has from the inequality above $x(0, b_{in}) - x^* > x - x^*$ and as $(-\delta^{1/3} t^{-1/2}, b_{in}) \in Z_1[L_1]$ one has, from (5.12),

$$x(-\delta^{1/3}\mathsf{t}^{-1/2}, b_{in}) - x^* = -p^{*2}\delta(1 + o(1)) < -\epsilon \le x - x^*. \tag{5.26}$$

Hence by the intermediate value Theorem there exists a solution a_{in} to $x(a_{in},b_{in})=x$, which is unique as $\partial_a x>0$ on $Z_1[L_1]$ from (5.20). One can show the existence and uniqueness of the out point (a_{out},b_{out}) at the north boundary $\{b=\delta t^{-3/4}\}$ with the same argument. The computation (5.26) holds true at the left boundary $\{a=-\delta^{1/3}t^{-1/2}\}$ of Z_0^c , and a similar computation shows that $x-x^*>\epsilon$ at the right boundary $\{a=\delta^{1/3}t^{-1/2}\}$. Hence the two points (a_{in},b_{in}) and (a_{out},b_{out}) are the only points of the curve at the boundary of Z_0^c .

Step 2 *Proof of (i).* From the first step, the strict monotonicity $\partial_a x > 0$ in $Z_1[L_2]$ from (5.20), and since $\Gamma \cap Z_0^c \subset Z_1[L_2]$, a standard application of the implicit function theorem gives that the curve x(a,b) = x can be parametrised with the variable b as a = a(x,b) for $b \in [-\delta t^{-3/4}, \delta t^{-3/4}]$.

Step 3 *Proof of (ii).* Fix $Kt^{3/2} \le x - x^* \le \epsilon$. We first prove the existence and uniqueness of the point (a_1, b_1) on the curve $b_1 = -L_1(|a_1|^{3/2} + 1)$ with $a_1 < 0$. On this curve, from (5.14), using the fact that $|a_1| \le |b_1|$,

$$\mathfrak{X}(a_1,b_1) = b_1^2(1+o(1)),$$

where the o(1) is as $L_1 \to \infty$. Hence, as for $a_1 = 0$, $\mathfrak{X}(0, -L_1) = O(L_1^2) < K \le \mathfrak{X}$ and, for $b_1 = -\delta t^{-3/4}$,

$$x\left(-\left(\frac{\delta}{\mathsf{t}^{3/4}L_1}-1\right)^{2/3},-\delta\mathsf{t}^{-3/4}\right)-x^*=\delta^2(1+o(1))>\epsilon\geqq x-x^*,$$

there exists a solution (a_1, b_1) with $b_1 = -L_1(|a_1|^{3/2} + 1)$ and $a_1 < 0$ to $x(a_1, b_1) = x$. One can also show that $\partial_{b_1} \mathcal{X} = 2b_1(1 + o(1))$ on this curve which implies the uniqueness of the point (a_1, b_1) . The existence and uniqueness of (a_2, b_2) , (a_3, b_3) and (a_4, b_4) can be done similarly.

We now show that (a_{in},b_{in}) is connected to (a_1,b_1) by the part of the curve staying in $Z_1[L_1]$ with a,b<0. Indeed, note that for b=0 and a<0, on has x<0 from (5.12). Also, for $|a|,|b| \le L_1$ one has from (5.12) that $x(a,b) \le C(L_1) t^{3/2}$ so x(a,b) < x for K large enough. Consider the part of Γ which is in the zone Z_1 with a,b<0. This proves that the only points of this set at the boundary of $Z_1 \cap \{a,b<0\}$ are precisely (a_{in},b_{in}) and (a_1,b_1) . From a direct check on the gradient of x, the curve Γ indeed penetrates the zone $Z_1 \cap \{a,b<0\}$ at these two points, and so the part of Γ in the zone $Z_1 \cap \{a,b<0\}$ consists of a curve joining these two points. Moreover, as in Z_1 , it holds that $\partial_a x>0$, from (5.20), so it can be parametrised with the variable b.

The proof of the properties for Γ_i for $i \geq 2$ can be proved following the same ideas. We just mention that in $Z_2[L_1]$ there holds $\partial_b \mathcal{X} > 0$ for b > 0 and $\partial_b \mathcal{X} < 0$ for b < 0 from (5.23), which shows that the curves Γ_2 and Γ_4 can indeed be parametrised with the variable a. \square

The knowledge of $(a, b) \mapsto \mathfrak{X}$ and of its level curves (Lemmas 5.1, 5.2 and 5.3), allows us to retrieve the value of \mathcal{Y} by incompressibility using (A.2).

Lemma 5.4. For any $N_2 \ge 1$, for N_1 large enough and then K large, the following holds true for $\delta > 0$ small and then $\epsilon > 0$ small enough. If, in the first case, $(X,Y) \in Z_0^c$ is such that either $-\epsilon \le x(a,b) - x^* \le Kt^{3/2}$, or, $Kt^{3/2} \le x - x^* \le \epsilon$ and b < 0 and $N_2|\mathfrak{X}(a,b)| \le |b|^2$ then it holds that

$$\mathcal{Y}(a,b) = \mathcal{Y}^{\Theta}(a,b) + \int_{-\infty}^{b} \frac{O\left(\mathsf{t}^{\frac{1}{12}} + |\tilde{b}|^{\frac{1}{4}}\mathsf{t}^{\frac{3}{16}} + |\mathfrak{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}}\right)}{1 + 3\Psi_{1}^{2}\left(p^{*}\left(\mathfrak{X} - \tilde{b}^{2}\right)\right)} d\tilde{b} + O(\mathsf{t}^{\frac{1}{4}}), \tag{5.27}$$

$$\partial_{a}\mathcal{Y}(a,b) = \partial_{a}\mathcal{Y}^{\Theta}(a,b) + 6p^{*}\left(1 + 3\Psi_{1}^{2}\left(p^{*}\left(\mathfrak{X} - b^{2}\right)\right)\right)$$

$$\times \left(\int_{-\infty}^{b} \frac{\Psi_{1}\left(p^{*}\left(\mathfrak{X} - \tilde{b}^{2}\right)\right)O\left(\mathsf{t}^{\frac{1}{12}} + |\mathfrak{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}} + |\tilde{b}|^{\frac{1}{4}}\mathsf{t}^{\frac{3}{16}} + \mathsf{t}^{\frac{1}{4}}|b|^{\frac{1}{3}}\right)}{\left(1 + 3\Psi_{1}^{2}\left(p^{*}(\mathfrak{X} - \tilde{b}^{2})\right)\right)^{3}} d\tilde{b} + O(\mathsf{t}^{\frac{7}{4}})$$

$$+ \int_{-\infty}^{b} \frac{O\left(\mathsf{t}^{\frac{1}{12}}\right)}{\left(1 + 3\Psi_{1}^{2}\left(p^{*}(\mathfrak{X} - \tilde{b}^{2})\right)\right)^{3}} d\tilde{b} + O(\mathsf{t}^{\frac{7}{4}}). \tag{5.28}$$

If, in the second case, $(X, Y) \in Z_0^c$ is such that

$$N_1 \le |p^{*2}a^3 + b^2|, \ b^2 \le N_2|p^{*2}a^3 + b^2|,$$
 (5.29)

then

$$\mathcal{Y}(a,b) = \mathcal{Y}^{\Theta}(a,b) \left(1 + O\left(\mathsf{t}^{\frac{1}{12}} | \mathfrak{X}|^{\frac{1}{18}} \right) \right),$$

$$\partial_{a} \mathcal{Y}(a,b) = \partial_{a} \mathcal{Y}^{\Theta}(a,b) + O\left(\mathsf{t}^{\frac{1}{12}} | \mathfrak{X}|^{-\frac{1}{2} + \frac{1}{18}} \right),$$

$$\partial_{b} \mathcal{Y}(a,b) = \partial_{b} \mathcal{Y}^{\Theta}(a,b) + O\left(|\mathfrak{X}|^{-\frac{2}{3} + \frac{1}{18}} \mathsf{t}^{\frac{1}{12}} \right).$$
(5.30)

Proof of Lemma 5.4. The proof is relegated to Appendix B. \Box

5.4. Inverting the characteristics map

We now prove Theorem 2. Our main strategy is to renormalise the characteristics and to invert them precisely. The below drawing sums up the transformations. In particular, we will show that the mapping $(a,b)\mapsto (\mathfrak{X},\mathcal{Y})$ is close to the mapping Φ defined by (1.17). We will use a perturbative argument to show the inverse is close to $\Phi^{-1}=(a,b)$. However, this inversion is done in an unbounded zone, which forces us to renormalise the perturbation problems when approaching infinity or the boundary of support of Θ . Hence we need precise asymptotic estimates for a and b. The Lemma below provides us with all the estimates that will be used to conclude the proof of Theorem 1.

Lemma 5.5. One has the formulae for the mappings $(\mathfrak{X}^{\Theta}, \mathcal{Y}^{\Theta})$ and (a, b) defined by (5.4):

$$\partial_{a}\mathcal{Y}^{\Theta}(a,b) = 6p^{*}\left(1 + 3p^{*2}a^{2}\right) \int_{-\infty}^{b} \frac{\Psi_{1}\left(p\left(\mathfrak{X}^{\Theta}(a,b) - \tilde{b}^{2}\right)\right)}{\left(1 + 3\Psi_{1}^{2}\left(p(\mathfrak{X}^{\Theta}(a,b) - \tilde{b}^{2}\right)\right)\right)^{3}} d\tilde{b},$$

$$\partial_{b}\mathcal{Y}^{\Theta}(a,b) = \frac{1}{1 + 3p^{*2}a^{2}} + 12p^{*}b \int_{-\infty}^{b} \frac{\Psi_{1}\left(p\left(\mathfrak{X}^{\Theta}(a,b) - \tilde{b}^{2}\right)\right)}{\left(1 + 3\Psi_{1}^{2}\left(p(\mathfrak{X}^{\Theta}(a,b) - \tilde{b}^{2}\right)\right)\right)^{3}} d\tilde{b},$$

$$\left(\frac{\partial_{\mathcal{X}}a}{\partial_{\mathcal{X}}b} \frac{\partial_{\mathcal{Y}}a}{\partial_{\mathcal{Y}}b}\right) = \begin{pmatrix}\partial_{b}\mathcal{Y}^{\Theta} - \partial_{b}\mathfrak{X}^{\Theta} \\ -\partial_{a}\mathcal{Y}^{\Theta} \frac{\partial_{a}\mathfrak{X}^{\Theta}}{\partial_{a}\mathfrak{X}^{\Theta}}\right).$$

$$(5.32)$$

⁹ Note that in this second subcase, for *K* large, from (5.11) one has necessarily $|a| \approx |b|^{2/3} \gg 1$.

(i) Bottom of the self similar zone. There exists $c_i \neq 0$ for i = 1, ..., 4 such that, as $\kappa \to 0$, for all $(\mathfrak{X}, \mathcal{Y}) \in \mathcal{H}$ such that, $0 < \mathcal{Y} \leq \kappa \langle \mathfrak{X} \rangle^{-1/6}$, it holds that $\ell < 0$ and

$$|p^{*2}a^3 + \ell^2| = o(\ell^2), \quad |\ell| \approx \frac{1}{y^3}, \quad |a| \approx \frac{1}{y^2},$$

$$\left| \int_{-\infty}^{\ell} \frac{\Psi_1(\mathfrak{X} - \tilde{\ell}^2)}{\left(1 + 3\Psi_1^2(\mathfrak{X} - \tilde{\ell}^2)\right)^3} d\tilde{\ell} \right| \approx |\ell|^{-\frac{7}{3}},$$

and, at the point $(a, b) = (a, b)(\mathfrak{X}, \mathfrak{Y})$,

$$|\partial_{\alpha} \mathfrak{X}^{\Theta}| \sim c_1 |\mathfrak{E}|^{\frac{4}{3}}, \quad |\partial_{\theta} \mathfrak{X}^{\Theta}| \sim c_2 |\mathfrak{E}|, |\partial_{\alpha} \mathfrak{Y}^{\Theta}| \sim c_3 |\mathfrak{E}|^{-1}, \quad |\partial_{\theta} \mathfrak{Y}^{\Theta}| \sim c_4 |\mathfrak{E}|^{-\frac{4}{3}}.$$
 (5.34)

(ii) Sides of the self similar zone. For $\kappa > 0$ small, there exists $M^*(\kappa)$ with $M^*(\kappa) \to \infty$ such that, for $M \ge M^*(\kappa)$, $|\mathfrak{X}| \ge M$ and $\kappa |\mathfrak{X}|^{-1/6} \le \mathcal{Y} \le (2-\kappa)C_{\pm}|\mathfrak{X}|^{-1/6}$ where $\pm = sgn(\mathfrak{X})$,

$$|\mathcal{E}| \lesssim C(\kappa) |p^{*2}\alpha^3 + \mathcal{E}^2|, \ |p^{*2}\alpha^3 + \mathcal{E}^2| \geqq \frac{M}{2}, \ |\mathcal{E}| \approx |\mathfrak{X}|^{1/2}, \ |\alpha| \approx |\mathfrak{X}|^{\frac{1}{6}},$$

$$\begin{array}{l} \partial_{\mathcal{X}} a \sim |\mathfrak{X}|^{-\frac{2}{3}} \varphi_{\pm}^{1}(\mathcal{Y}|\mathfrak{X}|^{1/6}), \quad \partial_{\mathcal{Y}} a \sim |\mathfrak{X}|^{\frac{1}{2}} \varphi_{\pm}^{2}(\mathcal{Y}|\mathfrak{X}|^{1/6}), \\ \partial_{\mathcal{X}} b \sim |\mathfrak{X}|^{-\frac{1}{2}} \varphi_{\pm}^{3}(\mathcal{Y}|\mathfrak{X}|^{1/6}), \quad \partial_{\mathcal{Y}} b \sim |\mathfrak{X}|^{\frac{2}{3}} \varphi_{\pm}^{4}(\mathcal{Y}|\mathfrak{X}|^{1/6}), \end{array}$$
(5.35)

for some functions $\varphi_{\pm}^{j} \in C^{\infty}(0, 2C_{\pm})$ where $\pm = sgn(\mathfrak{X})$, such that $((\varphi_{\pm}^{1}, \varphi_{\pm}^{3}), (\varphi_{\pm}^{2}, \varphi_{\pm}^{4}))$ is volume preserving. For $N, \tilde{N} > 0$, we have as $\tilde{N} \to \infty$ and $N^{2}\tilde{N}^{-1} \to \infty$ that for $(a, b) \in \mathbb{R}^{2}$ with $|p^{*2}a^{3}+b^{2}| \geq \max(N, \tilde{N}^{-1}b^{2})$ it holds that

$$\mathcal{Y}^{\Theta}(a, \mathfrak{k}) \approx |\mathfrak{X}^{\Theta}(a, \mathfrak{k})|^{-\frac{1}{6}},
\int_{-\infty}^{\mathfrak{k}} \frac{|\tilde{\mathfrak{k}}|^{\frac{1}{9}} d\tilde{\mathfrak{k}}}{1 + 3\Psi_{1}^{2} \left(p^{*}(\mathfrak{X}^{\Theta}(a, \mathfrak{k}) - \tilde{\mathfrak{k}}^{2})\right)} \lesssim |\mathfrak{X}^{\Theta}(a, \mathfrak{k})|^{-\frac{1}{6} + \frac{1}{18}}, \quad (5.36)
\left| \int_{-\infty}^{\mathfrak{k}} \frac{\Psi_{1} \left(p^{*}(\mathfrak{X}^{\Theta} - \tilde{\mathfrak{k}}^{2})\right) d\tilde{\mathfrak{k}}}{\left(1 + 3\Psi_{1}^{2} \left(p^{*}(\mathfrak{X}^{\Theta} - \tilde{\mathfrak{k}}^{2})\right)\right)^{3}} \right| \lesssim |\mathfrak{X}^{\Theta}|^{-\frac{7}{6}},
\int_{-\infty}^{\mathfrak{k}} \frac{|\Psi_{1} \left(p^{*}(\mathfrak{X}^{\Theta} - \tilde{\mathfrak{k}}^{2})\right) ||\tilde{\mathfrak{k}}|^{\frac{1}{12}} d\tilde{\mathfrak{k}}}{\left(1 + 3\Psi_{1}^{2} \left(p^{*}(\mathfrak{X}^{\Theta} - \tilde{\mathfrak{k}}^{2})\right)\right)^{3}} \lesssim |\mathfrak{X}^{\Theta}|^{-\frac{7}{6} + \frac{1}{24}}. \quad (5.37)$$

Proof of Lemma 5.5. All identities in Lemma 5.5 are direct consequences of the formula for the mapping Φ defined by (1.17), and of the other properties of Θ listed in Proposition 1. To avoid repetition, we do not give a proof and refer to Section 3 for the study of these functions. \Box

We are now in position to end the proof of Theorem 1. The proof is lengthy and a bit repetitive. The computations are however detailed for clarity. For $|x-x^*(t)| \le \epsilon$, let $\Gamma_{(X_b,0)}^{(X_{out},Y_{out})}$ be the part of the curve $\Gamma[x] = \{x[t](X,Y) = x\}$ joining the boundary of the upper half plane and the point (a_{out},b_{out}) defined in Lemma 5.3. We define

$$y^{*}(t,x) = \int_{\Gamma_{(X_{lo,0})}^{(X_{out}, Y_{out})}} \frac{\mathrm{d}s}{|\nabla x|}.$$
 (5.38)

We introduce the following zones: the core, the sides, the bottom and the top of the self-similar zone, and the zones below and above, respectively; that is,

$$\mathfrak{Z}_{co}[M_{co}, \kappa_{co}]$$

$$= \left\{ |x - x^*| \le M_{co} t^{3/2}, \ \kappa_{co} t^{-1/4} \le y \le 2 \left(\mathcal{Y}_{\mu,\nu,\iota}^* \left(\frac{x - x^*}{t^{3/2}} \right) - \kappa_{co} \right) t^{-\frac{1}{4}} \right\},$$
(5.39)

$$\mathcal{Z}_{si}[M_{si}, \kappa_{si}] = \left\{ M_{si} t^{3/2} \le |x - x^*| \le \epsilon, \ \frac{\kappa_{si}}{|x - x^*|} \le y \le \frac{C_{\text{sgn}(x - x^*)} - \kappa_{si}}{|x - x^*|^{1/6}} \right\},$$
(5.40)

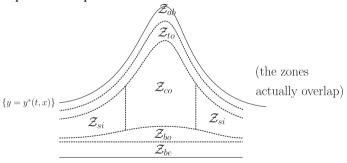
$$\mathcal{Z}_{bo}[K_{bo}, \kappa_{bo}] = \left\{ |x - x^*| \le \epsilon, \ K_{bo} \le y \le \frac{\kappa_{bo}}{|x - x^*|^{1/6} + t^{1/4}} \right\},\tag{5.41}$$

$$\mathcal{Z}_{to}[M_{to}, \kappa_{to}] = \left\{ |x - x^*| \le \epsilon, \ y^*(t, x)(1 - \kappa_{to}) \le y \le y^*(t, x) - K_{to} \right\},\tag{5.42}$$

$$\mathcal{Z}_{be}[K_{bo}] = \{ |x - x^*| \le \epsilon, \ 0 \le y \le K_{bo} \}, \tag{5.43}$$

$$\mathcal{Z}_{ab}[K_{to}] = \{ |x - x^*| \le \epsilon, \ y^*(t, x) - K_{to} \le y \}.$$
 (5.44)

This corresponds to the picture



Their Lagrangian counterparts are defined as follows:

$$Z_{co}[N_{co}] = \{ |a| \le N_{co}, \quad |b| \le N_{co} \}, \tag{5.45}$$

$$Z_{si}[N_{si}, \tilde{N}_{si}] = Z_0^c \cap \left\{ N_{si} \le |p^{*2}a^3 + b^2|, \quad b^2 \le \tilde{N}_{si}|p^{*2}a^3 + b^2|. \right\}, \quad (5.46)$$

$$Z_{bo}[N_{bo}, \tilde{N}_{bo}] = \left\{ -\delta t^{-3/4} \le b \le -N_{bo}, \quad \tilde{N}_{bo}|p^{*2}a^3 + b^2| \le b^2 \right\}, \quad (5.47)$$

$$Z_{to}[M_{to}, \kappa_{to}] = \left\{ -\delta t^{-3/4} \le b \le -N_{to}, \quad \tilde{N}_{to}|p^{*2}a^3 + b^2| \le b^2 \right\}$$
 (5.48)

Proof of Theorem 1. We invert the characteristics, bearing in mind that the leading order term is (α, β) as defined in (5.4). The change of variables preserving volume, one has

$$\begin{pmatrix} \partial_{\mathcal{X}} a \ \partial_{\mathcal{Y}} a \\ \partial_{\mathcal{X}} b \ \partial_{\mathcal{Y}} b \end{pmatrix} = \begin{pmatrix} \partial_b \mathcal{Y} & -\partial_b \mathcal{X} \\ -\partial_a \mathcal{Y} & \partial_a \mathcal{X} \end{pmatrix}$$

Once the characteristics are inverted, we use the Taylor expansion of u in Lagrangian variables near (X_0, Y_0) (a direct consequence of (5.2)), where u_X below is evaluated at (T, X_0, Y_0) , to get

$$u(t, X, Y) = u^* - (-u_X \overline{k}_1) a t^{\frac{1}{2}} + O\left(t^{\frac{3}{4}} |b| + t|a|^2 + t^{\frac{3}{2}} |a|\right)$$
(5.49)

$$\partial_a u = -(-u_X \overline{k}_1) t^{\frac{1}{2}} \left(1 + O\left(T - t + t^{\frac{1}{2}} |a| + t^{\frac{3}{4}} |b|\right)\right),$$

$$\partial_b u = O(t^{\frac{3}{4}}),$$

$$\partial_{\mathcal{X}} u = \partial_a u \partial_b \mathcal{Y} - \partial_b u \partial_a \mathcal{Y}, \qquad \partial_{\mathcal{Y}} u = -\partial_a u \partial_b \mathcal{X} + \partial_b u \partial_a \mathcal{X}.$$
 (5.50)

We fix, once for all, the variables L_1 and L_2 such that Lemmas 5.1, 5.2 and 5.3 hold true.

Step 1 The core of the self-similar zone. We claim that for any M_{co} , $\kappa_{co} > 0$, for δ small and then ϵ small, the estimates (1.28), (1.29) and (1.30) hold true for $(\hat{x}, \hat{y}) \in \mathcal{Z}_{co}$. Fix then $(\hat{x}, \hat{y}) \in \mathcal{Z}_{co}$, and define (\hat{x}, \hat{y}) by (5.5). We want to invert the characteristics and to find the corresponding \hat{a} and \hat{b} such that $(x, y)(\hat{a}, \hat{b}) = (\hat{x}, \hat{y})$.

Let $N_{co} \gg 1$ to be chosen later on and consider $(a, b) \in Z_{co}$. We will first show a priori estimates in Z_{co} , that will allow us to prove that $(\hat{a}, \hat{b}) \in Z_{co}$. This will justify the a priori estimates and prove the claim. The zone Z_{co} lies in the zone Z_1 for δ small enough, so the corresponding estimates in Lemma 5.1 apply. Moreover, as $|a|, |b|, |\mathfrak{X}| \lesssim 1$, one obtains from (5.11), (5.20) and (5.22) that

$$\mathfrak{X} = a + p^{*2}a^3 + b^2 + O\left(\mathsf{t}^{\frac{1}{4}}\right) = \mathfrak{X}^{\Theta}(a, b) + O\left(\mathsf{t}^{\frac{1}{4}}\right),$$

and, similarly,

$$\partial_{a} \mathcal{X} = 1 + 3p^{*2}a^{2} + O\left(\mathsf{t}^{\frac{1}{4}}\right) = \partial_{a} \mathcal{X}^{\Theta} + O\left(\mathsf{t}^{\frac{1}{4}}\right),$$

$$\partial_{b} \mathcal{X} = 2b + O\left(\mathsf{t}^{\frac{1}{4}}\right) = \partial_{b} \mathcal{X}^{\Theta} + O\left(\mathsf{t}^{\frac{1}{4}}\right).$$
(5.52)

Since $|\mathfrak{X}| \lesssim 1$, one can use the identities (5.27) and (5.28). Injecting that $|\mathfrak{X}|, |b| \lesssim 1$ and that $1+3\Psi_1^2\left(p^*\left(\mathfrak{X}-b^2\right)\right)\gtrsim (1+|\tilde{b}|^{4/3})$ for $\tilde{b}\leq b$ from (3.14) in (5.27) gives

$$\begin{aligned} \mathcal{Y}(a,b) &= 2 \int_{-\infty}^{b} \frac{\mathrm{d}\tilde{b}}{1 + 3\Psi_{1}^{2} \left(p^{*} \left(\mathfrak{X} - b^{2} \right) \right)} + O \left(\int_{-\infty}^{b} \frac{|\tilde{b}|^{\frac{1}{4}} \mathsf{t}^{\frac{3}{16}}}{1 + |\tilde{b}|^{\frac{4}{3}}} \mathrm{d}\tilde{b} \right) + O \left(\mathsf{t}^{\frac{1}{12}} \right) \\ &= \mathcal{Y}^{\Theta}(a,b) + O \left(\mathsf{t}^{\frac{1}{12}} \right). \end{aligned}$$

Injecting that |b|, $|\mathfrak{X}| \lesssim 1$ and $1 + 3\Psi_1^2 \left(p^* \left(\mathfrak{X} - b^2 \right) \right) \approx (1 + |\tilde{b}|^{4/3})$ in (5.28) gives, similarly, that

$$\begin{split} \partial_{a}\mathcal{Y}(a,b) &= 6p^{*} \left(1 + 3\Psi_{1}^{2} \left(p^{*} \left(\mathfrak{X} - b^{2} \right) \right) \right) \int_{-\infty}^{b} \frac{\Psi_{1} \left(p^{*} \left(\mathfrak{X} - \tilde{b}^{2} \right) \right)}{\left(1 + 3\Psi_{1}^{2} \left(p^{*} (\mathfrak{X} - \tilde{b}^{2}) \right) \right)^{3}} \mathrm{d}\tilde{b} \\ &+ O \left(\int_{-\infty}^{b} \frac{\mathsf{t}^{\frac{1}{12}} + |\tilde{b}|^{\frac{1}{4}} \mathsf{t}^{\frac{3}{16}}}{1 + \tilde{b}^{\frac{10}{3}}} \mathrm{d}\tilde{b} \right) + O \left(\mathsf{t}^{\frac{7}{4}} \right) \\ &= \partial_{a}\mathcal{Y}^{\Theta}(a,b) + O \left(\mathsf{t}^{\frac{1}{12}} \right). \end{split}$$

We retrieve the last partial derivative $\partial_b \mathcal{Y}(a, b)$ by incompressibility, using $\partial_a \mathcal{X} \approx 1$, (5.52) and the above identity to get

$$\partial_b \mathcal{Y}(a,b) = \frac{1 + \partial_a \mathcal{Y} \partial_b \mathcal{X}}{\partial_a \mathcal{X}} = \frac{1 + \left(\partial_a \mathcal{Y}^{\Theta} + O\left(\mathsf{t}^{\frac{1}{12}}\right)\right) \left(\partial_b \mathcal{X}^{\Theta} + O\left(\mathsf{t}^{\frac{1}{4}}\right)\right)}{\partial_a \mathcal{X}^{\Theta} \left(1 + O\left(\mathsf{t}^{\frac{1}{12}}\right)\right)} \\
= \partial_b \mathcal{Y}^{\Theta} + O\left(\mathsf{t}^{\frac{1}{12}}\right).$$

We are now ready to invert the characteristics. We look for a solution of the form $(a, b) = (\overline{a} + h_1, \overline{b} + h_2)$ to (x, y)(a, b) = (x, y), where

$$(\overline{a},\overline{b}) = \left(a\left(\hat{\mathcal{X}},\hat{\mathcal{Y}}\right),t\left(\hat{\mathcal{X}},\hat{\mathcal{Y}}\right)\right) = \left(-\Theta\left(\hat{\mathcal{X}},\hat{\mathcal{Y}}\right),t\left(\hat{\mathcal{X}},\hat{\mathcal{Y}}\right)\right).$$

As for $(\hat{x}, \hat{y}) \in \mathcal{Z}_{co}$, $(\hat{\mathcal{X}}, \hat{\mathcal{Y}})$ is in a compact zone inside the support of Θ , then $(\overline{a}, \overline{b}) \in Z_{co}$ for N_{co} large enough depending on M_{co} and κ_{co} , so that our previous computations apply. Consider then the mapping

$$\Xi:(h_1,h_2)\mapsto \left(\mathfrak{X}\left(\overline{a}+h_1,\overline{b}+h_2\right),\mathcal{Y}\left(\overline{a}+h_1,\overline{b}+h_2\right)\right).$$

From the estimates on the derivatives done above, it holds for $|h_1|$, $|h_2| = O(\mathfrak{t}^{1/12})$ that

$$\begin{pmatrix} \partial_{h_1} \Xi_1 & \partial_{h_2} \Xi_1 \\ \partial_{h_1} \Xi_2 & \partial_{h_2} \Xi_2 \end{pmatrix} = \begin{pmatrix} \partial_a \mathfrak{X}^{\Theta}(\overline{a}, \overline{b}) & \partial_b \mathfrak{X}^{\Theta}(\overline{a}, \overline{b}) \\ \partial_a \mathcal{Y}^{\Theta}(\overline{a}, \overline{b}) & \partial_b \mathcal{Y}^{\Theta}(\overline{a}, \overline{b}) \end{pmatrix} + O\left(\mathfrak{t}^{\frac{1}{12}}\right). \tag{5.53}$$

Also, again from the computations performed above,

$$\Xi(0,0) - \left(\hat{\mathfrak{X}}, \hat{\mathscr{Y}}\right) = O\left(\mathsf{t}^{\frac{1}{12}}\right).$$

Note that, as \overline{a} and \overline{b} vary in Z_{co} , the first term in the right hand side of (5.53) belongs to a compact set of invertible matrices. Hence we can invert the above equation applying the implicit function Theorem, uniformly as $t \to T$ for all $(\hat{x}, \hat{y}) \in Z_{co}$: there exists $(h_1, h_2) = O(\mathfrak{t}^{\frac{1}{12}})$ such that $\Xi(h_1, h_2) = (\hat{\mathfrak{X}}, \hat{\mathfrak{Y}})$. Hence we inverted the characteristics and found that

$$\hat{a} = \overline{a} + O\left(\mathfrak{t}^{\frac{1}{12}}\right) = -\Theta(\hat{\mathfrak{X}}, \hat{\mathscr{Y}}) + O\left(\mathfrak{t}^{\frac{1}{12}}\right), \qquad \hat{b} = \overline{b} + O\left(\mathfrak{t}^{\frac{1}{12}}\right).$$

Using the Taylor expansion (5.49) of u and the fact that $|\hat{a}|$, $|\hat{b}| \lesssim 1$,

$$u(t, \hat{x}, \hat{y}) = u(t, \hat{X}, \hat{Y}) = u(t, X_0, Y_0) - (-u_X \overline{k}_1) t^{\frac{1}{2}} (\hat{a} + O(t^{\frac{1}{4}})),$$

so we infer from (5.6) that,

$$u(t, \hat{x}, \hat{y}) = u^* + \mathsf{t}^{\frac{1}{2}} \left(\Theta_{\mu, \nu, \iota} \left(\frac{\hat{x} - x^*}{\mathsf{t}^{\frac{3}{2}}}, \frac{\hat{y}}{\mathsf{t}^{-\frac{1}{4}}} \right) + O\left(\mathsf{t}^{\frac{1}{12}}\right) \right), \tag{5.54}$$

which shows (1.28). Once the inversion is done, the estimates for the derivatives (1.29) and (1.29) follow naturally, as from (5.50), (5.51), (5.33) and the above estimates, to give

$$\partial_{\mathcal{X}} u(t, \hat{x}, \hat{y}) = -\mathbf{t}^{\frac{1}{2}} \partial_{b} \mathcal{Y}^{\Theta} \left(1 + O\left(\mathbf{t}^{\frac{1}{12}}\right) \right) + O(\mathbf{t}^{\frac{3}{4}})
= \mathbf{t}^{\frac{1}{2}} \partial_{\mathcal{X}} \Theta_{\mu,\nu,\iota} \left(\frac{\hat{x} - x^{*}}{\mathbf{t}^{3/2}}, \frac{\hat{y}}{\mathbf{t}^{-1/4}} \right) + O\left(\mathbf{t}^{\frac{1}{12}}\right)
\partial_{\mathcal{Y}} u(t, \hat{x}, \hat{y}) = \mathbf{t}^{\frac{1}{2}} \partial_{b} \mathcal{X}^{\Theta} \left(1 + O(\mathbf{t}^{\frac{1}{12}}) \right) + O\left(\mathbf{t}^{\frac{3}{4}}\right)
= \mathbf{t}^{\frac{1}{2}} \partial_{\mathcal{Y}} \Theta_{\mu,\nu,\iota} \left(\frac{\hat{x} - x^{*}}{\mathbf{t}^{3/2}}, \frac{\hat{y}}{\mathbf{t}^{-1/4}} \right) + O\left(\mathbf{t}^{\frac{1}{12}}\right).$$
(5.56)

Step 2 The bottom of the self-similar zone. We claim that there exists $K_{bo}*>0$ such that for all $K_{bo} \ge K_{bo}^*$, and $\kappa_{co}>0$, for δ small and then ϵ small, the estimates (1.28), (1.29) and (1.30) hold true for $(\hat{x}, \hat{y}) \in \mathcal{Z}_{bo}$.

We apply a similar strategy as in Step 1. However the leading order term of the characteristics, which is still $(\mathfrak{X}^{\Theta}, \mathcal{Y}^{\Theta})$, becomes degenerate in this zone. Hence we first renormalise the characteristics, in order to prove that their invertibility is uniformly possible in \mathcal{Z}_{bo} . Fix $(\hat{x}, \hat{y}) \in \mathcal{Z}_{bo}$ meaning $|\hat{\mathfrak{X}}| \leq k_5 \epsilon t^{-3/2}$ and $k_6 K_{bo} t^{1/4} \leq \hat{\mathcal{Y}} \leq k_6 \kappa_{bo} / (k_5^{-1/6} |\hat{\mathfrak{X}}|^{1/6} + 1)$, and consider $(a, b) \in Z_{bo}$ for N_{bo} , \tilde{N}_{bo} to be chosen later. One has from (5.47) and from (5.11) that

$$a < 0, |b| \approx |a|^{3/2} \gg 1 \text{ and } |\mathfrak{X}| \ll |b|^2$$
 (5.57)

for all N_{bo} , \tilde{N}_{bo} large enough, hence $(a, b) \in Z_1$. Consequently all the computations corresponding to the zone Z_1 in Lemma 5.1 apply. The identities (5.12), (5.20) and (5.22) give, when injecting the bounds (5.57),

$$\mathfrak{X} = \left(a + p^{*2}a^{3} + b^{2}\right) + O\left(\mathsf{t}^{\frac{1}{4}}|b|^{2 + \frac{1}{3}}\right)
= \mathfrak{X}^{\Theta}(a, b) + O\left(\mathsf{t}^{\frac{1}{4}}|b|^{2 + \frac{1}{3}}\right), \tag{5.58}$$

$$\partial_{a}\mathfrak{X} = (1 + 3p^{*2}a^{2})\left(1 + O\left(|b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right)\right)
= \partial_{a}\mathfrak{X}^{\Theta}(a, b)\left(1 + O\left(|b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right)\right), \tag{5.59}$$

$$\partial_{b}\mathfrak{X} = 2b\left(1 + O\left(|b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right)\right) = \partial_{b}\mathfrak{X}^{\Theta}(a, b)\left(1 + O\left(|b|^{\frac{1}{3}}\mathsf{t}^{\frac{1}{4}}\right)\right). \tag{5.60}$$

We now compute \mathcal{Y} . Since b<0 and $|\mathfrak{X}|\ll |b|^2$, (5.27) and (5.28) apply. As $|\mathfrak{X}|\ll |b|^2$ and b<0, then, for $\tilde{b}\leqq b$, one has from (B.1) and (5.57) that

$$|\tilde{b}| \gg 1$$
, $\Psi_1^2(p^*(\mathfrak{X} - \tilde{b}^2)) \approx |\tilde{b}|^{4/3}$ and $|\mathfrak{X}| \ll |\tilde{b}|$. (5.61)

Injecting the above bound and (5.57) in the identity (5.27), and using (5.34), gives

$$\mathcal{Y} = 2 \int_{-\infty}^{b} \frac{d\tilde{b}}{1 + 3\Psi_{1}^{2} \left(p^{*} \left(\mathcal{X} - \tilde{b}^{2} \right) \right)} + O\left(\int_{-\infty}^{b} \frac{\mathsf{t}^{\frac{1}{12}} |\tilde{b}|^{\frac{1}{9}} d\tilde{b}}{|\tilde{b}|^{\frac{4}{3}}} \right) + O\left(\mathsf{t}^{\frac{1}{4}}\right)$$

$$= \mathcal{Y}^{\Theta}(a, b) \left(1 + O\left(\mathsf{t}^{\frac{1}{12}} |b|^{\frac{1}{9}}\right) \right). \tag{5.62}$$

Similarly, injecting (5.61) and (5.57) in the integral (5.28) to give $\partial_a \mathcal{Y}$, and using (5.32), gives

$$\begin{split} \partial_a \mathcal{Y}(a,b) &= 6p^* \left(1 + 3\Psi_1^2 \left(p^* \left(\mathfrak{X} - b^2 \right) \right) \right) \\ & \left(\int_{-\infty}^b \frac{\Psi_1 \left(p^* \left(\mathfrak{X} - \tilde{b}^2 \right) \right)}{\left(1 + 3\Psi_1^2 \left(p^* (\mathfrak{X} - \tilde{b}^2) \right) \right)^3} + O \left(\int_{-\infty}^b \frac{\mathsf{t}^{\frac{1}{12}} |\tilde{b}|^{\frac{1}{9}}}{|\tilde{b}|^{\frac{10}{3}}} \mathrm{d}\tilde{b} \right) + O \left(\mathsf{t}^{\frac{7}{4}} \right) \right) \\ &= \partial_a \mathcal{Y}^\Theta(a,b) \left(1 + O \left(\mathsf{t}^{\frac{1}{12}} |b|^{\frac{1}{9}} \right) \right). \end{split}$$

We compute the last partial derivative $\partial_b \mathcal{Y}(a, b)$ via the incompressibility, using (5.59), (5.60) and the above bound, and (5.34) to get

$$\begin{split} \partial_b \mathcal{Y}(a,b) &= \frac{1 + \partial_a \mathcal{Y} \partial_b \mathcal{X}}{\partial_a \mathcal{X}} = \frac{1 + \partial_a \mathcal{Y}^{\Theta} \partial_b \mathcal{X}^{\Theta} \left(1 + O\left(|b|^{\frac{1}{9}} \mathfrak{t}^{\frac{1}{12}}\right) \right)}{\partial_a \mathcal{X}^{\Theta} \left(1 + O\left(|b|^{\frac{1}{9}} \mathfrak{t}^{\frac{1}{12}}\right) \right)} \\ &= \partial_b \mathcal{Y}^{\Theta}(a,b) \left(1 + O\left(\mathfrak{t}^{\frac{1}{12}}|b|^{\frac{1}{9}}\right) \right). \end{split}$$

We can now invert the characteristics. We look for a solution of $(x, y)(\hat{a}, \hat{b}) = (\hat{x}, \hat{y})$ of the form $(a, b) = (\overline{a} + h_1 |\overline{b}|^{\frac{2}{3}}, \overline{b}(1 + h_2))$ close to

$$(\overline{a},\overline{b}) = \left(a\left(\hat{x},\hat{\mathcal{Y}}\right), b\left(\hat{x},\hat{\mathcal{Y}}\right)\right) = \left(-\Theta\left(\hat{x},\hat{\mathcal{Y}}\right), b\left(\hat{x},\hat{\mathcal{Y}}\right)\right),$$

and with a priori bound $|h_1|$, $|h_2| \lesssim |\overline{b}|^{1/12} t^{1/16}$. From (i) in Lemma 5.5, since $(\hat{x}, \hat{y}) \in \mathcal{Z}_{bo}$,

$$|\overline{b}| < 0, |\overline{b}| \approx \frac{1}{\mathsf{t}^{\frac{3}{4}} \hat{y}^3}, |\overline{a}| \approx \frac{1}{\mathsf{t}^{\frac{1}{2}} \hat{y}^2}, |p^{*2}\overline{a}^3 + \overline{b}^2| \le \frac{1}{\tilde{N}_{bo}^*} \overline{b}^2$$
 (5.63)

for all κ_{bo} small enough, for some $\tilde{N}_{bo}^*(\kappa_{bo}) \to \infty$ as $\kappa_{bo} \to 0$. Since $\hat{\mathcal{Y}} \lesssim \kappa_{bo} \langle \mathfrak{X} \rangle^{-1/6}$ we obtain from (5.63) that $\bar{b} \to -\infty$ as $\kappa_{bo} \to 0$. Since $\hat{y} \geq K_{bo}$ we get from (5.63) that $\bar{b} \geq -\delta t^{-3/4}$ if $\delta \geq K_{bo}^{-3}$. Thus, by taking K_{bo} large and κ_{bo}

small, there always exist some large N_{bo} , \tilde{N}_{bo} and small δ such that $(\overline{a}, \overline{b}) \in Z_{bo}$. Consider now the mapping

$$\Xi:(h_1,h_2)\mapsto\left(\frac{\mathfrak{X}\left(\overline{a}+h_1|\overline{b}|^{\frac{2}{3}},\overline{b}(1+h_2)\right)}{\overline{b}^2},\mathcal{Y}\left(\overline{a}+h_1|\overline{b}|^{\frac{2}{3}},\overline{b}(1+h_2)\right)|\overline{b}|^{\frac{1}{3}}\right).$$

From the computations on the derivatives above, (5.34) and (5.63), we have

$$\begin{pmatrix} \partial_{h_1} \Xi_1 & \partial_{h_2} \Xi_1 \\ \partial_{h_1} \Xi_2 & \partial_{h_2} \Xi_2 \end{pmatrix} = \begin{pmatrix} |\overline{b}|^{-\frac{4}{3}} \partial_a \mathfrak{X}^{\Theta}(\overline{a}, \overline{b}) & |\overline{b}|^{-1} \partial_b \mathfrak{X}^{\Theta}(\overline{a}, \overline{b}) \\ |\overline{b}| \partial_a \mathcal{Y}^{\Theta}(\overline{a}, \overline{b}) & |\overline{b}|^{\frac{4}{3}} \partial_b \mathcal{Y}^{\Theta}(\overline{a}, \overline{b}) \end{pmatrix} + O\left(\hat{y}^{-\frac{1}{3}}\right).$$

From (5.34) the above matrix is bounded, and the leading order term in the right hand side is close to a fixed invertible matrix in the whole zone under consideration. From (5.58) and (5.62),

$$\Xi(0,0)-\left(\frac{\hat{\mathcal{X}}}{|\overline{b}|^2},\hat{\mathcal{Y}}|\overline{b}|^{\frac{1}{3}}\right)=O\left(|\overline{b}|^{\frac{1}{9}}\mathfrak{t}^{\frac{1}{12}}\right)=O\left(\hat{y}^{-\frac{1}{3}}\right).$$

Therefore, one can apply the implicit function Theorem to get that there exists $(h_1, h_2) = O(\hat{y}^{-1/3})$ such that $\Xi(h_1, h_2) = \left(\frac{\hat{x}}{|\overline{b}|^2}, \hat{y}|\overline{b}|^{\frac{1}{3}}\right)$ (or equivalent) for the characteristics

$$\hat{a} = \overline{a} + h_1 |\overline{b}|^{\frac{2}{3}} = \overline{a} \left(1 + O\left(\hat{y}^{-\frac{1}{3}}\right) \right), \quad \hat{b} = \overline{b} (1 + h_2) = \overline{b} \left(1 + O\left(\hat{y}^{-\frac{1}{3}}\right) \right),$$

where we used that $|\bar{a}| \approx |\bar{b}|^{2/3}$. Hence, using the Taylor expansion (5.49) of u and the fact that $|\hat{a}|^3 \approx |\hat{b}|^2 \gg 1$,

$$u(t, \hat{x}, \hat{y}) = u(t, \hat{X}, \hat{Y}) = u(t, X_0, Y_0) - (-u_X \bar{k}_1) t^{\frac{1}{2}} \hat{a} (1 + O(|\hat{a}|t^{1/2})),$$

so from (5.6) we infer that

$$u(t,\hat{x},\hat{y}) = u^* + \mathsf{t}^{\frac{1}{2}}\Theta_{\mu,\nu,\iota}\left(\frac{\hat{x} - x^*}{\mathsf{t}^{\frac{3}{2}}}, \frac{\hat{y}}{\mathsf{t}^{-\frac{1}{4}}}\right)\left(1 + O\left(\frac{1}{\hat{y}^{\frac{1}{3}}}\right)\right), \tag{5.64}$$

which shows (1.28). Again, the estimates for the derivatives (1.29) and (1.30) follow from (5.50), (5.51), (5.33), (5.34) and the above estimates to end

$$\partial_{\mathcal{X}} u = \partial_{a} u \partial_{b} \mathcal{Y} - \partial_{b} u \partial_{a} \mathcal{Y} = -\mathbf{t}^{\frac{1}{2}} \partial_{b} \mathcal{Y}^{\Theta} \left(1 + O\left(\frac{1}{|\hat{y}|^{\frac{1}{3}}}\right) \right) + O\left(\mathbf{t}^{\frac{3}{4}} |\hat{b}|^{-1}\right) \\
= \mathbf{t}^{\frac{1}{2}} \partial_{\mathcal{X}} \Theta_{\mu,\nu,\iota} \left(1 + O\left(\frac{1}{|\hat{y}|^{\frac{1}{3}}}\right) \right), \tag{5.65}$$

$$\partial_{\mathcal{Y}} u = -\partial_{a} u \partial_{b} \mathcal{X} + \partial_{b} u \partial_{a} \mathcal{X} = \mathbf{t}^{\frac{1}{2}} \partial_{b} \mathcal{X}^{\Theta} \left(1 + O\left(\frac{1}{|\hat{y}|^{\frac{1}{3}}}\right) \right) + O\left(\mathbf{t}^{\frac{3}{4}} |\hat{b}|\right) \\
= \mathbf{t}^{\frac{1}{2}} \partial_{\mathcal{Y}} \Theta_{\mu,\nu,\iota} \left(1 + O\left(\frac{1}{|\hat{y}|^{\frac{1}{3}}}\right) \right). \tag{5.66}$$

Step 3 The sides of the self-similar zone. We claim that there exists $\kappa_{si} * > 0$ such that for all $0 < \kappa_{si} \le \kappa_{si}^*$, for M_{si} large enough, then for δ small and then ϵ small, the estimates (1.28), (1.29) and (1.30) hold true for $(\hat{x}, \hat{y}) \in \mathcal{Z}_{si}$.

Fix then $(\hat{x}, \hat{y}) \in \mathcal{Z}_{si}$ corresponding to $k_5 \epsilon t^{-3/2} \leq \hat{\mathcal{X}} \leq -k_5 M_{si}$ and $k_6 k_5^{1/6} \kappa_{si}$ $|\hat{\mathcal{X}}|^{-1/6} \leq \hat{\mathcal{Y}} \leq k_6 k_5^{1/6} (C_- - \kappa_{si}) |\hat{\mathcal{X}}|^{-1/6}$ on the left side, or to $k_5 M_{si} \leq \hat{\mathcal{X}} \leq k_5 \epsilon t^{-3/2}$ and $k_6 k_5^{1/6} \kappa_{si} \hat{\mathcal{X}}^{-1/6} \leq \hat{\mathcal{Y}} \leq k_6 k_5^{1/6} (C_+ - \kappa_{si}) \hat{\mathcal{X}}^{-1/6}$ on the right side. Let $(a, b) \in Z_{si}$ for N_{si} , \tilde{N}_{si} to be fixed large later on. In Z_{si} , from (5.46), $|a| \lesssim (|p^{*2}a^3 + b^2| + b^2)^{1/3} \lesssim \tilde{N}_{si}^{1/3} |p^{*2}a^3 + b^2|^{1/3}$, so one infers from (5.11) that

$$\mathcal{X} = (p^{*2}a^3 + b^2) \left(1 + O\left(\frac{|a|}{|p^{*2}a^3 + b^2|} + \frac{|b|\mathsf{t}^{\frac{1}{4}}}{|p^{*2}a^3 + b^2|} + |p^{*2}a^3 + b^2|^{\frac{1}{24}}\mathsf{t}^{\frac{1}{6}}\right) \right)$$

$$= (p^{*2}a^3 + b^2) \left(1 + O\left(\tilde{N}_{si}^{\frac{1}{3}}N_{si}^{-\frac{2}{3}} + |p^{*2}a^3 + b^2|^{\frac{1}{24}}\mathsf{t}^{\frac{1}{6}}\right) \right)$$

which implies that $|\mathfrak{X}| \approx |p^{*2}a^3 + b^2|$ provided $N_{si} \ll \tilde{N}_{si}^2$. Hence the bounds in this zone are

$$|\mathfrak{X}| \gtrsim N_{si} \gg 1, \quad |b| \lesssim |\mathfrak{X}|^{\frac{1}{2}}, \quad |a| \lesssim |\mathfrak{X}|^{\frac{1}{3}}. \tag{5.67}$$

Injecting these bounds in (5.11), (5.18) and (5.19), one gets

$$\mathfrak{X} = \left(a + p^{*2}a^3 + b^2\right) \left(1 + O\left(\mathsf{t}^{\frac{1}{4}}|\mathfrak{X}|^{\frac{1}{6}}\right)\right) = \mathfrak{X}^{\Theta}(a, b) \left(1 + O\left(\mathsf{t}^{\frac{1}{4}}|\mathfrak{X}|^{\frac{1}{6}}\right)\right),$$

$$\partial_a \mathfrak{X} = 1 + 3p^{*2}a^2 + O\left(|\mathfrak{X}|^{\frac{5}{6}}\mathsf{t}^{\frac{1}{4}}\right) = \partial_a \mathfrak{X}^{\Theta} + O\left(|\mathfrak{X}|^{\frac{5}{6}}\mathsf{t}^{\frac{1}{4}}\right),$$

$$\partial_b \mathfrak{X} = 2b + O\left(\mathsf{t}^{\frac{1}{4}}|\mathfrak{X}|^{\frac{2}{3}}\right) = \partial_b \mathfrak{X}^{\Theta} + O\left(\mathsf{t}^{\frac{1}{4}}|\mathfrak{X}|^{\frac{2}{3}}\right).$$
(5.69)

In addition, the estimates (5.30) and (5.31) apply and the following estimates are true for \mathcal{Y} :

$$\mathcal{Y} = \mathcal{Y}^{\Theta}(a,b) \left(1 + O\left(\mathbf{t}^{\frac{1}{12}} | \mathcal{X} |^{\frac{1}{18}} \right) \right), \ \partial_{a} \mathcal{Y} = \partial_{a} \mathcal{Y} + O\left(\mathbf{t}^{\frac{1}{12}} | \mathcal{X} |^{-\frac{1}{2} + \frac{1}{18}} \right),$$
$$\partial_{b} \mathcal{Y} = \partial_{b} \mathcal{Y}^{\Theta} + O\left(| \mathcal{X} |^{-\frac{2}{3} + \frac{1}{18}} \mathbf{t}^{\frac{1}{12}} \right).$$

With these identities we can now invert the characteristics, and again, will renormalise in a suitable way the perturbation problem. We look for a solution (\hat{a}, \hat{b}) of the form $(a, b) = (\bar{a} + h_1 |\mathcal{X}|^{1/3}, \bar{b} + h_2 |\mathcal{X}|^{1/2})$ to $(x, y)(\hat{a}, \hat{b}) = (\hat{x}, \hat{y})$, where

$$(\overline{a}, \overline{b}) = \left(a\left(\hat{\mathbf{X}}, \hat{\mathbf{Y}}\right), t\left(\hat{\mathbf{X}}, \hat{\mathbf{Y}}\right)\right) = \left(-\Theta\left(\hat{\mathbf{X}}, \hat{\mathbf{Y}}\right), t\left(\hat{\mathbf{X}}, \hat{\mathbf{Y}}\right)\right).$$

As \hat{x} , \hat{y} is in the zone (5.41), this produces, thanks to (ii) in Lemma 5.5 that

$$|\overline{b}|^2 \leq C(\kappa_{si})|p^{*2}\overline{a}^3 + \overline{b}^2|, |p^{*2}\overline{a}^3 + \overline{b}^2| \gtrsim M_{si}.$$

Hence, for any κ_{si} small enough, there exists N_{si} , \tilde{N}_{si} large with $N_{si} \gg \tilde{N}_{si}^{1/2}$ such that for M_{si} large enough, if $(\hat{a}, \hat{b}) \in \mathcal{Z}_{si}$ then $(\overline{a}, \overline{b}) \in Z_{si}$, which shows

the validity of all the computations done so far. From the above computations one infers that

$$\mathfrak{X}(\overline{a},\overline{b}) = \hat{\mathfrak{X}} \cdot \left(1 + O\left(|\hat{x} - x^*|^{\frac{1}{6}}\right)\right), \quad \mathcal{Y}(\overline{a},\overline{b}) = \hat{\mathcal{Y}} \cdot \left(1 + O\left(|\hat{x} - x^*|^{\frac{1}{24}}\right)\right).$$

Consider the mapping

$$\Xi: (h_1, h_2) \mapsto \left(\frac{\mathcal{X}\left(\overline{a} + h_1 | \overline{\mathcal{X}}|^{\frac{1}{3}}, \overline{b} + h_2 | \overline{\mathcal{X}}|^{\frac{1}{2}}\right)}{|\overline{\mathcal{X}}|}, \mathcal{Y}\left(\overline{a} + h_1 | \overline{\mathcal{X}}|^{\frac{1}{3}}, \overline{b} + h_2 | \overline{\mathcal{X}}|^{\frac{1}{2}}\right) | \overline{\mathcal{X}}|^{\frac{1}{6}}\right)$$

From the estimates on the derivatives done above, it holds for $|h_1|$, $|h_2| = O(|\hat{x}|^{1/18})$ that

$$\begin{pmatrix} \partial_{h_1} \Xi_1 & \partial_{h_2} \Xi_1 \\ \partial_{h_1} \Xi_2 & \partial_{h_2} \Xi_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{|\overline{x}|_3^2} \partial_a \mathfrak{X}^{\Theta}(\overline{a}, \overline{b}) & \frac{1}{|\overline{x}|_2^1} \partial_b \mathfrak{X}^{\Theta}(\overline{a}, \overline{b}) \\ |\overline{x}|_2^1 \partial_a \mathcal{Y}^{\Theta}(\overline{a}, \overline{b}) & |\overline{x}|_2^2 \partial_b \mathcal{Y}^{\Theta}(\overline{a}, \overline{b}) \end{pmatrix} + O\left(|\hat{x}|_{\overline{18}}\right),$$

and the Jacobian matrix of Ξ must preserve volume. From the computations above,

$$\Xi(0,0) - \left(\frac{\hat{\mathcal{X}}}{|\overline{\mathcal{X}}|}, \hat{\mathcal{Y}}|\overline{\mathcal{X}}|^{\frac{1}{6}}\right) = O\left(|\hat{x}|^{\frac{1}{18}}\right).$$

Note that, due to (5.35), as $\mathfrak{X} \to +\infty$, in the zone that we consider (5.46), the leading order matrix in the identity giving the Jacobian of Ξ in the right hand side belongs to a compact set of matrices with determinant 1. Hence, applying the inverse function Theorem, we can invert the above equation, uniformly as $\epsilon \to 0$ in the zone that we consider: there exists $(h_1,h_2) = O(|\hat{x}|^{\frac{1}{24}})$ such that $\Xi(h_1,h_2) = \left(\frac{\hat{x}}{|\Xi|},\hat{\mathcal{Y}}|\overline{\mathcal{X}}|^{\frac{1}{6}}\right)$. Hence we inverted the characteristics and found that

$$\hat{a} = \overline{a} \left(1 + O\left(|\hat{x}|^{\frac{1}{18}} \right) \right), \ \hat{b} = \overline{b} \left(1 + O\left(|\hat{x}|^{\frac{1}{18}} \right) \right).$$

Hence, using the Taylor expansion (5.49) of u and the fact that $|\hat{a}|^3$, $|\hat{b}|^2 \lesssim |\hat{\mathcal{X}}|$,

$$u(t, \hat{x}, \hat{y}) = u(t, X, Y) = u^* - (-u_X \overline{k}_1) t^{\frac{1}{2}} \hat{a} + O\left(|\hat{b}| t^{\frac{3}{4}} + |\hat{a}|^3 t^{\frac{3}{2}}\right)$$
$$= -(-u_X \overline{k}_1) t^{\frac{1}{2}} \left(\hat{a} + O\left(|\hat{X}|^{\frac{1}{3} + \frac{1}{6}} t^{\frac{1}{4}}\right)\right),$$

and we infer from (5.6) that

$$u(t, \hat{x}, \hat{y}) = u^* + t^{\frac{1}{2}} \left(\Theta_{\mu, \nu, \iota} \left(\frac{\hat{x} - x^*}{t^{\frac{3}{2}}}, \frac{\hat{y}}{t^{-\frac{1}{4}}} \right) + O\left(\frac{|\hat{x} - x^*|^{\frac{1}{3} + \frac{1}{18}}}{t^{\frac{1}{2}}} \right) \right),$$
(5.70)

which shows (1.28). The estimates for the derivatives (1.29) an (1.30) follow from (5.50), (5.51), (5.33), (5.34) and the above estimates to give

$$\partial_{\mathcal{X}} u = \partial_{a} u \partial_{b} \mathcal{Y} - \partial_{b} u \partial_{a} \mathcal{Y}
= -\mathbf{t}^{\frac{1}{2}} \partial_{b} \mathcal{Y}^{\Theta} + O\left(\mathbf{t}^{\frac{1}{2} + \frac{1}{12}} |\mathcal{X}|^{-\frac{2}{3} + \frac{1}{18}}\right) \left(1 + O\left(\frac{1}{|\hat{y}|^{\frac{1}{3}}}\right)\right) + O\left(\mathbf{t}^{\frac{3}{4}} |\mathcal{X}|^{-\frac{1}{2}}\right)
= \mathbf{t}^{\frac{1}{2}} \partial_{\mathcal{X}} \Theta_{\mu,\nu,\iota} + O\left(\mathbf{t}^{\frac{3}{2}} |x|^{-\frac{2}{3} + \frac{1}{18}}\right)$$

$$\partial_{\mathcal{Y}} u = -\partial_{a} u \partial_{b} \mathcal{X} + \partial_{b} u \partial_{a} \mathcal{X} = \mathbf{t}^{\frac{1}{2}} \partial_{b} \mathcal{X}^{\Theta} + O\left(\mathbf{t}^{\frac{3}{4}} |\mathcal{X}|^{\frac{2}{3}}\right) + O\left(\mathbf{t}^{\frac{3}{4}} |\mathcal{X}|^{\frac{2}{3}}\right)
= \mathbf{t}^{\frac{1}{2}} \partial_{\mathcal{Y}} \Theta_{\mu,\nu,\iota} + O\left(\mathbf{t}^{-\frac{1}{4}} |x|^{\frac{1}{2} + \frac{1}{6}}\right)$$
(5.72)

Step 4 End of the proof of (1.28), (1.29) and (1.30). These stability estimates concerning the self-similar zone and the bottom, are direct consequences of Step 1, 2, and 3, upon choosing first the parameter κ_{bo} and K_{bo} , then κ_{si} and M_{si} , and finally M_{co} , and then taking δ small and ϵ small, to ensure the zones overlap and any point (\hat{x}, \hat{y}) belongs to at least one zone.

Step 5 The displacement line, proof of (1.27). We invest here the properties of y^* defined by (5.38). The analogue of (B.14) adapts, namely,

$$y^*(x) = k_6^{-1} \frac{\mathcal{Y}^{\Theta}(a_{out}, b_{out})}{\mathsf{t}^{\frac{1}{4}}} \left(1 + O\left(\mathsf{t}^{\frac{1}{12}} + |\mathcal{X}|^{\frac{1}{18}} \mathsf{t}^{\frac{1}{12}} \right) \right).$$

By definition, as $b_{out} = \delta t^{-3/4}$,

$$\mathcal{Y}^{\Theta}(a_{out}, b_{out}) = \int_{-\infty}^{\delta t^{-3/4}} \frac{\mathrm{d}\tilde{b}}{1 + 3\Psi_1^2 \left(p^* \left(\mathfrak{X} - \tilde{b}^2\right)\right)} = 2\mathcal{Y}^*(\mathfrak{X}) + O\left(t^{\frac{1}{4}}\right),$$

as for $b \ge \delta t^{-3/4}$ it holds that $|\mathfrak{X}| \ll b$ for ϵ small enough, so that $\Psi_1^2 \left(p^* \left(\mathfrak{X} - \tilde{b}^2 \right) \right) \approx b^{4/3}$ from (3.14). Therefore, from (5.4),

$$y^{*}(x) = k_{6}^{-1} \frac{2\mathcal{Y}^{*}\left(\frac{k_{5}(x-x^{*})}{\mathsf{t}^{\frac{3}{2}}}\right)}{\mathsf{t}^{\frac{1}{4}}} \left(1 + O\left(\mathsf{t}^{\frac{1}{12}} + |x|^{\frac{1}{18}}\right)\right)$$
$$= \frac{2\mathcal{Y}^{*}_{\mu,\nu,\iota}\left(\frac{x-x^{*}}{\mathsf{t}^{\frac{3}{2}}}\right)}{\mathsf{t}^{\frac{1}{4}}} \left(1 + O\left(\mathsf{t}^{\frac{1}{12}} + |x|^{\frac{1}{18}}\right)\right).$$

This shows (1.27).

Step 6 Reconnection functions: proof of (1.33). The reconnection functions f and g are defined the following way. Fix f = f, and consider the curve f := f = f

from the boundary of the upper half plane to (X_0, Y_0) , and Γ_{top} which is the top part from (X_0, Y_0) and beyond. We change variables, using (5.3), to get

$$\begin{pmatrix} A \\ B \end{pmatrix} = \begin{pmatrix} k_1 & k_2 \\ -k_3 & k_4 \end{pmatrix} \begin{pmatrix} X - X_0 \\ Y - Y_0 \end{pmatrix},$$

so that from the Taylor expansion of x (5.17), for |A|, $|B| \ll 1$,

$$x(T, X, Y) = x^*(T) + p^{*2}A^3 + B^2 + O(|A|^4 + |A||B|^2 + |B|^3),$$

which extends naturally to higher order derivatives. Therefore, near (X_0, Y_0) , on Γ one has that

$$A = -\frac{1}{p^{*\frac{2}{3}}} B^{\frac{2}{3}} \left(1 + O\left(|B|^{\frac{2}{3}}\right) \right). \tag{5.73}$$

Denote by $(X_0^*, 0)$ the point of the boundary such that $x(T, X_0^*, 0) = x^*(T)$, by (X_{in}, Y_{in}) that for which $B = -\delta$, and by (X_{out}, Y_{out}) that for which $B = \delta$. On Γ_{bot} for $|B| \ll 1$ and B < 0 we compute y using (A.1) and split to get

$$y = \int_{\Gamma_{(X_0^*,0)}^{(X_1,Y_1)}} \frac{\mathrm{d}s}{|\nabla x(T)|} + k_6^{-1} \int_{-\delta}^{B} \frac{\mathrm{d}\tilde{B}}{\partial_A x}$$

$$= O(1) + \frac{1}{k_6 3 p^{*\frac{2}{3}}} \int_{-\delta}^{B} \frac{\left(1 + O\left(|\tilde{B}|^{\frac{2}{3}}\right)\right) d\tilde{B}}{\tilde{B}^{\frac{4}{3}}}$$

$$= O(1) - \frac{1}{k_6 p^{*\frac{2}{3}}} \frac{1}{B^{\frac{1}{3}}}.$$

This shows that $y \to \infty$ as (X, Y) approaches (X_0, Y_0) on Γ_b . Given any $y \ge 0$, there thus exists a unique point $\phi(y)$ on Γ_b between the boundary of \mathcal{H} and (X_0, Y_0) such that y(X, Y) = y and we define can

$$f(y) = u(T, \phi(y)).$$

From the above expansion for y one obtains, writing $\phi(y)$ in (A, B) variables, that

$$B(\phi(y)) \sim -\frac{1}{y^3 k_6^3 p^{*2}}$$
 as $y \to \infty$,

which, from (5.49), (5.73) and (5.6), gives,

$$f(y) - u^* = u(T, \phi(y)) - u^* \sim \frac{-u_X \overline{k}_1}{v^2 k_e^2 p^{*2}} = \frac{1}{v^2} \frac{\mu v^2}{p^{*2}} \text{ as } y \to \infty,$$

and the first part of (1.33) is proved. For $(X, Y) \in \Gamma_{top}$, we define

$$\tilde{y}(X,Y) = \int_{\Gamma_{(X,Out,Y_{out})}^{(X,Y)}} \frac{\mathrm{d}s}{|\nabla x[T]|},$$

where this integral is taken with positive sign if (X, Y) is after (A_{out}, B_{out}) on Γ , and with negative sign if it is between (A_{out}, B_{out}) and (X_0, Y_0) . It follows from (5.73) that

$$\tilde{y}(A_{out}, B_{out}) = 0, \quad \lim_{(X,Y) \in \Gamma_{top}, \ |(X,Y)| \to \infty} \tilde{y}(X,Y) = \infty,$$

$$\tilde{y} \sim -\frac{1}{k_6 p^{*\frac{2}{3}}} \frac{1}{B^{\frac{1}{3}}} \text{ as } B \to 0^{+}.$$

Hence $(X, Y) \mapsto \tilde{y}$ defines a C^3 diffeomorphism between Γ_{top} and \mathbb{R} . Given any $\tilde{y} \in \mathbb{R}$, there exists a unique point $\tilde{\phi}(\tilde{y})$ on Γ_{top} such that $\tilde{y}(\tilde{\phi}(\tilde{y})) = \tilde{y}$ and we thus define

$$g(\tilde{y}) = u(T, \tilde{\phi}(\tilde{y})). \tag{5.74}$$

From (5.49) and (5.73) one obtains

$$g(\tilde{y}) - u^* \sim \frac{-u_X \overline{k}_1}{y^2 k_6^2 p^{*2}} = \frac{1}{y^2} \frac{\mu v^2}{p^{*2}} \text{ as } y \to -\infty.$$

Denoting by $X^E \mapsto x^E$ the Lagrangian to Eulerian map of the Bernouilli equation (1.2) (with $\dot{x}^E = u^E(t, x^E)$ and $x^E(0, X^E) = X^E$) then, at time T, $x^E[T]$ is a diffeomorphism since (u^E, p^E) is a globally regular solution of (1.2). From the second equation in (1.1), we get that for $\tilde{y} \to \infty$, $X(\tilde{\phi}(\tilde{y})) \to X^E(T, x^*(T))$. Hence $g(\tilde{y}) \to u^E(x^*(T))$ as $\tilde{y} \to \infty$. This and the above equation proves the second identity in (1.33).

Step 7 Reconnection: proof of (1.34) in \mathfrak{Z}_{be} , (1.35) in \mathfrak{Z}_{ab} , (1.31) and (1.32) in \mathfrak{Z}_{to} . For any $K_{bo} > 0$, as $(t, x) \to (T, x^*)$, the characteristics map $(X, Y) \mapsto (x, y)$ still defines a diffeomorphism when restricted to the preimage of $y < K_{bo}$, since it avoids a size one zone near (X_0, Y_0) . Hence the convergence of u to f in Z_{be} follows from a direct continuity argument. This shows the reconnection at the bottom (1.34).

We now turn to the reconnection at the top. For any $K_{to} > 0$, the zone $y^* - K_{to} \le y \le y^* + K_{to}$ corresponds in Lagrangian variable to a zone which stays at a distance 1 away from (X_0, Y_0) , and hence where the parametrisation of the curves $\Gamma := \{x(X, Y) = Cte\}$ and ∇x remain uniformly regular as $t \to T$. From this fact and the definition (5.38) of y^* , as $(x, t) \to (T, x^*)$, the inverse of the characteristics map $(x, y) \mapsto (X, Y)$ is such that

$$(X, Y)(x, y) \rightarrow \tilde{\phi}(y - y^*)$$

where $\tilde{\phi}$ is defined by (5.74). Hence from (5.74) one has $u(t, X, Y) \to g(y - y^*(x))$ in this zone which proves (1.35) for $y^* - K_{to} \leq y \leq y^* + K_{to}$. For $y \geq y^* + K_{to}$, we have that $X \to X^E(T, x^*(T))$ where X^E is defined in Step 6, and $Y \to \infty$, uniformly as $K_{to} \to \infty$ for $|x - x^*| \leq \epsilon$. Thus $u(t, x, y) \to u^E(T, x^*(T))$ uniformly. This proves (1.35) for $y \geq y^* + K_{to}$ since $g(\tilde{y}) \to u^E(T, x^*(T))$ for $\tilde{y} \to \infty$. Hence (1.35) is proved.

We now turn to the convergence in the top part of the self-similar zone Z_{to} . Let $K_{to} \gg 1$ be large, and then $0 < \kappa_{to}$, $\epsilon \ll 1$ be small, and consider $(\hat{x}, \hat{y}) \in \mathcal{Z}_{to}$, corresponding to

$$|\hat{\mathcal{X}}| \leq k_5 \epsilon \mathsf{t}^{-\frac{3}{2}}, \ k_6 \mathsf{t}^{\frac{1}{4}} y^*(t, x) (1 - \kappa_{to}) \leq \hat{\mathcal{Y}} \leq k_6 \mathsf{t}^{\frac{1}{4}} (y^*(x) - K_{to}), \ (5.75)$$

Define \overline{b} as follows

$$\overline{b} = M\left(1 + |\hat{\mathcal{X}}|^{\frac{1}{2}}\right).$$

Here, $M\gg 1$ will be chosen later on. One has for ϵ small enough depending on δ that $|\overline{b}|\gg |\hat{\mathfrak{X}}|^{1/2}$. We now look for the solution \overline{a} to $\mathfrak{X}(\overline{a},\overline{b})=\hat{\mathfrak{X}}$. In the zone a<0 with $|a|\approx |\overline{b}|^{2/3}$ one is in Z_1 and therefore from (5.20) one has $\partial_a\mathfrak{X}\approx |\overline{b}|^{4/3}$. Hence, as $|\mathfrak{X}|\ll |b|^2$ this condition on the derivative via the intermediate value Theorem implies that there exists $\overline{a}<0$ with $|\overline{a}|\approx |\overline{b}|^{2/3}$ such that $\mathfrak{X}(\overline{a},\overline{b})=\hat{\mathfrak{X}}$. From Lemma 5.3, the curve $\Gamma[\hat{x}]$, before leaving Z_0^c by the point (a_{out},b_{out}) , is in Z_1 where it can be parametrised with the variable \widetilde{b} as $\widetilde{a}=\widetilde{a}(\mathfrak{X},\widetilde{b})$. Either in case (i) of Lemma 5.3 it always stayed in Z_1 , or in case (ii) before that stage the curve was in Z_2 .

As $(\overline{a}, \overline{b})$ belongs to Z_1 , this means that in any case, one can parametrise with the variable \tilde{b} the last part of Γ before exiting Z_0^c , as a curve $\tilde{a} = \tilde{a}(\mathfrak{X}, \tilde{b})$ for $\overline{b} \leq \tilde{b} \leq \delta t^{3/4}$. For (a, b) along this curve it holds, by definition of y^* (5.38), that

$$\mathfrak{X}(a,b) = \hat{\mathfrak{X}}, \quad \mathcal{Y}(a,b) = k_6 \mathsf{t}^{\frac{1}{4}} y^*(\hat{x}) - \int_b^{\frac{\delta}{\mathfrak{t}^{3/4}}} \frac{\mathrm{d}\tilde{b}}{\partial_a \mathfrak{X}(\tilde{a}(\hat{\mathfrak{X}},b),\tilde{b})}.$$

As this curve lies in Z_1 from (5.20), and from the inequality $|\hat{\mathcal{X}}| \ll |\tilde{b}|$ for $b \leq \delta t^{-3/4}$,

$$\mathcal{Y}(a,b) = k_6 \mathsf{t}^{\frac{1}{4}} y^*(\hat{x}) - \int_b^{\frac{\delta}{\mathfrak{t}^{\frac{3}{4}}}} \frac{\mathrm{d}\tilde{b}}{1 + 3\Psi_1^2 \left(p^*(\hat{\mathcal{X}} - \tilde{b}^2) \right)} \left(1 + O\left(|\tilde{b}|^{\frac{1}{9}} \mathsf{t}^{\frac{1}{12}} \right) \right).$$

An expansion at infinity of Ψ_1 gives that

$$\frac{1}{1+3\Psi_1^2\left(p^*(\hat{\mathcal{X}}-\tilde{b}^2)\right)}\left(1+O\left(|\tilde{b}|^{\frac{1}{9}}\mathsf{t}^{\frac{1}{12}}\right)\right)=\frac{1}{p^{*\frac{2}{3}}3\tilde{b}^{\frac{4}{3}}}+O\left(\frac{\mathsf{t}^{\frac{1}{12}}|\tilde{b}|^{\frac{1}{9}}}{|\tilde{b}|^{\frac{4}{3}}}+\frac{|\hat{\mathcal{X}}||\tilde{b}|^{-2}}{|\tilde{b}|^{\frac{4}{3}}}\right),$$

so that

$$\mathcal{Y}(a,b) = k_6 \mathbf{t}^{\frac{1}{4}} y^*(t,\hat{x}) - \frac{k_6}{p^{*\frac{2}{3}} b^{\frac{1}{3}}} + O\left(|b|^{-\frac{1}{3} + \frac{1}{9}} \mathbf{t}^{\frac{1}{12}} + |b|^{-\frac{1}{3} - 2} |\hat{\mathcal{X}}|\right).$$

We write $\mathcal{Y} = k_6 t^{1/4} y^*(t, \hat{x}) - \Delta \mathcal{Y}$, and from (5.75) and (1.27),

$$k_6 t^{\frac{1}{4}} K \leq \Delta \mathcal{Y} \leq \frac{k_6 \kappa}{1 + |\hat{\mathcal{X}}|^{\frac{1}{6}}}.$$

Solving $\mathcal{Y}(a, b) = \mathcal{Y}$ then amounts to solving

$$-\frac{1}{p^{*\frac{2}{3}}b^{\frac{1}{3}}} + O\left(|b|^{-\frac{1}{3} + \frac{1}{9}}\mathsf{t}^{\frac{1}{12}} + |b|^{-\frac{1}{3} - 2}|\hat{\mathcal{X}}|\right) = -\Delta \mathcal{Y}.$$

For $b = \delta \mathsf{t}^{-3/4}$ one has $b^{-1/3} \gtrsim \mathsf{t}^{1/4} \delta^{-1/3} \gg \mathsf{t}^{\frac{1}{4}} K_{to}$ for δ small enough, and for $b = \bar{b}$ one has $\bar{b}^{-1/3} \gtrsim M^{-1/3} (1 + |\mathfrak{X}|^{1/6})^{-1} \gg \kappa_{to} (1 + |\mathfrak{X}|^{1/6})^{-1}$ for M large enough. Hence, there exists indeed a solution (\hat{a}, \hat{b}) to the above equation by the intermediate value Theorem, and bootstrapping information from the above equation and using that $|\hat{\mathfrak{X}}| \approx |\hat{b}|^2$ one obtains

$$\hat{b} = \frac{1}{p^{*2}k_6^3 \left(y^*(t,\hat{x}) - \hat{y}\right)^3 t^{\frac{3}{4}}} \left(1 + O\left(\frac{1}{(y^*(\hat{x}) - \hat{y})^{\frac{1}{3}}}\right)\right).$$
 (5.76)

Bootstrapping information from the equation (5.12) gives, finally that

$$\begin{split} \hat{a} &= -p^{*-\frac{2}{3}} \hat{b}^{\frac{2}{3}} \left(1 + O\left(\frac{|\hat{\mathcal{X}}|}{\hat{b}^{2}} + \mathsf{t}^{\frac{1}{12}} | \hat{b} |^{\frac{1}{9}} \right) \right) \\ &= -\frac{1}{k_{6}^{2} p^{*2} (y^{*}(t, \hat{x}) - \hat{y})^{2} \mathsf{t}^{\frac{1}{2}}} \left(1 + O\left(\frac{|\hat{y} - y^{*}(t, \hat{x})|}{y^{*}(t, \hat{x})} + \frac{1}{(\hat{y} - y^{*}(t, \hat{x}))^{\frac{1}{4}}} \right) \right). \end{split}$$

Hence, from (5.49) and (5.6),

$$u(t, \hat{x}, \hat{y}) - u^*(t) = \frac{\mu v^2}{p^{*2} (y^*(t, \hat{x}) - \hat{y})^2} \left(1 + O\left(\frac{|\hat{y} - y^*|}{y^*} + \frac{1}{(\hat{y} - y^*)^{\frac{1}{4}}}\right) \right).$$

The estimates for the derivative proved in Lemma 5.4 adapt, namely at the point (\hat{a}, \hat{b}) , such that $(x, y)(\hat{a}, \hat{b}) = (\hat{x}, \hat{y})$, using (5.76)

$$\begin{split} &\partial_{a}\mathcal{X} = 1 + 3p^{*2}\hat{a}^{2} + O(|\hat{b}|^{\frac{5}{3}}\mathsf{t}^{\frac{1}{4}}) = \partial_{a}\mathcal{X}^{\Theta} + O\left(\frac{(y^{*} - \hat{y})}{(y^{*} - \hat{y})^{4}\mathsf{t}}\right), \\ &\partial_{b}\mathcal{X} = 2b + O(\mathsf{t}^{\frac{1}{4}}|\hat{b}|^{\frac{4}{3}}) = \partial_{b}\mathcal{X}^{\Theta} + O\left(\frac{(y^{*} - \hat{y})^{-1}}{(y^{*} - \hat{y})^{3}\mathsf{t}^{\frac{3}{4}}}\right), \\ &\partial_{a}\mathcal{Y} = \partial_{a}\mathcal{Y}^{\Theta} + O(\mathsf{t}^{\frac{1}{12}}|\hat{b}|^{-1+\frac{1}{9}}) = \partial_{a}\mathcal{Y}^{\Theta} + O\left((y^{*} - \hat{y})^{3-\frac{1}{3}}\mathsf{t}^{\frac{3}{4}}\right), \\ &\partial_{b}\mathcal{Y} = \partial_{b}\mathcal{Y}^{\Theta} + O\left(|1 + |\hat{\mathcal{X}}||^{-\frac{7}{6}}|\hat{b}|^{1+\frac{1}{9}}\mathsf{t}^{\frac{1}{12}}\right) = \partial_{b}\mathcal{Y}^{\Theta} + O\left((y^{*} - \hat{y})^{4-\frac{1}{3}}\mathsf{t}\right), \end{split}$$

so that, from (5.50), (5.51), (5.33), (5.34), (iii) in Proposition 1 and the above estimates, we have

$$\begin{split} \partial_{\mathcal{X}} u &= \partial_{a} u \partial_{b} \mathcal{Y} - \partial_{b} u \partial_{a} \mathcal{Y} \\ &= -t^{\frac{1}{2}} (2 \partial_{b} \mathcal{Y}^{*} (\mathcal{X}^{\Theta}) + \partial_{b} (2 \mathcal{Y}^{*} (\mathcal{X}^{\Theta}) - \partial_{b} \mathcal{Y}^{\Theta})) \\ &+ O\left(t^{\frac{3}{2}} |t^{\frac{3}{2}} + |\hat{x} - x^{*}||^{-\frac{7}{6}} |y^{*} - \hat{y}|^{-3 - \frac{1}{3}}\right) \\ &= -t^{\frac{1}{2}} 4b \partial_{\mathcal{X}} \mathcal{Y}^{*} + O(t^{-\frac{1}{4}} |y - y^{*}|^{4}) \\ &+ O\left(t^{\frac{3}{2}} |t^{\frac{3}{2}} + |\hat{x} - x^{*}||^{-\frac{7}{6}} |y^{*} - \hat{y}|^{-3 - \frac{1}{3}}\right), \\ \partial_{\mathcal{Y}} u &= -\partial_{a} u \partial_{b} \mathcal{X} + \partial_{b} u \partial_{a} \mathcal{X} = -\frac{1}{t^{\frac{1}{4}} p^{*2} k_{6}^{3} (y^{*} - y)^{3}} + O\left(\frac{(y^{*} - \hat{y})}{(y^{*} - \hat{y})^{3} t^{\frac{1}{4}}}\right), \end{split}$$

which, using (5.6), completes the proof of (1.32). \Box

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A. Parametrisation and volume preservation

Lemma A.1. Let $\Omega \subset \mathbb{R}^2$ be open, and $f = (f_1, f_2) \in C^1(\Omega, \mathbb{R}^2)$ be such that $\nabla f_1 \neq 0$ on Ω , and that for each q in the range of f_1 , the level set $\Gamma[q] = \{z \in \Omega, f_1(z) = q\}$ is diffeomorphic to \mathbb{R} . Then

(i) Let $\gamma: \mathfrak{G} \to \Omega$ be a diffeomorphism between an open set $\mathfrak{G} \subset \mathbb{R}^2$ and Ω , such that for each $q \in \mathbb{R}$, $\gamma(q, \cdot)$ is an arclength parametrisation of $\Gamma[q]$. Then f preserves volume if and only if for all q in the range of f_1 , and any two $z = \gamma(q, s)$ and $z' = \gamma(q, s')$ it holds that

$$|f_2(z) - f_2(z')| = \left| \int_s^{s'} \frac{\mathrm{d}\tilde{s}}{|\nabla f_1(\gamma(q,\tilde{s}))|} \right|. \tag{A.1}$$

(ii) If $\partial_{z_1} f_1 \neq 0$ on Ω , let $\tilde{z}_1 : \mathfrak{G} \to \Omega$ be the only diffeomorphism between an open set $\mathfrak{G} \subset \mathbb{R}^2$ and Ω , such that for each $q \in \mathbb{R}$, $\tilde{z}_1(q, \cdot)$ is the parametrisation of $\Gamma[q]$ by the second component, i.e. $\Gamma[q] = \{(\tilde{z}_1(q, \tilde{z}_2), \tilde{z}_2), (q, \tilde{z}_2) \in \mathfrak{G}\}$,

then f preserves volume if and only if, for all q in the range of f_1 , and any two $z = (\tilde{z}_1(q, z_2), z_2)$ and $z' = (\tilde{z}_1(q, z_2'), z_2')$,

$$|f_2(z) - f_2(z')| = \left| \int_{z_2}^{z'_2} \frac{d\tilde{z_2}}{\partial_{z_1} f_1(\tilde{z}_1(q, \tilde{z}_2), \tilde{z}_2)} \right|.$$
 (A.2)

Proof. Proof of (i). We denote by $\gamma^{-1} = (q, s) : \Omega \to \emptyset$ the inverse of γ , and note that $q = f_1$. At a point $z \in \Omega$, considering the orthonormal vectors $v_1 = \nabla f_1(z) |\nabla f_1(z)|^{-1}$ and $v_2 = \nabla^{\perp} f_1(z) |\nabla f_1(z)|^{-1}$ where $(e_1, e_2)^{\perp} = (-e_2, e_1)$ we get the identities $\nabla q.v_1 = |\nabla f_1(z)|$, $\nabla q.v_2 = 0$ and $\nabla s.v_2 = 1$. This implies $|\text{Det}(J\gamma^{-1})| = |\nabla f_1(z)|$. Consider now the mapping $\phi: (q, s) \mapsto (q, f_2(\gamma(q, s)))$. Since $\frac{\partial q}{\partial s}|_q = 0$ and $\frac{\partial q}{\partial q}|_s = 1$ we have $|\text{Det}(J\phi)| = |\frac{\partial f_2}{\partial s}|_q$. Since $f = \phi \circ \gamma^{-1}$, we get from the two previous computations that f preserves volume, that is, |DetJf| = 1, if and only if

$$\left|\frac{\partial f_2}{\partial s}\right|_a = \frac{1}{\left|\nabla f_1(z)\right|}.$$

This is equivalent to (i) upon integrating, and noticing that these quantities cannot change sign.

Proof of (ii). From the assumptions on f, there always exists a parametrisation by arclength of the level sets $\gamma: \mathbb{G}' \to \Omega$ satisfying the properties of (i). We change variables $\tilde{z}_1^{-1} \circ \gamma: (q,s) \mapsto (q,\tilde{z}_2)$. Differentiating the identity $f_1(\tilde{z}_1(q,\tilde{z}_2),\tilde{z}_2) = q$ we find $\frac{\partial \tilde{z}_1}{\partial \tilde{z}_2}|_{q} = -\partial_{z_2} f_1/\partial_{z_1} f_1$. Hence

$$\left|\frac{\partial s}{\partial \tilde{z}_2}\right|_q = \sqrt{1 + \left(\frac{\partial_{z_2} f_1}{\partial_{z_1} f_1}\right)^2} = \frac{|\nabla f_1|}{|\partial_{z_1} f_1|}.$$

Changing variables $s \mapsto \tilde{z}_2$ in (A.1), then yields that f preserves volume if and only if (A.2) holds true. \square

B. Computing the normal component of the characteristics

proof of Lemma 5.4. At several moments in the proof, we will use the following: the function Ψ_1 enjoys

$$c < \left| \frac{X \partial_X \Psi_1(X)}{\Psi_1(X)} \right| \le \frac{1}{c}, \quad |\Psi_1(X)| \lesssim |X|^{\frac{1}{3}},$$

$$\Psi_1(X + X') = \Psi_1(X) + O\left(|X'|^{\frac{1}{3}}\right) \tag{B.1}$$

uniformly for $X, X' \in \mathbb{R}$. From the first bound above, given a small quantity O(|z|) that has size |z|, as an application of the implicit function theorem, it is true that

$$\Psi_1(X(1+O(|z|))) = \Psi_1(X)(1+O(|z|)), \tag{B.2}$$

where the "new" O(|z|) in the right hand side enjoys the same differentiability properties and similar bounds, as the one in the left hand side. To rearrange the O()'s in what follows, we shall simplify $O(|z_1|) + O(|z_2|) = O(|z_2|)$ in zones where $|z_1| \lesssim |z_2|$, and $O(|z|^{\alpha}) = O(|z|^{\beta})$ if $0 < \beta \le \alpha$ as all quantities in the O()'s will be small.

To compute the vertical component, we will use the following result. Assume that (a,b) and (a',b') belong to the same level set curve $\Gamma[x]=\{x(\tilde{a},\tilde{b})=x\}$. Assume that, when ordering points on Γ with their distance to the boundary, (a',b') is after (a,b), and that either $b \leq b'$ or $a \leq a'$. Assume moreover that $\Gamma_{(a,b)}^{(a',b')}$, the part of Γ between (a,b) and (a',b'), can be either parametrised with the variable \tilde{b} as $\tilde{a}=\tilde{a}(\mathfrak{X},\tilde{b})$ for $b\leq \tilde{b}\leq b'$ or with the variable \tilde{a} as $\tilde{b}=\tilde{b}(\mathfrak{X},\tilde{a})$ for $a\leq \tilde{a}\leq a'$. Then by applying Lemma A.1 and (5.5) one obtains the following identities:

$$\int_{\Gamma_{(a,b)}^{(a',b')}} \frac{\mathrm{d}s}{|\nabla x|} = \frac{1}{k_6 t^{\frac{1}{4}}} \int_b^{b'} \frac{\mathrm{d}\tilde{b}}{|\partial_a \mathfrak{X}|} \text{ or } \int_{\Gamma_{(a,b)}^{(a',b')}} \frac{\mathrm{d}s}{|\nabla x|} = \frac{1}{k_6 t^{\frac{1}{4}}} \int_a^{a'} \frac{\mathrm{d}\tilde{b}}{|\partial_b \mathfrak{X}|}.$$
(B.3)

Step 1 The normal component for left part of the sides, the core, and the bottom, of the self-similar zone. We first derive rough estimates that will be used in the next steps. Fix $(X, Y) \in Z_0^c$ such that either $-\epsilon \le x(a, b) - x^* \le Kt^{3/2}$, or, $Kt^{3/2} \le x - x^* \le \epsilon$ and b < 0 and $N_2|\mathcal{X}| \le |b|^2$. Note that in the second case, from (5.11), one has necessarily $|a| \approx |b|^{2/3} \gg 1$. Let Γ denote the part of the curve $\Gamma[x]$ which joins the boundary of the upper half plane and (X, Y). We decompose it in two parts:

$$\Gamma_1 := \Gamma \cap Z_0, \quad \Gamma_2 = \Gamma \cap Z_0^c, \quad \mathcal{Y} = k_6 t^{\frac{1}{4}} \left(\int_{\Gamma_1} \frac{\mathrm{d}s}{|\nabla x|} + \int_{\Gamma_2} \frac{\mathrm{d}s}{|\nabla x|} \right). \quad (B.4)$$

The integral in Z_0 is at distance one to (X_0, Y_0) , and everything then remains regular:

$$\int_{\Gamma_1} \frac{\mathrm{d}s}{|\nabla x|} = O(1), \ \partial_{\mathcal{X}} \left(\int_{\Gamma_1} \frac{\mathrm{d}s}{|\nabla x|} \right) = O\left(\mathsf{t}^{\frac{3}{2}}\right). \tag{B.5}$$

In Z_0^c , from Lemma 5.3 the curve $\Gamma[x]$ lies in Z_1 , so it can be parametrised with the variable \tilde{b} . Also, from (B.3), (5.20) and, as $|\tilde{b}| t^{3/4} \ll 1$ for $-\delta t^{-3/4} \leq \tilde{b} \leq b$,

$$k_{6}t^{\frac{1}{4}}\int_{\Gamma_{2}} \frac{ds}{|\nabla x|} = \int_{-\frac{\delta}{t^{-\frac{3}{4}}}}^{b} \frac{d\tilde{b}}{\partial_{a}\mathcal{X}} = \int_{-\frac{\delta}{t^{-\frac{3}{4}}}}^{b} \frac{1 + O\left(t^{\frac{1}{12}} + |\tilde{b}|^{\frac{1}{3}}t^{\frac{1}{4}} + |\mathcal{X}|^{\frac{1}{6}}t^{\frac{1}{4}}\right)}{1 + 3\Psi_{1}^{2}(p^{*}(\mathcal{X} - \tilde{b}^{2}))} d\tilde{b}$$

$$= \int_{-\infty}^{b} \frac{1 + O\left(t^{\frac{1}{12}} + |\tilde{b}|^{\frac{1}{4}}t^{\frac{3}{16}} + |\mathcal{X}|^{\frac{1}{6}}t^{\frac{1}{4}}\right)}{1 + 3\Psi_{1}^{2}(p^{*}(\mathcal{X} - \tilde{b}^{2}))} d\tilde{b} + O\left(\int_{-\infty}^{-\frac{\delta}{t^{-\frac{3}{4}}}} \frac{d\tilde{b}}{|\tilde{b}|^{\frac{4}{3}}}\right)$$

$$= \int_{-\infty}^{b} \frac{1 + O\left(t^{\frac{1}{12}} + |\tilde{b}|^{\frac{1}{4}}t^{\frac{3}{16}} + |\mathcal{X}|^{\frac{1}{6}}t^{\frac{1}{4}}\right)}{1 + 3\Psi_{1}^{2}(p^{*}(\mathcal{X} - \tilde{b}^{2}))} d\tilde{b} + O\left(t^{\frac{1}{4}}\right), \quad (B.6)$$

where we used the fact that $|\mathfrak{X}| \leq \epsilon t^{-3/2}$, and that for $\tilde{b} \leq -\delta t^{-3/4}$, $\tilde{b}^2 \gg \mathfrak{X}$ if ϵ is small enough, implying $\Psi_1^2(p^*(\mathfrak{X}-\tilde{b}^2)) \approx |\tilde{b}|^{4/3}$. Hence, injecting (B.5) and (B.6) in (B.4),

$$\mathcal{Y}(a,b) = \int_{-\infty}^{b} \frac{1 + O\left(\mathsf{t}^{\frac{1}{12}} + |\tilde{b}|^{\frac{1}{4}} \mathsf{t}^{\frac{3}{16}} + |\mathcal{X}|^{\frac{1}{6}} \mathsf{t}^{\frac{1}{4}}\right)}{1 + 3\Psi_{1}^{2}(p^{*}(\mathcal{X} - \tilde{b}^{2}))} \mathsf{d}\tilde{b} + O\left(\mathsf{t}^{\frac{1}{4}}\right). \tag{B.7}$$

We now study the derivative of \mathcal{Y} . As $\mathfrak{X}(\tilde{a},\tilde{b})=\mathfrak{X}$ is inverted through $\tilde{a}=\tilde{a}(\mathfrak{X},\tilde{b})$ one has

$$\begin{split} \frac{\partial}{\partial \mathfrak{X}}_{|\tilde{b}}\left(\tilde{a}(\mathfrak{X},\tilde{b})\right) &= \frac{1}{\partial_{a}\mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b})}, \ \frac{\partial}{\partial \mathfrak{X}}_{|\tilde{b}}\left(\frac{1}{\partial_{a}\mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b})}\right) \\ &= -\frac{\partial_{aa}\mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b})}{(\partial_{a}\mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b}))^{3}} \end{split}$$

One deduces from (B.3), (5.20), (5.21) that

$$\begin{split} \frac{\partial}{\partial \mathfrak{X}|_{b}} \left(k_{6}\mathsf{t}^{\frac{1}{4}} \int_{\Gamma_{2}} \frac{\mathrm{d}s}{|\nabla x|} \right) &= \frac{\partial}{\partial \mathfrak{X}|_{b}} \left(\int_{-\frac{\delta}{13/4}}^{b} \frac{\mathrm{d}\tilde{b}}{\partial_{a} \mathfrak{X}(\tilde{a}(\mathfrak{X}, \tilde{b}), \tilde{b})} \right) \\ &= - \int_{-\frac{\delta}{13/4}}^{b} \frac{\partial_{aa} \mathfrak{X}(\tilde{a}, \tilde{b}) \mathrm{d}\tilde{b}}{(\partial_{a} \mathfrak{X}(\tilde{a}, \tilde{b}))^{3}} \\ &= 6p^{*} \int_{-\frac{\delta}{13/4}}^{b} \frac{\Psi_{1} \left(p^{*} \left(\mathfrak{X} - \tilde{b}^{2} \right) \right)}{\left(1 + 3\Psi_{1}^{2} \left(p^{*} (\mathfrak{X} - \tilde{b}^{2}) \right) \right)^{3}} \\ &\qquad \left(1 + O \left(\mathsf{t}^{\frac{1}{12}} + |\mathfrak{X}|^{\frac{1}{6}} \mathsf{t}^{\frac{1}{4}} + |\tilde{b}|^{\frac{1}{3}} \mathsf{t}^{\frac{1}{4}} \right) \right) \mathrm{d}\tilde{b}} \\ &\qquad + \int_{-\frac{\delta}{13/4}}^{b} \frac{O \left(\mathsf{t}^{\frac{1}{12}} \right)}{\left(1 + 3\Psi_{1}^{2} \left(p^{*} (\mathfrak{X} - \tilde{b}^{2}) \right) \right)^{3}} \mathrm{d}\tilde{b}. \end{split}$$

Note that in the integrals above, for $\tilde{b} \leq -\delta t^{-3/4}$ there holds $\Psi_1(p^*(\mathfrak{X} - \tilde{b}^2)) \gtrsim \tilde{b}^{2/3}$. Hence, integrating from infinity instead of $-\delta t^{-3/4}$ produces an error which is $O(t^{7/4})$ and

$$\frac{\partial}{\partial \mathcal{X}|_{b}} \left(k_{6} t^{\frac{1}{4}} \int_{\Gamma_{2}} \frac{ds}{|\nabla x|} \right) = 6p^{*} \int_{-\infty}^{b} \frac{\Psi_{1} \left(p^{*} \left(\mathcal{X} - \tilde{b}^{2} \right) \right)}{\left(1 + 3\Psi_{1}^{2} \left(p^{*} \left(\mathcal{X} - \tilde{b}^{2} \right) \right) \right)^{3}} \left(1 + O\left(t^{\frac{1}{12}} + |\mathcal{X}|^{\frac{1}{6}} t^{\frac{1}{4}} + |\tilde{b}|^{\frac{1}{4}} t^{\frac{3}{16}} \right) \right) d\tilde{b}
+ \int_{-\infty}^{b} \frac{O\left(t^{\frac{1}{12}} \right)}{\left(1 + 3\Psi_{1}^{2} \left(p^{*} \left(\mathcal{X} - \tilde{b}^{2} \right) \right) \right)^{3}} d\tilde{b} + O\left(t^{\frac{7}{4}} \right)$$

Therefore, injecting (5.20), (B.5) and the above identity in (B.4), we get

$$\begin{split} \partial_{a}\mathcal{Y}(a,b) &= \partial_{a}\mathfrak{X}\left(k_{6}\mathsf{t}^{\frac{1}{4}}\frac{\partial}{\partial\mathfrak{X}}\int_{\Gamma_{1}}\frac{\mathrm{d}s}{|\nabla x|} + \frac{\partial}{\partial\mathfrak{X}}_{|b}\left(k_{6}\mathsf{t}^{\frac{1}{4}}\int_{\Gamma_{2}}\frac{\mathrm{d}s}{|\nabla x|}\right)\right) \\ &= \partial_{a}\mathfrak{X}\left(6p^{*}\int_{-\infty}^{b}\frac{\Psi_{1}\left(p^{*}\left(\mathfrak{X}-\tilde{b}^{2}\right)\right)}{\left(1+3\Psi_{1}^{2}\left(p^{*}(\mathfrak{X}-\tilde{b}^{2})\right)\right)^{3}} \\ & \left(1+O\left(\mathsf{t}^{\frac{1}{12}}+|\mathfrak{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}}+|\tilde{b}|^{\frac{1}{4}}\mathsf{t}^{\frac{3}{16}}\right)\right)\mathrm{d}\tilde{b} \\ &+ \int_{-\infty}^{b}\frac{O\left(\mathsf{t}^{\frac{1}{12}}\right)}{\left(1+3\Psi_{1}^{2}\left(p^{*}(\mathfrak{X}-\tilde{b}^{2})\right)\right)^{3}}\mathrm{d}\tilde{b}+O\left(\mathsf{t}^{\frac{7}{4}}\right)\right) \\ &= 6p^{*}\left(1+3\Psi_{1}^{2}\left(p^{*}(\mathfrak{X}-\tilde{b}^{2})\right)\right) \\ &\left(\int_{-\infty}^{b}\frac{O\left(\mathsf{t}^{\frac{1}{12}}\right)}{\left(1+3\Psi_{1}^{2}\left(p^{*}(\mathfrak{X}-\tilde{b}^{2})\right)\right)^{3}}\mathrm{d}\tilde{b}+O\left(\mathsf{t}^{\frac{7}{4}}\right) \\ &+ \int_{-\infty}^{b}\frac{\Psi_{1}\left(p^{*}\left(\mathfrak{X}-\tilde{b}^{2}\right)\right)}{\left(1+3\Psi_{1}^{2}\left(p^{*}(\mathfrak{X}-\tilde{b}^{2})\right)\right)^{3}} \\ &\left(1+O\left(\mathsf{t}^{\frac{1}{12}}+|\mathfrak{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}}+|\tilde{b}|^{\frac{1}{4}}\mathsf{t}^{\frac{3}{16}}+\mathsf{t}^{\frac{1}{4}}|b|^{\frac{1}{3}}\right)\right)\mathrm{d}\tilde{b}\right). \quad (B.8) \end{split}$$

The estimates (5.27) and (5.28), and (1.17), prove (5.27) and (5.28) for the first case.

Step 2 The normal component for the sides of the self-similar zone. We now prove the estimates (5.30) and (5.31) in the second case described by (5.29). The parametrisation of the curve $\Gamma[x]$ has to be done more carefully. In the case of the left side, i.e. x < 0, we are in the case considered in Step 1, which has already been covered. In the case of the right side, i.e. x > 0, we are in case (ii) of Lemma 5.3, and then inside Z_0^c , the curve Γ can be decomposed in five curves, Γ_i for i = 1, ..., 5 that enjoy the properties described there. We use different variables to parametrise the curves Γ_i , applying Lemma 5.3. On Γ_1 we use the variable \tilde{b} , on Γ_2 \tilde{a} , on Γ_3 \tilde{b} , on Γ_4 \tilde{a} and on Γ_5 \tilde{b} . Without loss of generality for the argument, we assume that (\bar{a}, \bar{b}) is located on Γ_2 . Indeed, treating the case of three or more different parametrisation can be done the very same way. We consider a point (a, b) close to (\bar{a}, \bar{b}) , which still belongs to Γ_2 (up to changing slightly the constants in the definition of Z_1 and Z_2). We denote by Γ_0 the part of the curve outside Z_0^c . Hence, from (B.3),

$$\mathcal{Y} = k_6 t^{\frac{1}{4}} \int_{\Gamma_0} \frac{\mathrm{d}s}{|\nabla x|} + \int_{-\frac{\delta}{13/4}}^{b_1} \frac{\mathrm{d}\tilde{b}}{\partial_a \mathcal{X}} + \int_{a_1}^a \frac{\mathrm{d}\tilde{a}}{\partial_b \mathcal{X}}, \tag{B.9}$$

where we recall that (a_1, b_1) is the endpoint of Γ_1 and the starting point of Γ_2 , defined in Lemma 5.3. The integral over Γ_0 is at distance one to (X_0, Y_0) and hence, in a zone where everything remains regular,

$$\int_{\Gamma_0} \frac{\mathrm{d}s}{|\nabla x|} = O(1), \ \partial_{\mathcal{X}} \left(\int_{\Gamma_0} \frac{\mathrm{d}s}{|\nabla x|} \right) = O\left(\mathsf{t}^{\frac{3}{2}}\right). \tag{B.10}$$

We now consider the second integral, corresponding to the part Γ_1 of the curve joining the points $(a_{in}, -\delta t^{-3/4})$ and (a_1, b_1) . Since this part is in Z_1 , one obtains from (5.20), injecting (5.67), that

$$\int_{-\frac{\delta}{t^{3/4}}}^{b_1} \frac{d\tilde{b}}{\partial_a \mathfrak{X}} = \int_{-\frac{\delta}{t^{3/4}}}^{b_1} \frac{d\tilde{b}}{1 + 3\Psi_1^2(p^*(\mathfrak{X} - \tilde{b}^2))} \left(1 + O\left(t^{\frac{1}{12}}|\mathfrak{X}|^{\frac{1}{18}} + t^{\frac{1}{12}}|\tilde{b}|^{\frac{1}{9}}\right)\right)$$
(B.11)

We turn to the third integral, corresponding to the part Γ_2 of the curve joining the points (a_1, b_1) and (a, b). There, since this part is in Z_2 , one obtains from (5.23) that

$$\int_{a_1}^{a} \frac{\mathrm{d}\tilde{a}}{\partial_b \mathfrak{X}} = \int_{a_1}^{a} \frac{\mathrm{d}\tilde{a}}{2\sqrt{\mathfrak{X} - \tilde{a} - p^{*2}\tilde{a}^3}} \left(1 + O\left(|\mathfrak{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}}\right) \right).$$

In Z_2 , one has from (5.10) that $|\tilde{a}| \ll |\tilde{b}|^{2/3}$ and $|\tilde{b}| \gg 1$, so that from (5.11) one has

$$\mathfrak{X} \approx |\tilde{b}|^2 \gg |\tilde{a}|^3$$
 and $\sqrt{\mathfrak{X} - \tilde{a} - p^{*2}\tilde{a}^3} \approx \mathfrak{X}^{1/2}$ (B.12)

uniformly for \tilde{a} in Z_2 , as well as $|a_1|$, $|a| \ll \mathfrak{X}^{1/3}$. Using these bounds, one infers from the above identity that

$$\int_{a_{1}}^{a} \frac{d\tilde{a}}{\partial_{b} \mathfrak{X}} = \int_{a_{1}}^{a} \frac{d\tilde{a}}{2\sqrt{\mathfrak{X} - \tilde{a} - p^{*2}\tilde{a}^{3}}} + O\left(\frac{|a - a_{1}|}{|\mathfrak{X}|^{\frac{1}{6}}}|\mathfrak{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}}\right)$$
$$= \int_{a_{1}}^{a} \frac{d\tilde{a}}{2\sqrt{\mathfrak{X} - \tilde{a} - p^{*2}\tilde{a}^{3}}} + O\left(|\mathfrak{X}|^{-\frac{1}{6} + \frac{1}{6}}\mathsf{t}^{\frac{1}{4}}\right).$$

Also, from the identity (5.15), using the above bound (B.12),

$$\begin{vmatrix} a + \frac{1}{p^*} \Psi_1 \left(p^* \left(\mathfrak{X} - b^2 \right) \right) \Big| + \Big| a + \frac{1}{p^*} \Psi_1 \left(p^* \left(\mathfrak{X} - b^2 \right) \right) \Big| \lesssim |\mathfrak{X}|^{\frac{1}{3} + \frac{1}{18}} \mathsf{t}^{\frac{1}{12}},
\left| \int_a^{-\frac{1}{p^*} \Psi_1 \left(p^* (\mathfrak{X} - b^2) \right)} \frac{\mathrm{d}\tilde{a}}{\sqrt{\mathfrak{X} - \tilde{a} - p^{*2}\tilde{a}^3}} \right|
\lesssim \frac{\left| a + \frac{1}{p^*} \Psi_1 \left(p^* \left(\mathfrak{X} - b^2 \right) \right) \right|}{|\mathfrak{X}|^{\frac{1}{2}}} \lesssim |\mathfrak{X}|^{-\frac{1}{6} + \frac{1}{18}} \mathsf{t}^{\frac{1}{12}},
\left| \int_{a_1}^{-\frac{1}{p^*} \Psi_1 \left(p^* (\mathfrak{X} - 4b_1^2) \right)} \frac{\mathrm{d}\tilde{a}}{\sqrt{\mathfrak{X} - \tilde{a} - p^{*2}\tilde{a}^3}} \right|
\lesssim \frac{\left| a_1 + \frac{1}{p^*} \Psi_1 \left(p^* \left(\mathfrak{X} - 4b_1^2 \right) \right) \right|}{|\mathfrak{X}|^{\frac{1}{2}}} \lesssim |\mathfrak{X}|^{-\frac{1}{6} + \frac{1}{18}} \mathsf{t}^{\frac{1}{12}}.$$
(B.13)

Therefore

$$\int_{a_1}^{a} \frac{\mathrm{d}\tilde{a}}{\partial_b \mathfrak{X}} = \int_{-\frac{1}{n^*} \Psi_1(p^*(\mathfrak{X} - b^2))}^{-\frac{1}{p^*} \Psi_1(p^*(\mathfrak{X} - b^2))} \frac{\mathrm{d}\tilde{a}}{2\sqrt{\mathfrak{X} - \tilde{a} - p^{*2}\tilde{a}^3}} + O\left(|\mathfrak{X}|^{-\frac{1}{6} + \frac{1}{18}} \mathsf{t}^{\frac{1}{12}}\right).$$

We now change variables in the above integral, taking $\tilde{b} = -\sqrt{\mathfrak{T} - \tilde{a} - p^{*2}\tilde{a}^3}$. The left and right endpoints of the integral are precisely b_1 and b, and this produces

$$\begin{split} \tilde{a} &= -\frac{1}{p^*} \Psi_1 \left(p^* (\mathfrak{X} - \tilde{b}^2) \right), \ d\tilde{b} = \frac{1}{2} \frac{1 + 3 p^{*2} \tilde{a}^2}{\sqrt{\mathfrak{X} - \tilde{a} - p^{*2} \tilde{a}^3}} d\tilde{a}, \\ \int_{a_1}^a \frac{d\tilde{a}}{\partial_b \mathfrak{X}} &= \int_{b_1}^b \frac{d\tilde{b}}{1 + 3 \Psi_1^2 \left(p^* \left(\mathfrak{X} - \tilde{b}^2 \right) \right)} + O \left(|\mathfrak{X}|^{-\frac{1}{6} + \frac{1}{18}} \mathfrak{t}^{\frac{1}{12}} \right). \end{split}$$

We inject the identities (B.10), (B.11) and the above identity in the expression (B.9), giving the following expression for \mathcal{Y} :

$$\mathcal{Y} = \int_{-\frac{\delta}{3}}^{b} \frac{d\tilde{b} \left(1 + O\left(|\mathfrak{X}|^{\frac{1}{18}} \mathbf{t}^{\frac{1}{12}} + |\tilde{b}|^{\frac{1}{9}} \mathbf{t}^{\frac{1}{12}} \right) \right)}{1 + 3\Psi_{1}^{2} \left(p^{*} \left(\mathfrak{X} - \tilde{b}^{2} \right) \right)} + O\left(|\mathfrak{X}|^{-\frac{1}{6} + \frac{1}{18}} \mathbf{t}^{\frac{1}{12}} \right) \\
= \mathcal{Y}^{\Theta}(a, b) \left(1 + O\left(\mathbf{t}^{\frac{1}{12}} |\mathfrak{X}|^{\frac{1}{18}} \right) \right). \tag{B.14}$$

Here we used (5.36). This shows the first desired bound in (5.30). We now consider the derivatives of \mathcal{Y} . The point (a_1, b_1) changes as \mathcal{X} changes, but the identity $\mathcal{X}(a_1, b_1) = \mathcal{X}(a, b)$ ensures that

$$\partial_{\mathcal{X}} a_1 \partial_a \mathcal{X}(a_1, b_1) + \partial_{\mathcal{X}} b_1 \partial_b \mathcal{X}(a_1, b_1) = 1. \tag{B.15}$$

Hence, differentiating the sum of the two leading order integrals in (B.9) one obtains

$$\begin{split} & t^{\frac{1}{4}}k_{6}\partial_{a}\left(\int_{\Gamma_{1}}\frac{\mathrm{d}s}{|\nabla x|}+\int_{\Gamma_{2}}\frac{\mathrm{d}s}{|\nabla x|}\right)\\ &=\partial_{a}\left(\int_{-\frac{\delta}{t^{3/4}}}^{b_{1}(a,b)}\frac{\mathrm{d}\tilde{b}}{\partial_{a}\mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b})}+\int_{a_{1}(a,b)}^{a}-\frac{\mathrm{d}\tilde{a}}{\partial_{b}\mathfrak{X}(\tilde{a},\tilde{b}(\mathfrak{X},\tilde{a}))}\right)\\ &=\partial_{a}\mathfrak{X}(a,b)\\ & \left(\int_{-\frac{\delta}{t^{3/4}}}^{b_{1}}\partial_{\mathfrak{X}}\left(\frac{1}{\partial_{a}\mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b})}\right)\mathrm{d}\tilde{b}+\int_{a_{1}}^{a}\partial_{\mathfrak{X}}\left(-\frac{1}{\partial_{b}\mathfrak{X}(\tilde{a},\tilde{b}(\mathfrak{X},\tilde{a}))}\right)d\tilde{a}\\ &+\frac{\partial_{\mathfrak{X}}b_{1}}{\partial_{a}\mathfrak{X}(a_{1},b_{1})}+\frac{\partial_{\mathfrak{X}}a_{1}}{\partial_{b}\mathfrak{X}(a_{1},b_{1})}\right)-\frac{1}{\partial_{b}\mathfrak{X}(a,b)}\\ &=\partial_{a}\mathfrak{X}(a,b)\\ & \left(\int_{-\frac{\delta}{t^{3/4}}}^{b_{1}}\frac{-\partial_{aa}\mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b})\mathrm{d}\tilde{b}}{\left(\partial_{a}\mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b})\right)^{3}}+\int_{a_{1}}^{a}\frac{\partial_{bb}\mathfrak{X}(\tilde{a},\tilde{b}(\mathfrak{X},\tilde{a}))d\tilde{a}}{\left(\partial_{b}\mathfrak{X}(\tilde{a},\tilde{b}(\mathfrak{X},\tilde{a}))\right)^{3}} \end{split}$$

$$+\frac{1}{\partial_a \mathfrak{X}(a_1, b_1)\partial_b \mathfrak{X}(a_1, b_1)}$$

$$-\frac{1}{\partial_b \mathfrak{X}(a, b)}.$$
(B.16)

The first integral is located in Z_1 with $|a| \gg 1$, hence from (5.20) and (5.21),

$$\int_{-\frac{\delta}{\mathfrak{t}^{3/4}}}^{b_{1}} \frac{-\partial_{aa}\mathfrak{X}\left(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b}\right)}{\left(\partial_{a}\mathfrak{X}\left(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b}\right)\right)^{3}} d\tilde{b}$$

$$= 6p^{*} \int_{-\frac{\delta}{\mathfrak{t}^{3/4}}}^{b_{1}} \frac{\Psi_{1}\left(p^{*}\left(\mathfrak{X}-\tilde{b}^{2}\right)\right)\left(1+O\left(\mathfrak{t}^{\frac{1}{12}}|\mathfrak{X}|^{\frac{1}{18}}+\mathfrak{t}^{\frac{1}{12}}|\tilde{b}|^{\frac{1}{9}}\right)\right)}{\left(1+3\Psi_{1}^{2}\left(p^{*}\left(\mathfrak{X}-\tilde{b}^{2}\right)\right)\right)^{3}} d\tilde{b}.$$
(B.17)

The second integral is located in \mathbb{Z}_2 , hence from (5.23) and (5.24),

$$\int_{a_1}^a \frac{\partial_{bb} \mathfrak{X}\left(\tilde{a}, \tilde{b}(\mathfrak{X}, \tilde{a})\right)}{\left(\partial_b \mathfrak{X}\left(\tilde{a}, \tilde{b}(\mathfrak{X}, \tilde{a})\right)\right)^3} d\tilde{a} = -\frac{1}{4} \int_{a_1}^a \frac{1 + O\left(|\mathfrak{X}|^{\frac{1}{6}}\mathsf{t}^{\frac{1}{4}}\right)}{\left(\mathfrak{X} - \tilde{a} - p^{*2}\tilde{a}^3\right)^{\frac{3}{2}}} d\tilde{a}.$$

From (B.12), (B.13),

$$\begin{split} &\int_{a_{1}}^{a} \frac{\partial_{bb} \mathcal{X} \left(\tilde{a}, \tilde{b}(\mathcal{X}, \tilde{a}) \right)}{\left(\partial_{b} \mathcal{X} \left(\tilde{a}, \tilde{b}(\mathcal{X}, \tilde{a}) \right) \right)^{3}} d\tilde{a} \\ &= -\frac{1}{4} \int_{-\frac{1}{p^{*}} \Psi_{1} \left(p^{*} (\mathcal{X} - b^{2}) \right)}^{-\frac{1}{p^{*}} \Psi_{1} \left(p^{*} (\mathcal{X} - 4b_{1}^{2}) \right)} \frac{d\tilde{a}}{\left(\mathcal{X} - \tilde{a} - p^{*2} \tilde{a}^{3} \right)^{\frac{3}{2}}} + O \left(|a - a_{1}| \frac{|\mathcal{X}|^{\frac{1}{6}} \mathbf{t}^{\frac{1}{4}}}{|\mathcal{X}|^{\frac{3}{2}}} \right) \\ &+ O \left(\left| \frac{\left| a + \frac{1}{p^{*}} \Psi_{1} \left(p^{*} \left(\mathcal{X} - b^{2} \right) \right) \right| + \left| a_{1} + \frac{1}{p^{*}} \Psi_{1} \left(p^{*} \left(\mathcal{X} - 4b_{1}^{2} \right) \right) \right|}{|\mathcal{X}|^{\frac{3}{2}}} \right| \right) \\ &= -\frac{1}{4} \int_{-\frac{1}{p^{*}} \Psi_{1} \left(p^{*} (\mathcal{X} - b^{2}) \right)}^{-\frac{1}{p^{*}} \Psi_{1} \left(p^{*} (\mathcal{X} - 4b_{1}^{2}) \right)} \frac{d\tilde{a}}{\left(\mathcal{X} - \tilde{a} - p^{*2} \tilde{a}^{3} \right)^{\frac{3}{2}}} + O \left(|\mathcal{X}|^{-\frac{7}{6} + \frac{1}{18}} \mathbf{t}^{\frac{1}{12}} \right). \end{split}$$

We now change variables, taking $\tilde{b}=-\sqrt{\mathfrak{X}-\tilde{a}-p^{*2}\tilde{a}^3}$. Note that this change of variables ensures $\mathfrak{X}^\Theta(\tilde{a},\tilde{b})=\tilde{a}+p^{*2}\tilde{a}^3+\tilde{b}^2=Cte=\mathfrak{X}$, and

$$-\frac{1}{4}\frac{1}{(\mathfrak{X}-\tilde{a}-p^{*2}\tilde{a}^{3})^{\frac{3}{2}}}=\frac{\partial_{bb}\mathfrak{X}^{\Theta}}{(\partial_{b}\mathfrak{X}^{\Theta})^{3}}.$$

There holds in this case a general formula when integrating on the curve $\{\mathfrak{X}(a,b)=Cte\}$, obtained by performing a change of variables and an integration by parts (note the signs $\partial_a \mathfrak{X}^\Theta > 0$ and $\partial_b \mathfrak{X}^\Theta < 0$ in the present case):

$$\int_{a_1}^{a_2} \frac{\partial_{bb} \mathfrak{X}^{\Theta}}{(\partial_b \mathfrak{X}^{\Theta})^3} da = -\int_{b_1}^{b_2} \frac{\partial_{bb} \mathfrak{X}^{\Theta} db}{(\partial_b \mathfrak{X}^{\Theta})^2 \partial_a \mathfrak{X}^{\Theta}}$$

$$\begin{split} &= -\int_{b_1}^{b_2} \left(\frac{\mathrm{d}}{\mathrm{d}b} \partial_b \mathfrak{X}^{\Theta} + \frac{\partial_b \mathfrak{X}^{\Theta}}{\partial_a \mathfrak{X}^{\Theta}} \partial_{ba} \mathfrak{X}^{\Theta} \right) \frac{\mathrm{d}b}{(\partial_b \mathfrak{X}^{\Theta})^2 \partial_a \mathfrak{X}^{\Theta}} \\ &= -\int_{b_1}^{b_2} \frac{\mathrm{d}}{\mathrm{d}b} (\partial_b \mathfrak{X}^{\Theta}) \frac{1}{(\partial_b \mathfrak{X}^{\Theta})^2 \partial_a \mathfrak{X}^{\Theta}} \mathrm{d}b - \int_{b_1}^{b_2} \frac{\partial_{ab} \mathfrak{X}^{\Theta}}{\partial_b \mathfrak{X}^{\Theta} (\partial_a \mathfrak{X}^{\Theta})^2} \\ &= -\int_{b_1}^{b_2} \frac{\mathrm{d}}{\mathrm{d}b} \left(\partial_b \mathfrak{X}^{\Theta} \frac{1}{(\partial_b \mathfrak{X}^{\Theta})^2 \partial_a \mathfrak{X}^{\Theta}} \right) \mathrm{d}a \\ &+ \int_{b_1}^{b_2} \partial_b \mathfrak{X}^{\Theta} \frac{\mathrm{d}}{\mathrm{d}b} \left(\frac{1}{(\partial_b \mathfrak{X}^{\Theta})^2 \partial_a \mathfrak{X}^{\Theta}} \right) \mathrm{d}b \\ &- \int_{b_1}^{b_2} \frac{\partial_{ab} \mathfrak{X}^{\Theta} \mathrm{d}b}{\partial_b \mathfrak{X}^{\Theta} (\partial_a \mathfrak{X}^{\Theta})^2} \\ &= -\frac{1}{\partial_a \mathfrak{X}^{\Theta} (a_2, b_2) \partial_b \mathfrak{X}^{\Theta} (a_2, b_2)} + \frac{1}{\partial_a \mathfrak{X}^{\Theta} (a_1, b_1) \partial_b \mathfrak{X}^{\Theta} (a_1, b_1)} \\ &- 2 \int_{b_1}^{b_2} \left(\partial_{ab} \mathfrak{X}^{\Theta} - \frac{\partial_b \mathfrak{X}^{\Theta}}{\partial_a \mathfrak{X}^{\Theta}} \partial_{ab} \mathfrak{X}^{\Theta} \right) \frac{1}{(\partial_b \mathfrak{X}^{\Theta})^2 \partial_a \mathfrak{X}^{\Theta}} \mathrm{d}b \\ &- \int_{b_1}^{b_2} \left(\partial_{ab} \mathfrak{X}^{\Theta} - \frac{\partial_b \mathfrak{X}^{\Theta}}{\partial_a \mathfrak{X}^{\Theta}} \partial_{aa} \mathfrak{X}^{\Theta} \right) \frac{1}{\partial_b \mathfrak{X}^{\Theta} (\partial_a \mathfrak{X}^{\Theta})^2} \mathrm{d}b \\ &- \int_{b_1}^{b_2} \frac{\partial_{ab} \mathfrak{X}^{\Theta}}{\partial_b \mathfrak{X}^{\Theta} (\partial_a \mathfrak{X}^{\Theta})^2} \\ &= -\frac{1}{\partial_a \mathfrak{X}^{\Theta} (a_2, b_2) \partial_b \mathfrak{X}^{\Theta} (a_2, b_2)} + \frac{1}{\partial_a \mathfrak{X}^{\Theta} (a_1, b_1) \partial_b \mathfrak{X}^{\Theta} (a_1, b_1)} \\ &+ 2 \int_{a_1}^{a_2} \frac{\partial_{bb} \mathfrak{X}^{\Theta}}{(\partial_b \mathfrak{X}^{\Theta})^3} \mathrm{d}a + \int_{b_1}^{b_2} \frac{\partial_{aa} \mathfrak{X}^{\Theta}}{(\partial_a \mathfrak{X}^{\Theta})^3} \mathrm{d}b, \end{split}$$

from which one deduces the change of parametrisation identity

$$\begin{split} \int_{a_1}^{a_2} \frac{\partial_{bb} \mathfrak{X}^{\Theta}}{(\partial_b \mathfrak{X}^{\Theta})^3} \mathrm{d}a &= \frac{1}{\partial_a \mathfrak{X}^{\Theta}(a_2, b_2) \partial_b \mathfrak{X}^{\Theta}(a_2, b_2)} - \frac{1}{\partial_a \mathfrak{X}^{\Theta}(a_1, b_1) \partial_b \mathfrak{X}^{\Theta}(a_1, b_1)} \\ &- \int_{b_1}^{b_2} \frac{\partial_{aa} \mathfrak{X}^{\Theta}}{(\partial_a \mathfrak{X}^{\Theta})^3} \mathrm{d}b. \end{split}$$

Applied to our case, this produces, noticing that the endpoint, are (a_1, b_1) and (a, b),

$$\begin{split} & -\frac{1}{4} \int_{-\frac{1}{p^*} \Psi_1(p^*(\mathcal{X}-b^2))}^{-\frac{1}{p^*} \Psi_1(p^*(\mathcal{X}-b^2))} \frac{1}{\left(\mathcal{X}-\tilde{a}-p^{*2}\tilde{a}^3\right)^{\frac{3}{2}}} d\tilde{a} \\ & = \frac{1}{\partial_a \mathcal{X}^{\Theta}(a,b)\partial_b \mathcal{X}^{\Theta}(a,b)} - \frac{1}{\partial_a \mathcal{X}^{\Theta}(a_1,b_1)\partial_b \mathcal{X}^{\Theta}(a_1,b_1)} - \int_{b_1}^{b} \frac{\partial_{aa} \mathcal{X}^{\Theta}}{(\partial_a \mathcal{X}^{\Theta})^3} d\tilde{b} \\ & = \frac{1}{(1+3p^{*2}a^2)2b} - \frac{1}{(1+3p^{*2}a_1^2)2b_1} \end{split}$$

$$+6p^* \int_{b_1}^b \frac{\Psi_1\left(p^*\left(\mathfrak{X}-\tilde{b}^2\right)\right)}{\left(1+3\Psi_1^2\left(p^*\left(\mathfrak{X}-\tilde{b}^2\right)\right)\right)^3} d\tilde{b}.$$

Note that, since (a_1, b_1) belong to both Z_1 and Z_2 , from (B.12), (5.23) and (5.20),

$$\frac{1}{\partial_a \mathfrak{X}(a_1, b_1) \partial_b \mathfrak{X}(a_1, b_1)} = \frac{1 + O\left(|\mathfrak{X}|^{\frac{1}{6}} \mathsf{t}^{\frac{1}{4}}\right)}{\left(1 + 3p^{*2}a_1^2\right) 2b_1}
= \frac{1}{\left(1 + 3p^{*2}a_1^2\right) 2b_1} + O\left(|\mathfrak{X}|^{-\frac{7}{6} + \frac{1}{6}} \mathsf{t}^{\frac{1}{4}}\right),$$

so that

$$\int_{a_1}^{a} \frac{\partial_{bb} \mathcal{X} \left(\tilde{a}, \tilde{b}(\mathcal{X}, \tilde{a}) \right)}{\left(\partial_b \mathcal{X} \left(\tilde{a}, \tilde{b}(\mathcal{X}, \tilde{a}) \right) \right)^3} d\tilde{a} = \frac{1}{(1 + 3p^{*2}a^2)2b} - \frac{1}{\partial_a \mathcal{X}(a_1, b_1)\partial_b \mathcal{X}(a_1, b_1)} + 6p^* \int_{b_1}^{b} \frac{\Psi_1 \left(p^* \left(\mathcal{X} - \tilde{b}^2 \right) \right)}{\left(1 + 3\Psi_1^2 \left(p^* \left(\mathcal{X} - \tilde{b}^2 \right) \right) \right)^3} d\tilde{b} + O\left(|\mathcal{X}|^{-\frac{7}{6} + \frac{1}{18}} \mathbf{t}^{\frac{1}{12}} \right).$$

From the above identity and (B.17) one concludes that

$$\begin{split} &\int_{-\frac{\delta}{t^{3/4}}}^{b_1} \frac{-\partial_{aa} \mathfrak{X} \left(\tilde{a}(\mathfrak{X}, \tilde{b}), \tilde{b}\right)}{\left(\partial_a \mathfrak{X} \left(\tilde{a}(\mathfrak{X}, \tilde{b}), \tilde{b}\right)\right)^3} \mathrm{d}\tilde{b} + \int_{a_1}^{a} \frac{\partial_{bb} \mathfrak{X} \left(\tilde{a}, \tilde{b}(\mathfrak{X}, \tilde{a})\right)}{\left(\partial_b \mathfrak{X} \left(\tilde{a}, \tilde{b}(\mathfrak{X}, \tilde{a})\right)\right)^3} d\tilde{a} \\ &+ \frac{1}{\partial_a \mathfrak{X}(a_1, b_1) \partial_b \mathfrak{X}(a_1, b_1)} \\ &= 6p^* \int_{-\frac{\delta}{t^{3/4}}}^{b} \frac{\Psi_1 \left(p^* \left(\mathfrak{X} - \tilde{b}^2\right)\right) \left(1 + O\left(\mathsf{t}^{\frac{1}{12}} |\mathfrak{X}|^{\frac{1}{18}} + \mathsf{t}^{\frac{1}{12}} |\tilde{b}|^{\frac{1}{9}}\right)\right)}{\left(1 + 3\Psi_1^2 \left(p^* \left(\mathfrak{X} - \tilde{b}^2\right)\right)\right)^3} \mathrm{d}\tilde{b} \\ &+ \frac{1}{(1 + 3p^{*2}a^2)2b} + O\left(|\mathfrak{X}|^{-\frac{7}{6} + \frac{1}{18}} \mathsf{t}^{\frac{1}{12}}\right) \end{split}$$

From (5.37), and using the fact that for $\tilde{b} \leq -\delta t^{3/4}$, one has $|\Psi_1(p^*(\mathfrak{X} - \tilde{b}^2))| \approx |\tilde{b}|^{2/3}$, and

$$\begin{split} &\int_{-\frac{\delta}{\mathsf{t}^{3/4}}}^{b} \frac{\Psi_{1}\left(p^{*}\left(\mathfrak{X}-\tilde{b}^{2}\right)\right)\left(1+O\left(\mathsf{t}^{\frac{1}{12}}|\mathfrak{X}|^{\frac{1}{18}}+\mathsf{t}^{\frac{1}{12}}|\tilde{b}|^{\frac{1}{9}}\right)\right)}{\left(1+3\Psi_{1}^{2}\left(p^{*}\left(\mathfrak{X}-\tilde{b}^{2}\right)\right)\right)^{3}} \mathrm{d}\tilde{b} \\ &= \int_{-\infty}^{b} \frac{\Psi_{1}\left(p^{*}\left(\mathfrak{X}-\tilde{b}^{2}\right)\right)}{\left(1+3\Psi_{1}^{2}\left(p^{*}\left(\mathfrak{X}-\tilde{b}^{2}\right)\right)\right)^{3}} \mathrm{d}\tilde{b} + O\left(|\mathfrak{X}|^{-\frac{7}{6}+\frac{1}{18}}\mathsf{t}^{\frac{1}{12}}\right). \end{split}$$

Therefore

$$\begin{split} &\int_{-\frac{\delta}{t^{3/4}}}^{b_{1}} \frac{-\partial_{aa} \mathcal{X}\left(\tilde{a}(\mathcal{X},\tilde{b}),\tilde{b}\right)}{\left(\partial_{a} \mathcal{X}\left(\tilde{a}(\mathcal{X},\tilde{b}),\tilde{b}\right)\right)^{3}} \mathrm{d}\tilde{b} + \int_{a_{1}}^{a} \frac{\partial_{bb} \mathcal{X}\left(\tilde{a},\tilde{b}(\mathcal{X},\tilde{a})\right)}{\left(\partial_{b} \mathcal{X}\left(\tilde{a},\tilde{b}(\mathcal{X},\tilde{a})\right)\right)^{3}} d\tilde{a} \\ &+ \frac{1}{\partial_{a} \mathcal{X}(a_{1},b_{1})\partial_{b} \mathcal{X}(a_{1},b_{1})} \\ &= \int_{-\infty}^{b} \frac{\Psi_{1}\left(p^{*}\left(\mathcal{X}-\tilde{b}^{2}\right)\right)}{\left(1+3\Psi_{1}^{2}\left(p^{*}\left(\mathcal{X}-\tilde{b}^{2}\right)\right)\right)^{3}} \mathrm{d}\tilde{b} + \frac{1}{(1+3p^{*2}a^{2})2b} \\ &+ O\left(|\mathcal{X}|^{-\frac{7}{6}+\frac{1}{18}}t^{\frac{1}{12}}\right) \end{split} \tag{B.18}$$

Since (a, b) is in \mathbb{Z}_2 , from (B.12), (5.23) and (5.20),

$$\frac{\partial_a \mathfrak{X}(a,b)}{(1+3p^{*2}a^2)2b} = \frac{1}{\partial_b \mathfrak{X}(a,b)} + O\left(|\mathfrak{X}|^{-\frac{1}{2} + \frac{1}{6}} \mathsf{t}^{\frac{1}{4}}\right).$$

Injecting the two identities above, (B.17) and $|\partial_a \mathfrak{X}| \lesssim |\mathfrak{X}|^{2/3}$ in the identity (B.16) gives

$$\begin{aligned} \mathbf{t}^{\frac{1}{4}} k_6 \partial_a \left(\int_{\Gamma_1} \frac{\mathrm{d}s}{|\nabla x|} + \int_{\Gamma_2} \frac{\mathrm{d}s}{|\nabla x|} \right) \\ &= 6 p^* \partial_a \mathfrak{X}(a,b) \int_{-\infty}^b \frac{\Psi_1 \left(p^* \left(\mathfrak{X} - \tilde{b}^2 \right) \right) \mathrm{d}\tilde{b}}{\left(1 + 3 \Psi_1^2 \left(p^* \left(\mathfrak{X} - \tilde{b}^2 \right) \right) \right)^3} \\ &+ O \left(|\mathfrak{X}|^{-\frac{1}{2} + \frac{1}{18}} \mathbf{t}^{\frac{1}{12}} \right) \end{aligned}$$

From this identity, (B.9), (B.10) and (5.68), we have proved that

$$\partial_a \mathcal{Y} = \partial_a \mathcal{Y}^{\Theta} + O\left(|\mathfrak{X}|^{-\frac{1}{2} + \frac{1}{18}} \mathsf{t}^{\frac{1}{12}}\right),\,$$

which is the second identity in (5.30) that we had to show. We now turn to the partial derivative with respect to b. From (B.9) and (B.15), and then injecting (B.18), (5.68), (5.69) and (5.67),

$$\begin{split} & t^{\frac{1}{4}}k_{6}\partial_{b}\left(\int_{\Gamma_{1}}\frac{\mathrm{d}s}{|\nabla x|}+\int_{\Gamma_{2}}\frac{\mathrm{d}s}{|\nabla x|}\right)\\ &=\partial_{b}\left(\int_{-\frac{\delta}{\mathfrak{t}^{3/4}}}^{b_{1}(a,b)}\frac{\mathrm{d}\tilde{b}}{\partial_{a}\mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b})}+\int_{a_{1}(a,b)}^{a}-\frac{\mathrm{d}\tilde{a}}{\partial_{b}\mathfrak{X}(\tilde{a},\tilde{b}(\mathfrak{X},\tilde{a}))}\right)\\ &=\partial_{b}\mathfrak{X}(a,b) \end{split}$$

$$\begin{split} &\left(\int_{-\frac{\delta}{t^{3/4}}}^{b_1} \frac{-\partial_{aa} \mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b}) \mathrm{d}\tilde{b}}{\left(\partial_a \mathfrak{X}(\tilde{a}(\mathfrak{X},\tilde{b}),\tilde{b})\right)^3} + \int_{a_1}^{a} \frac{\partial_{bb} \mathfrak{X}(\tilde{a},\tilde{b}(\mathfrak{X},\tilde{a})) d\tilde{a}}{\left(\partial_b \mathfrak{X}(\tilde{a},\tilde{b}(\mathfrak{X},\tilde{a}))\right)^3} \\ &+ \frac{1}{\partial_a \mathfrak{X}(a_1,b_1)\partial_b \mathfrak{X}(a_1,b_1)} \right) \\ &= \partial_b \mathfrak{X}(a,b) \\ &\left(\int_{-\infty}^{b} \frac{\Psi_1\left(p^*\left(\mathfrak{X}-\tilde{b}^2\right)\right)}{\left(1+3\Psi_1^2\left(p^*\left(\mathfrak{X}-\tilde{b}^2\right)\right)\right)^3} \mathrm{d}\tilde{b} + \frac{1}{(1+3p^{*2}a^2)2b} \\ &+ O\left(|\mathfrak{X}|^{-\frac{7}{6}+\frac{1}{18}} t^{\frac{1}{12}}\right)\right) \\ &= \partial_b \mathcal{Y}^\Theta + O\left(|\mathfrak{X}|^{-\frac{2}{3}+\frac{1}{18}} t^{\frac{1}{12}}\right), \end{split}$$

which was the last estimate (5.31) we had to show. We claim that the computations we performed for this right side of the self-similar zone can be adapted in a straightforward way in the case where one has to consider more parts of the curve Γ inside Z_0^c to parametrise; the integral over Γ_3 , Γ_4 and Γ_5 can be treated the very same way, leading to the same result. \square

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CHARLES COLLOT
Courant Institute of Mathematical Sciences,
New York University,
251 Mercer Street,
New York
NY
10003 USA.
e-mail: cc5786@nyu.edu

and

TEJ-EDDINE GHOUL NYUAD Research Institute, New York University in Abu Dhabi, Saadiyat Island, P.O. Box 129188, Abu Dhabi UAE.

and

Department of Mathematics, New York University in Abu Dhabi, Saadiyat Island, P.O. Box 129188, Abu Dhabi UAE. e-mail: teg6@nyu.edu

and

NADER MASMOUDI NYUAD Research Institute, New York University Abu Dhabi, PO Box 129188, Abu Dhabi UAE.

and

Courant Institute of Mathematical Sciences,
New York University,
251 Mercer Street,
New York
NY
10012 USA.
e-mail: masmoudi@cims.nyu.edu

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